

# **Model reduction of nonlinear systems – use of multi-time scale models and model reduction techniques**

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Concerned with **large-scale non-linear circuits.**

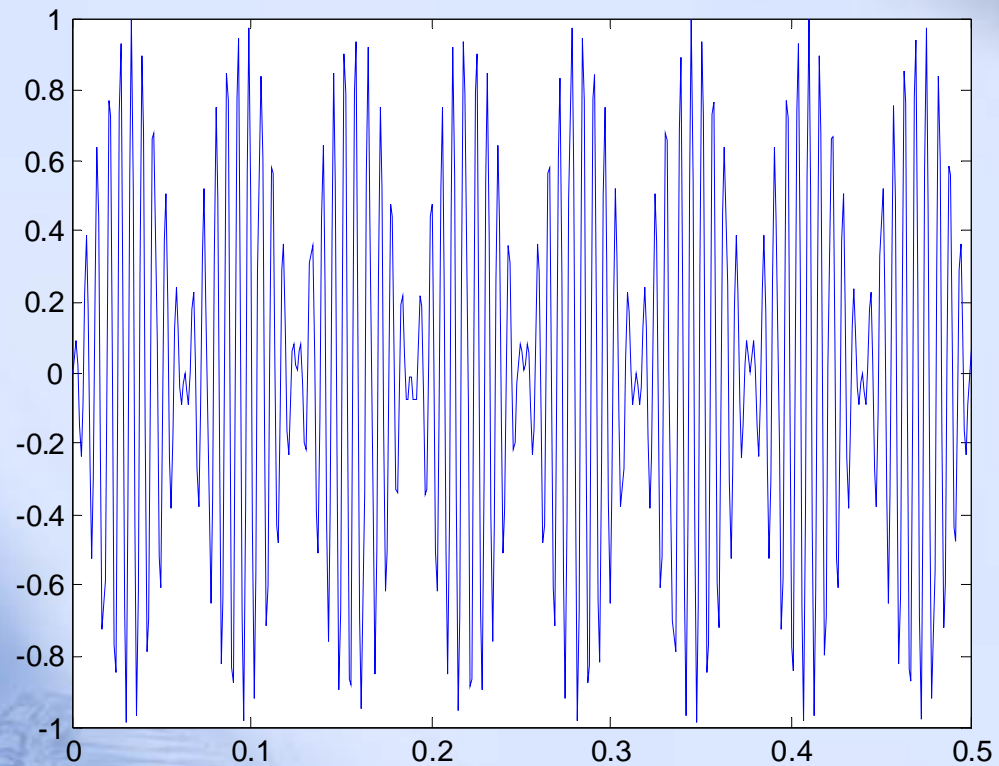
Their behaviour is described by:

$$\dot{\mathbf{x}}(t) = f(\mathbf{x}(t)) + \mathbf{b}(t)$$

$\mathbf{x}(t)$  are the states

$\mathbf{b}(t)$  are the inputs to the circuit

Concerned with **envelope modulated** signals



$$x(t) = \hat{x}(t_1, t_2)$$

Such systems are suitable for **MULTI-TIME SCALE** analysis

We set  $x(t) = \hat{x}(t_1, \dots, t_p)$

$p$  is the number of different time scales

We rewrite the governing equation in multi-time scale format

$$\frac{\partial \hat{x}}{\partial t_1} + \frac{\partial \hat{x}}{\partial t_2} + \dots + \frac{\partial \hat{x}}{\partial t_p} = f(\hat{x}(t_1, t_2, \dots, t_p)) + \hat{b}(t_1, t_2, \dots, t_p)$$

We can solve the **multi-time scale partial differential equation** using:

- Complete time-domain methods
- Mixed time-domain frequency-domain methods
- Mixed time-domain wavelet methods

We will consider **wavelet** approach

Why? –

- Suitable for highly nonlinear circuits
- Enables us to move from one level of accuracy to another in an incremental manner

