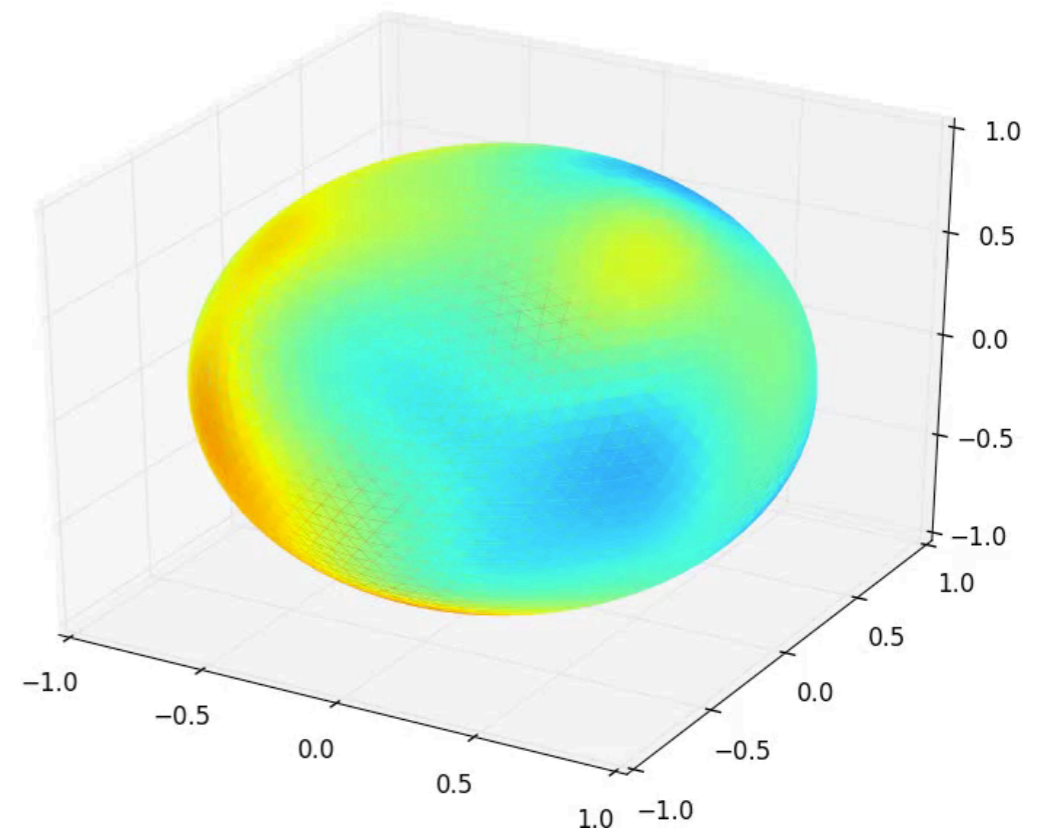
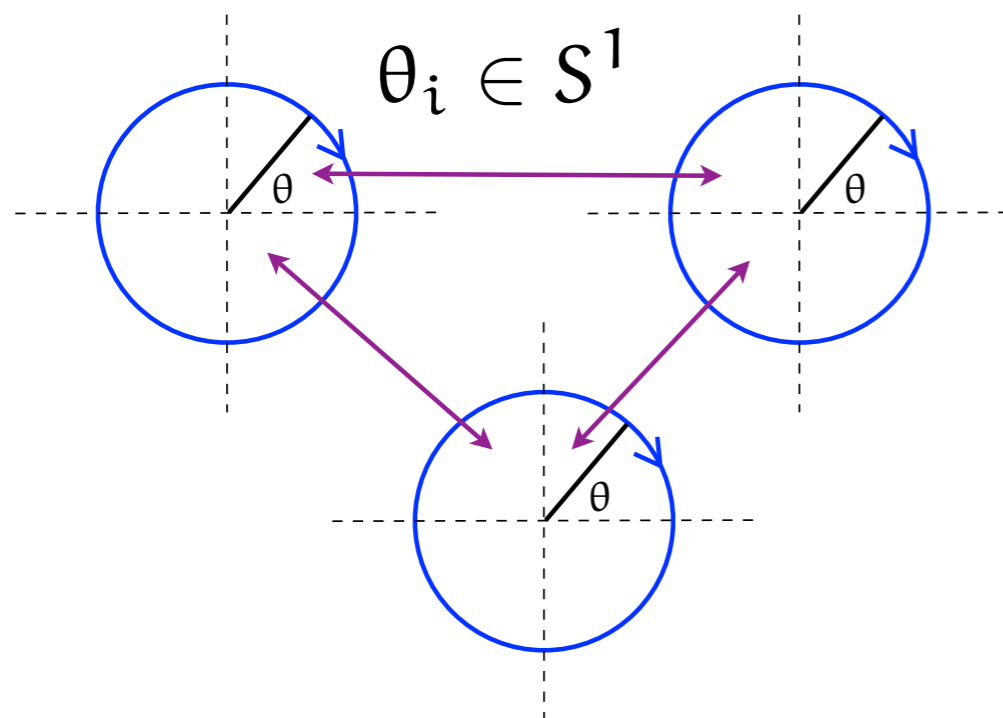
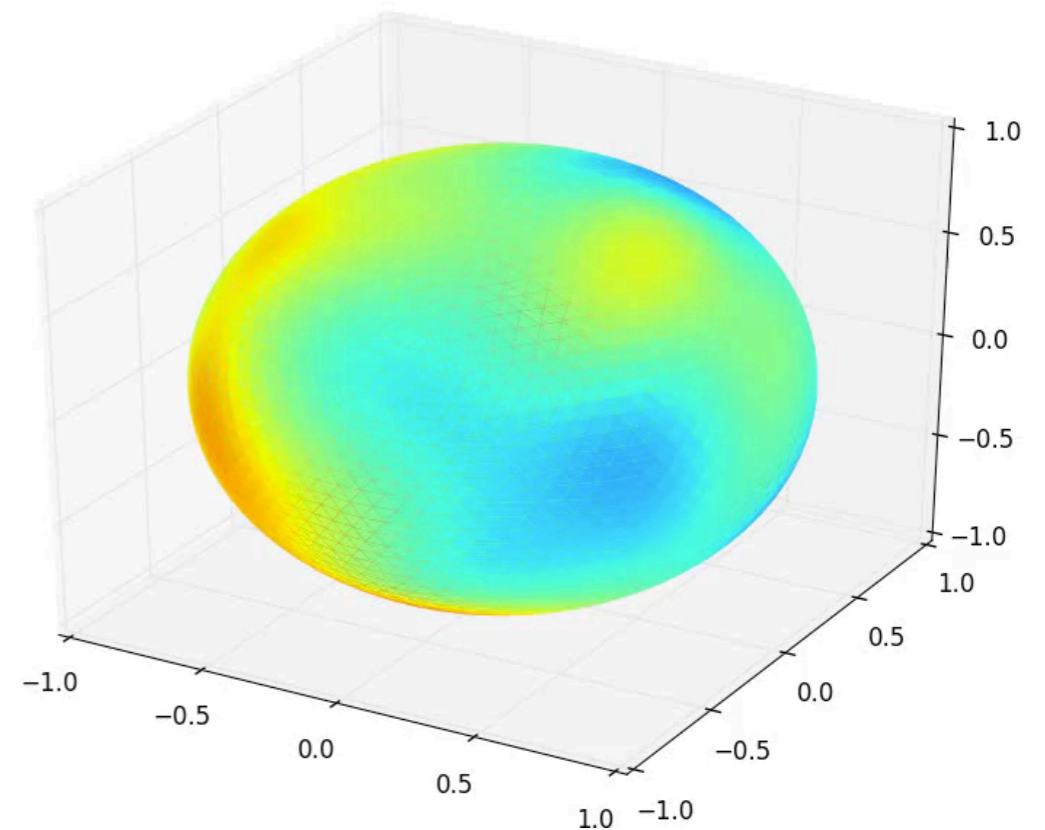
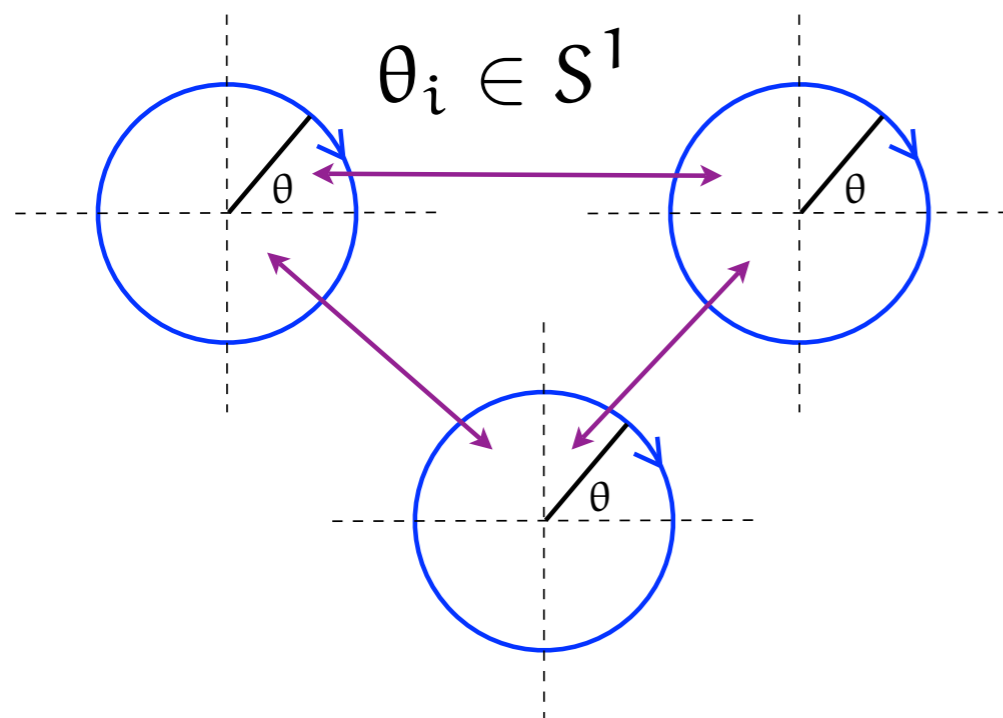


# Model reduction in mathematical neuroscience

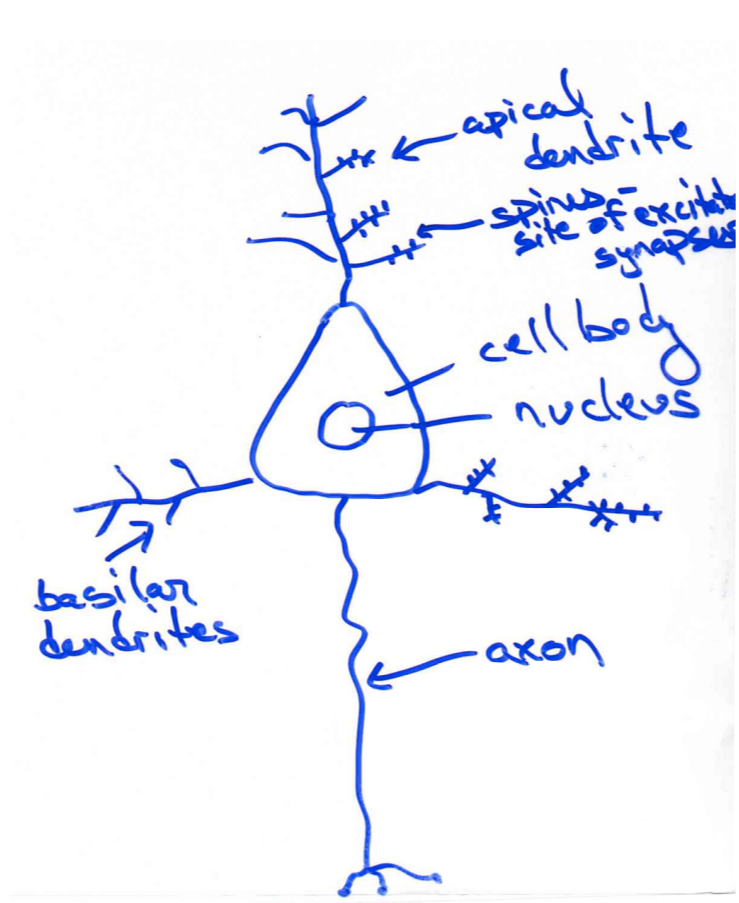