To simplify matters, consider **two** time scales.

$$\frac{\partial \hat{x}}{\partial t_1} + \frac{\partial \hat{x}}{\partial t_2} = f(\hat{x}(t_1, t_2)) + \hat{b}(t_1, t_2)$$

$x(t)$  is evaluated along the diagonal of the  $t_1, t_2$  plane

$$x(t) = \hat{x}(t, t)$$

- $x(t)$  is represented by:
- a series of wavelets in one time scale
  - coefficients which vary in the other time scale

$$\hat{x}_j(t_1, t_2) = \sum_{k=1}^N \bar{x}_k(t_1) \Psi_k(t_2)$$

If written for all collocation points in  $t_2$

$$\hat{x}_{jN}(t_1) = E \bar{x}(t_1)$$

$E$  is a constant square matrix.

Its columns comprise the values of the  $N$  wavelet functions,  $\Psi_k(t_2)$ , at the  $N$  collocation points

The governing equation now becomes:

$$E \frac{d\bar{x}}{dt_1} = -D\bar{x} + f_N(\bar{x}) + b_N$$

This is an ODE – but it concerns ONE time scale –

-so can be solved numerically in an efficient manner



At this point we employ **MODEL REDUCTION** techniques

We expand  $\bar{x}(t_1)$  in a Taylor's series  $t_1^0$  is the initial time

$$\bar{x}(t_1) = \sum_{i=0}^{\infty} a_i (t_1 - t_1^0)^i$$

The coefficients  $a_i$  may be computed recursively

A Krylov space is formed from  $a_i$

$$K = [a_0 \quad a_1 \quad \cdots \quad a_q]$$

$q$  is the order of the reduced system

We perform a QR decomposition of the Krylov space

$$K = QR$$

$$Q^T Q = I_q$$

Then  $Q$  is employed to perform a congruent transformation:

$$\bar{x} = Q\hat{x}$$

$$Q^T E Q \frac{d\hat{x}}{dt_1} = -Q^T D Q \hat{x} + Q^T f_N(Q\hat{x}) + Q^T b_N$$

or

$$\hat{E} \frac{d\hat{x}}{dt_1} = -\hat{D} \hat{x} + Q^T f_N(Q\hat{x}) + \hat{b}_N$$

where

$$\hat{E} = Q^T E Q \quad \hat{D} = Q^T D Q \quad \hat{b}_N = Q^T b_N$$

**Reduced** system is of size  $q \ll N$  – where  $N$  is the original size

For oscillators or systems subject to Frequency Modulated signals we use the **Warped Multi-time scale model**

$$\omega(\tau_2) \frac{\partial \hat{x}}{\partial t_1} + \frac{\partial \hat{x}}{\partial t_2} = f(\hat{x}(t_1, t_2)) + b(t_2)$$

It bends the path along which  $x(t)$  is evaluated to account for frequency variation

$$x(t) = \hat{x}(\varphi(t), t)$$
$$\varphi(t) = \int_0^t \omega(t) dt$$

Again we apply wavelet analysis

$$\hat{x}_J(t_1, t_2) = \sum_{k=1}^N \bar{x}_k(t_2) \Psi_k(t_1)$$

Warped Equation now becomes:

$$\omega(\tau_2)D\bar{x} + E \frac{\partial \bar{x}}{\partial t_2} = f(E\bar{x}) + b_N(t_2)$$