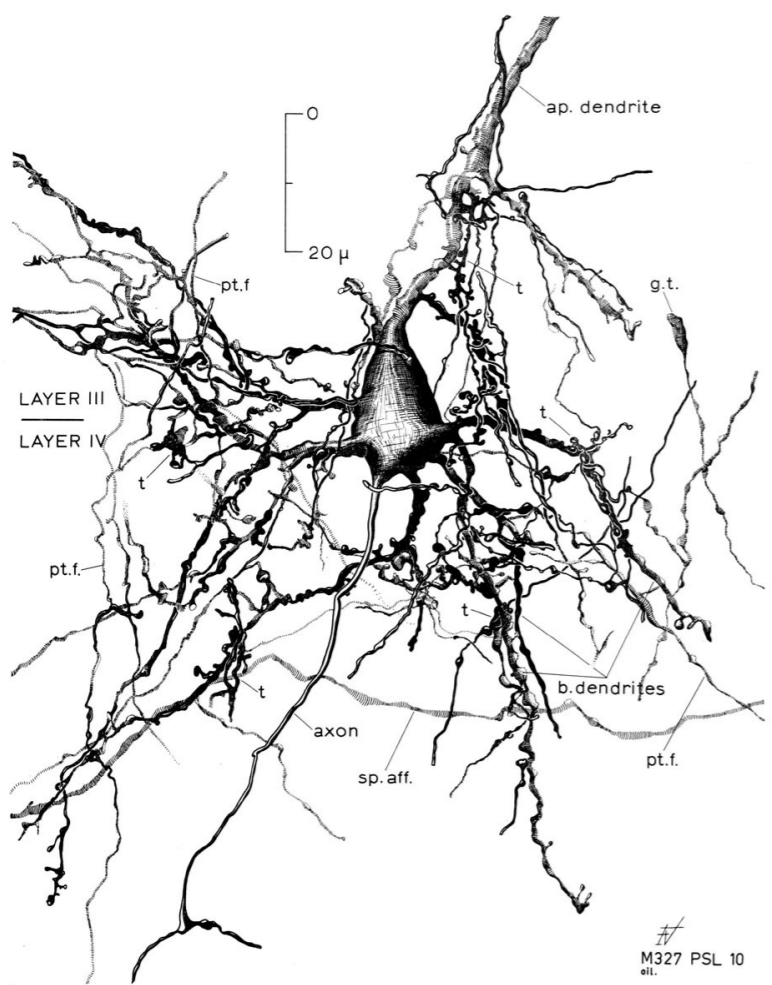


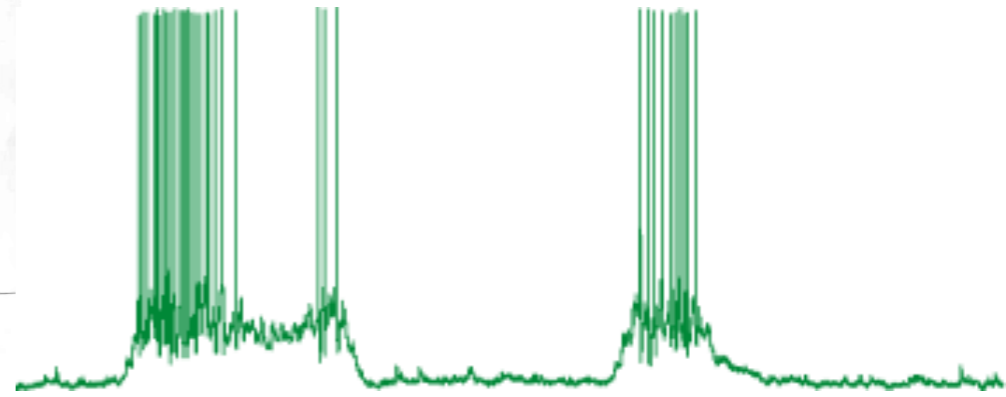
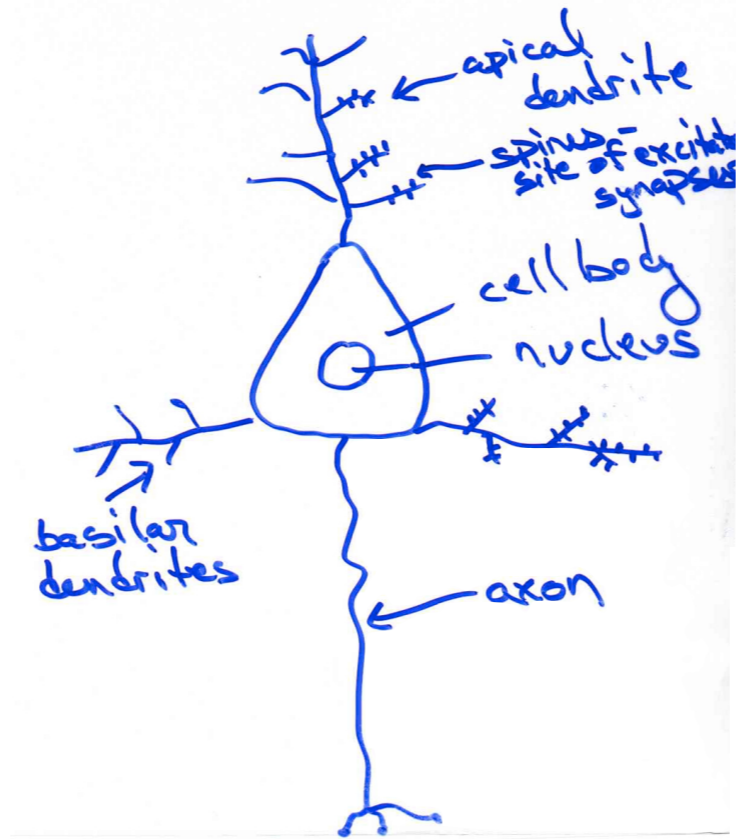