We apply the same reduction procedure

$$\bar{x}(t_2) = \sum_{i=0}^{\infty} a_i (t_2 - t_2^0)^i$$

$$K = [a_0 \quad a_1 \quad \cdots \quad a_q] = QR$$

Reduced equation is of size  $q \ll N$

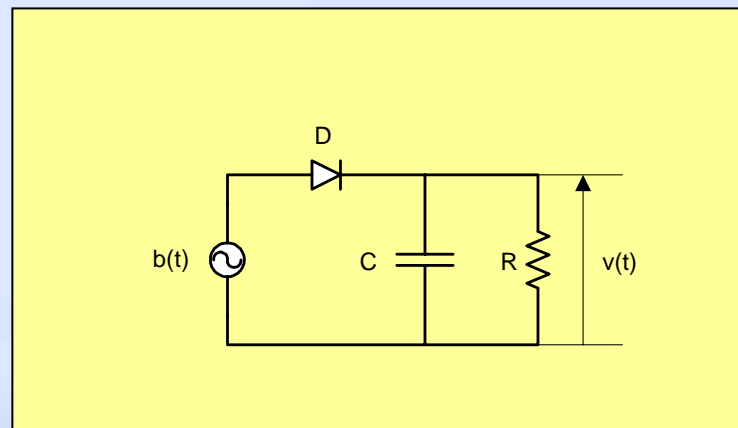
$$\omega(\tau_2) \hat{D} \hat{x} + \hat{E} \frac{\partial \hat{x}}{\partial t_2} = Q^T f(Q \hat{x}) + \hat{b}_N(t_2)$$



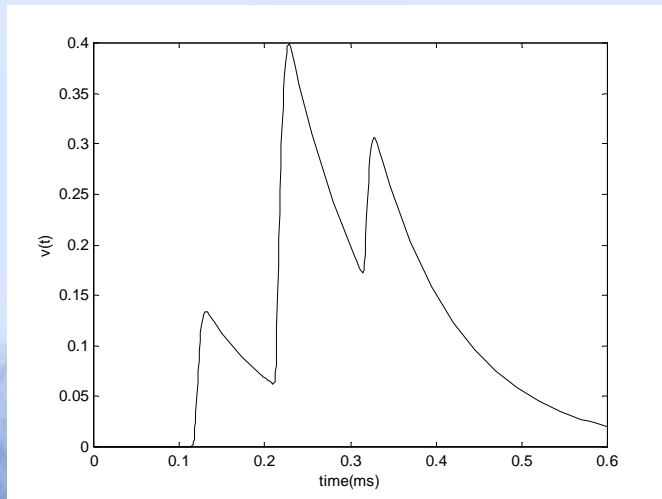
Example:

$$\text{Input signal: } b(t) = \sin\left(\frac{2\pi}{T_1}t\right) \sin\left(\frac{2\pi}{T_2}t\right)$$

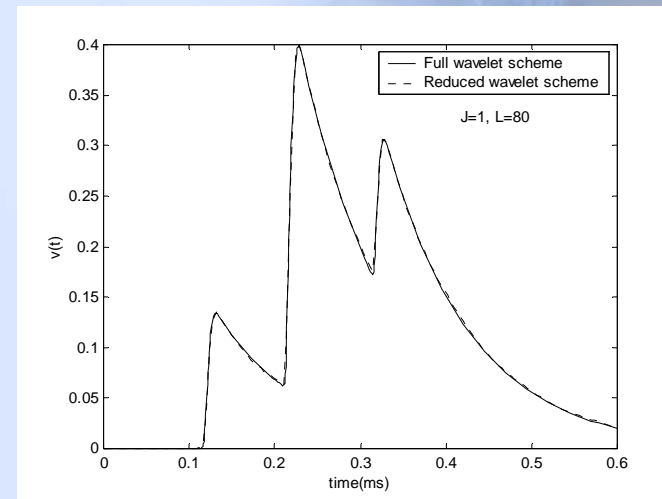
Nonlinear circuit



## Output with full model



## Output from reduced wavelet model



## CONCLUSIONS

- Multi-timescale analysis suitable for nonlinear circuits with modulated signals
- Multi-timescale model can be reduced using Krylov space techniques



**MORE RESEARCH WORK REQUIRED  
FOR NONLINEAR MODEL REDUCTION**

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