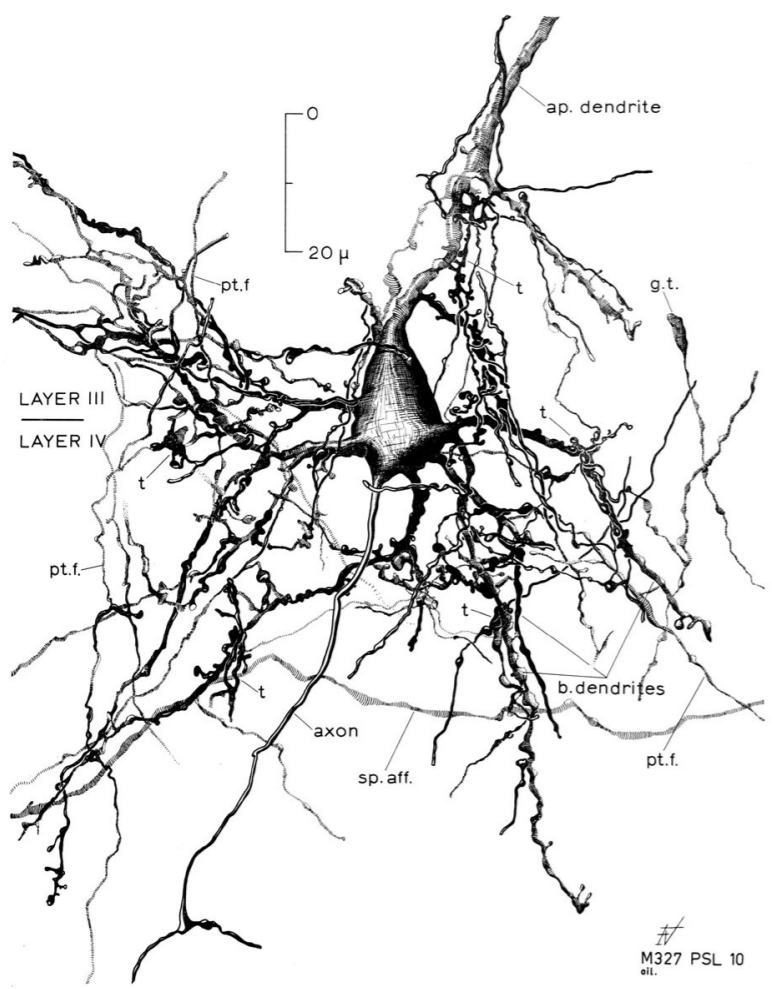
Stephen Coombes

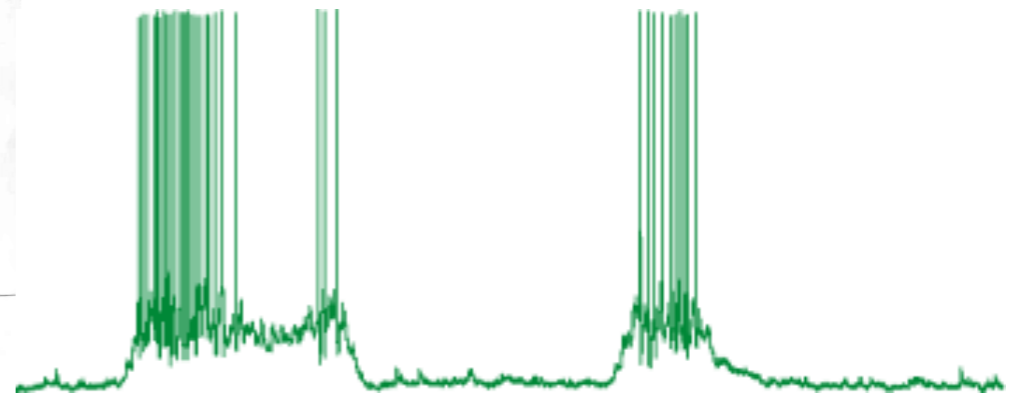
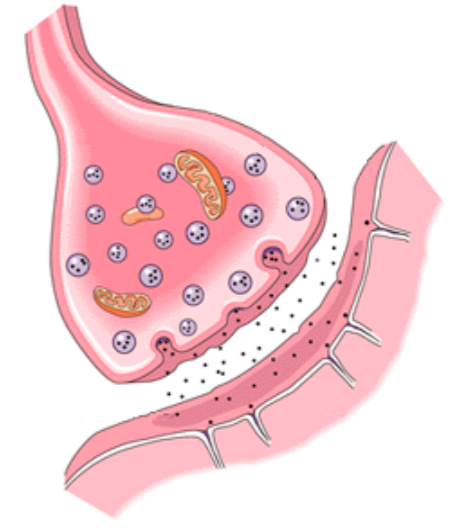
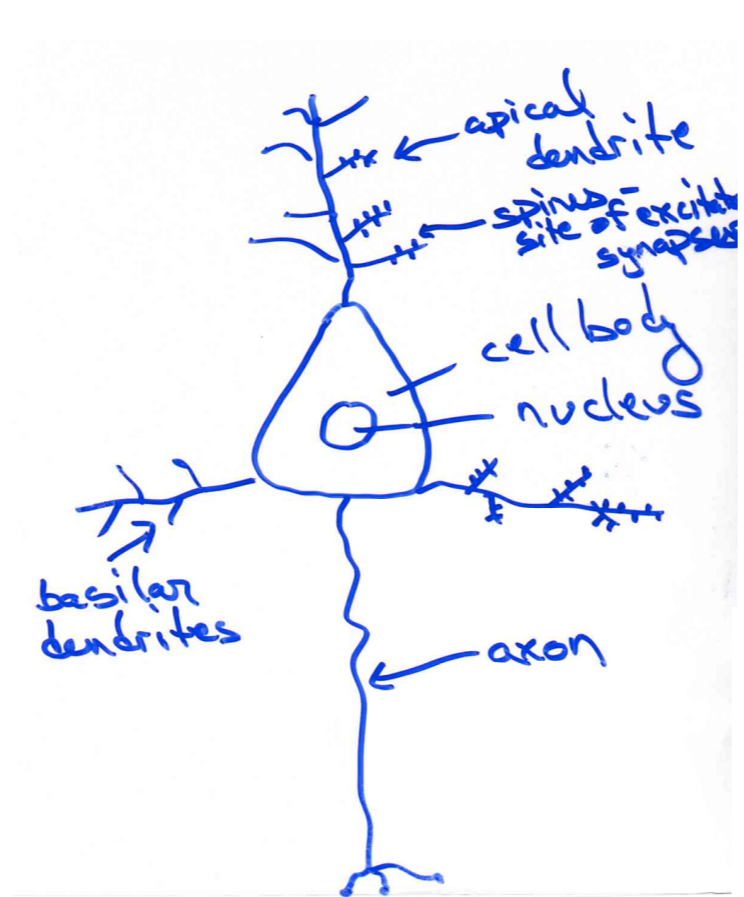
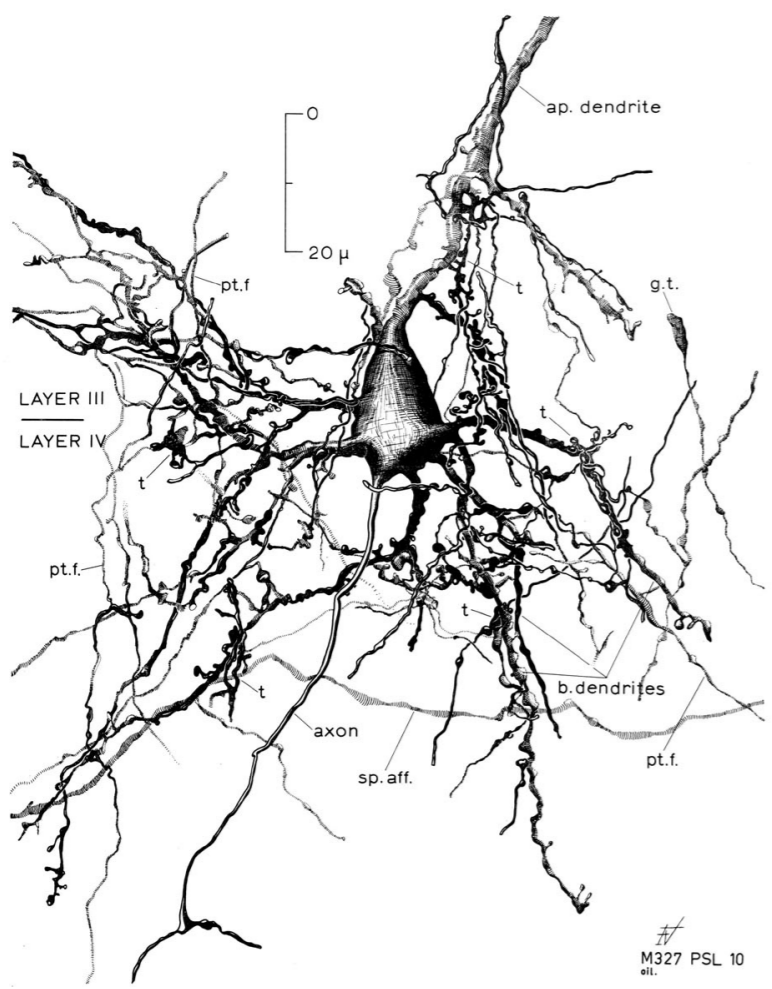
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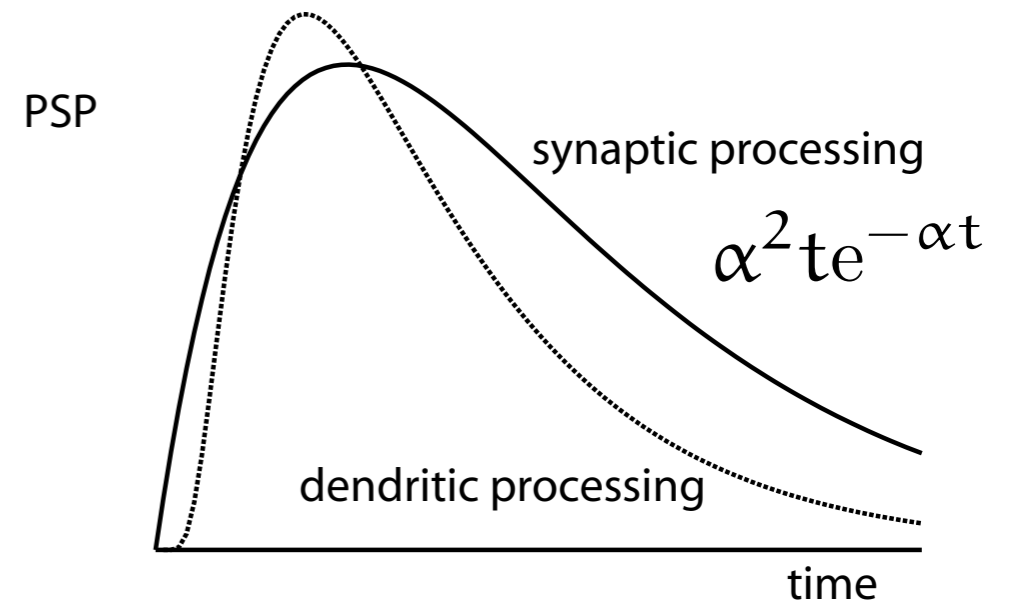
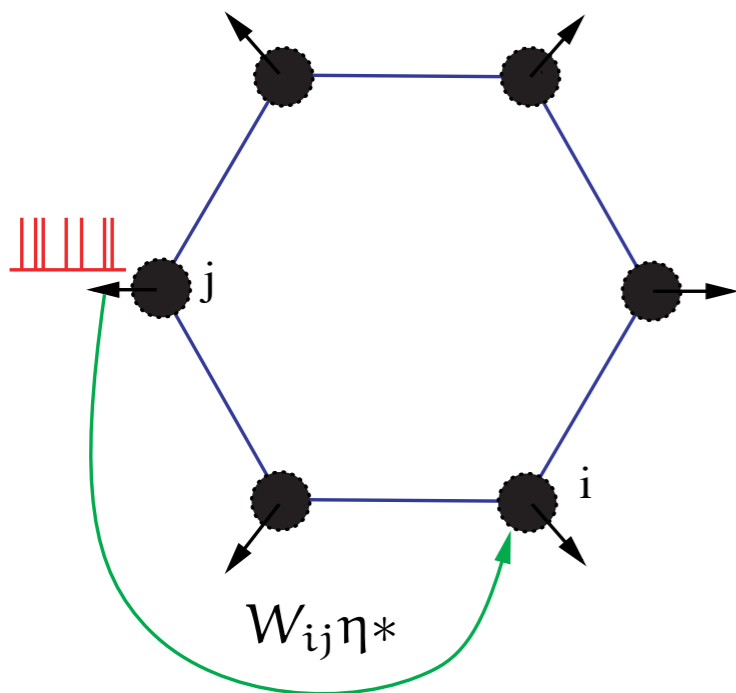
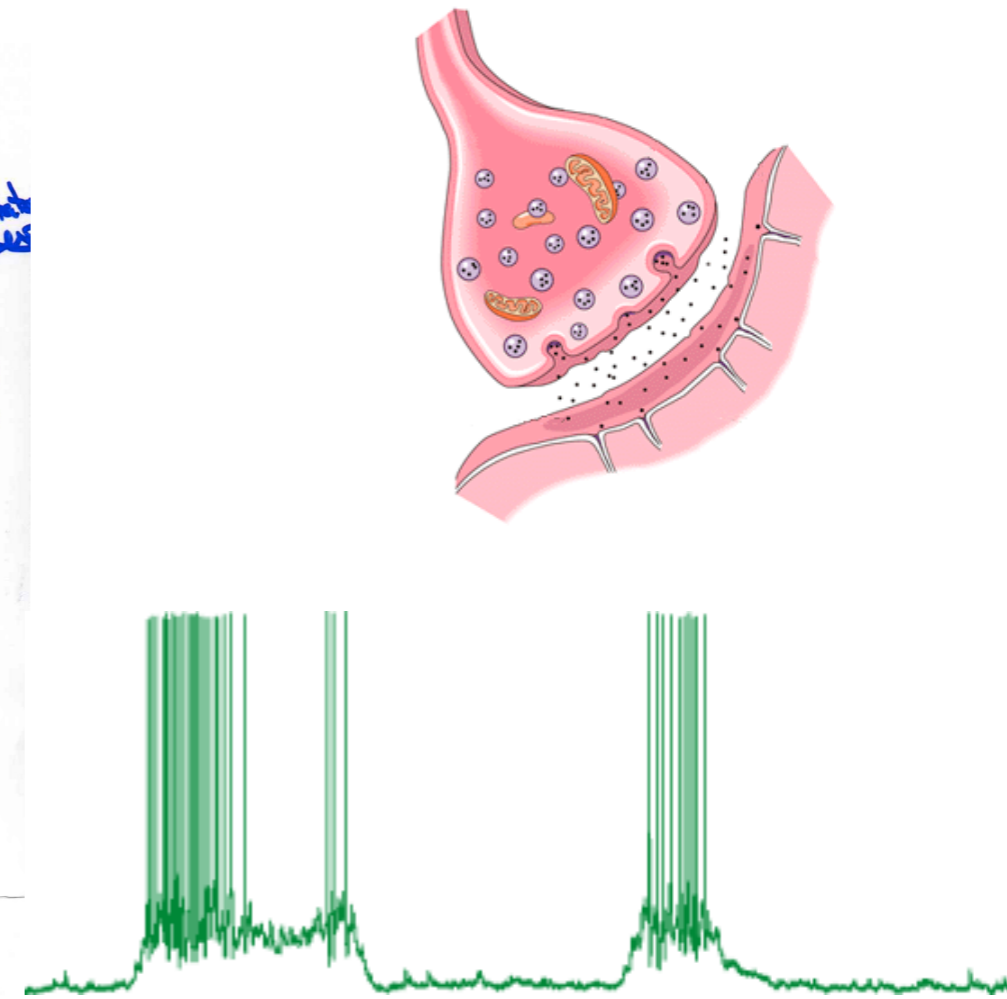
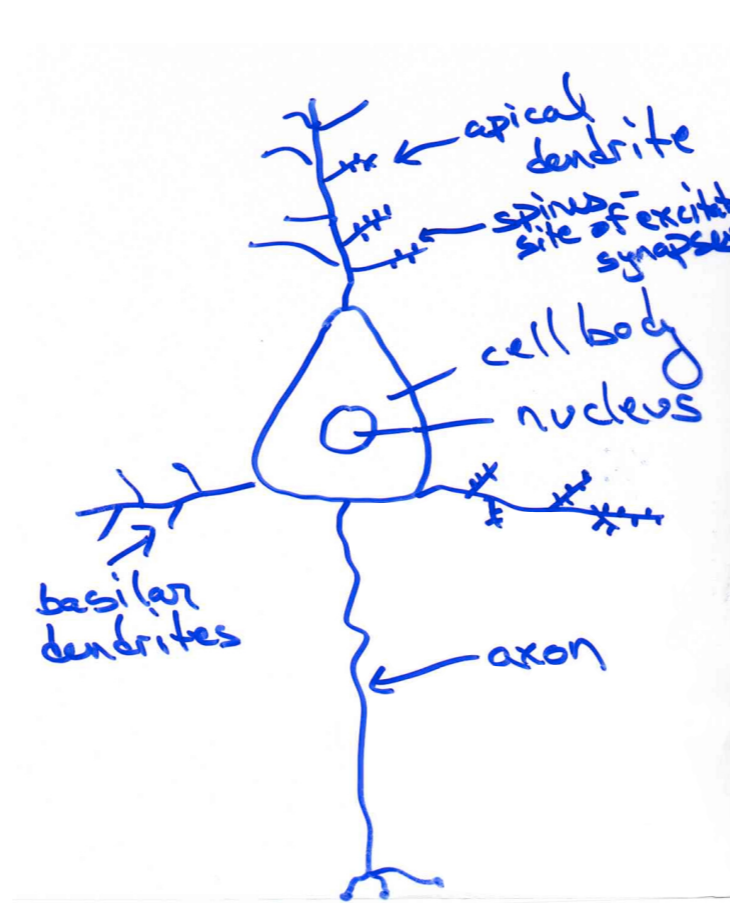
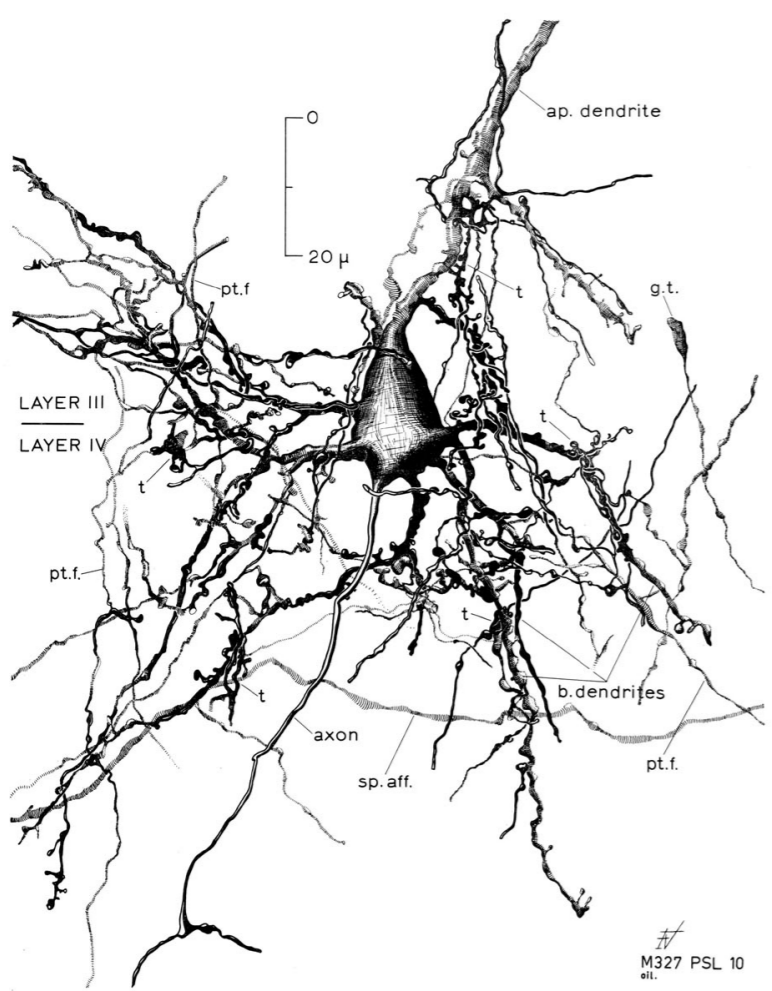


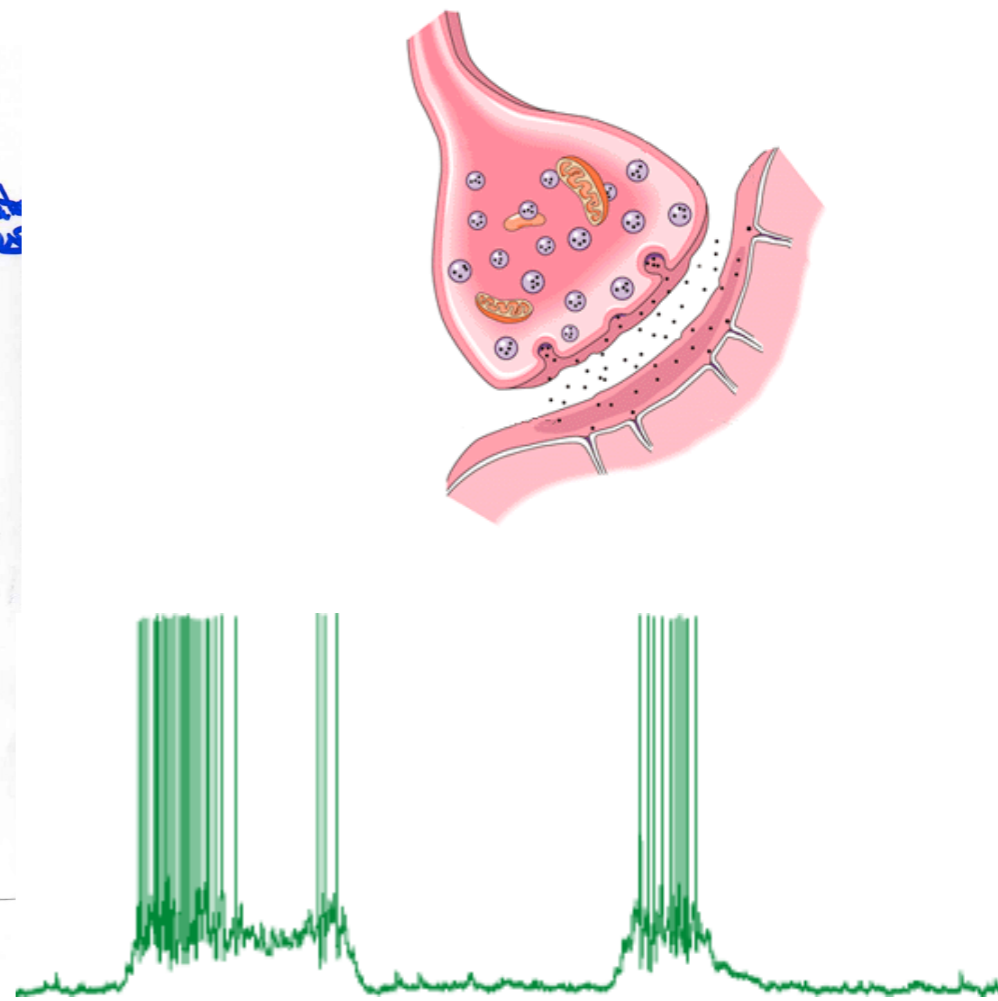
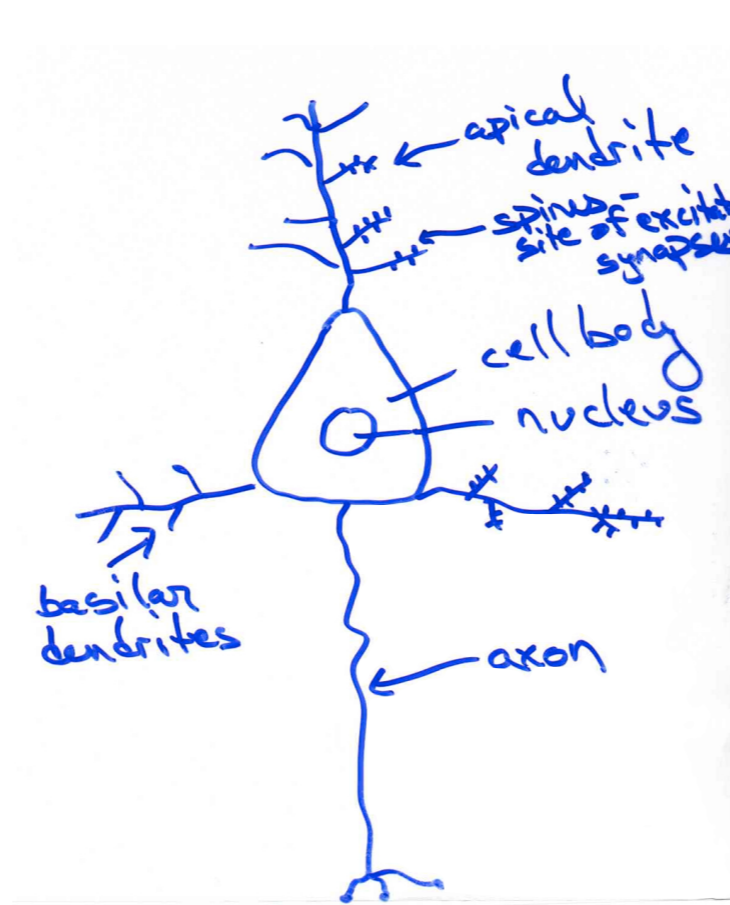
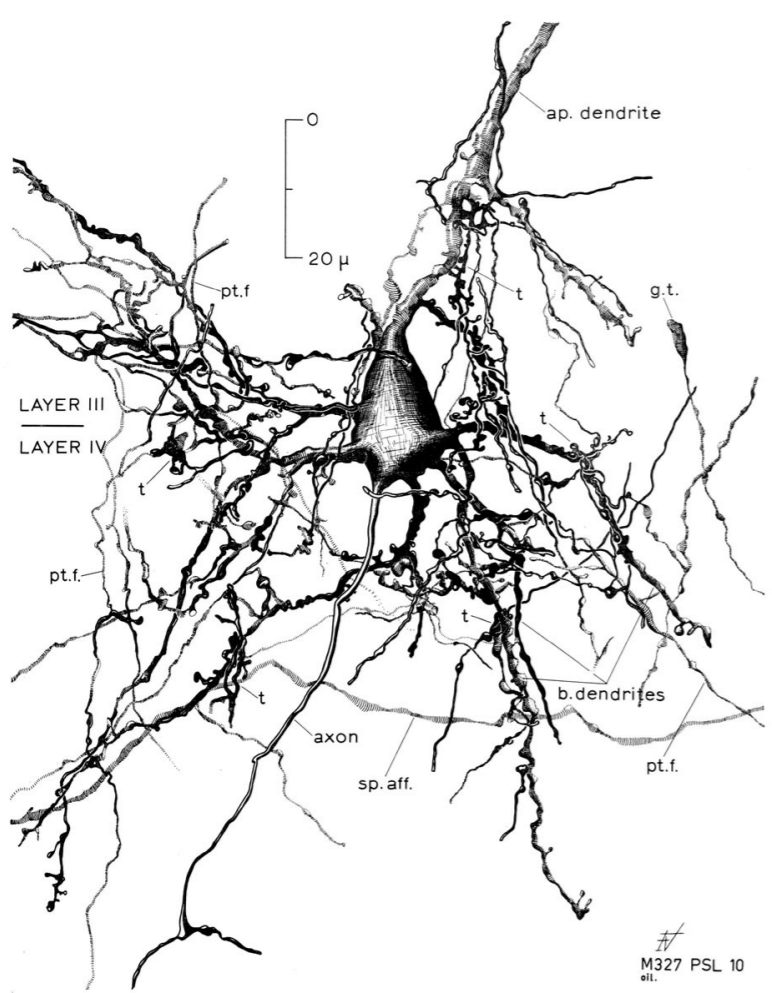
Stephen Coombes



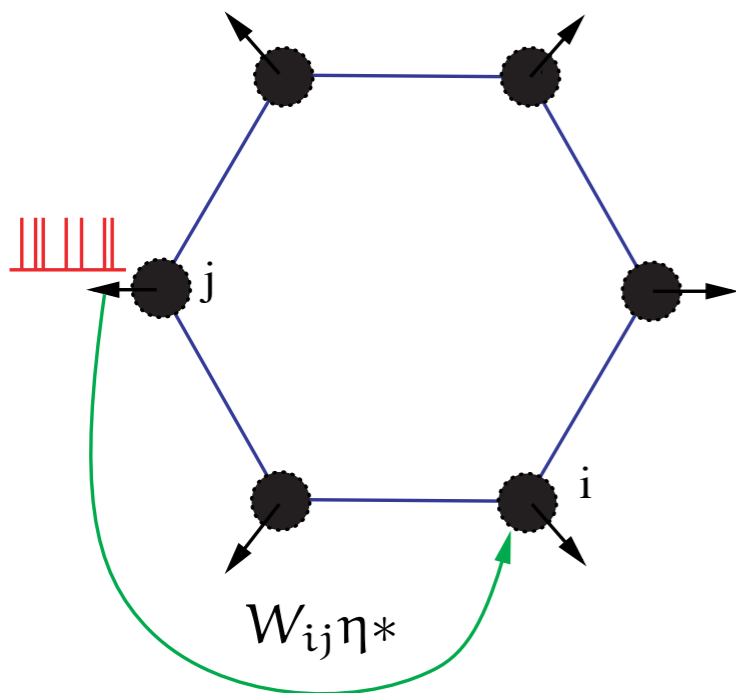




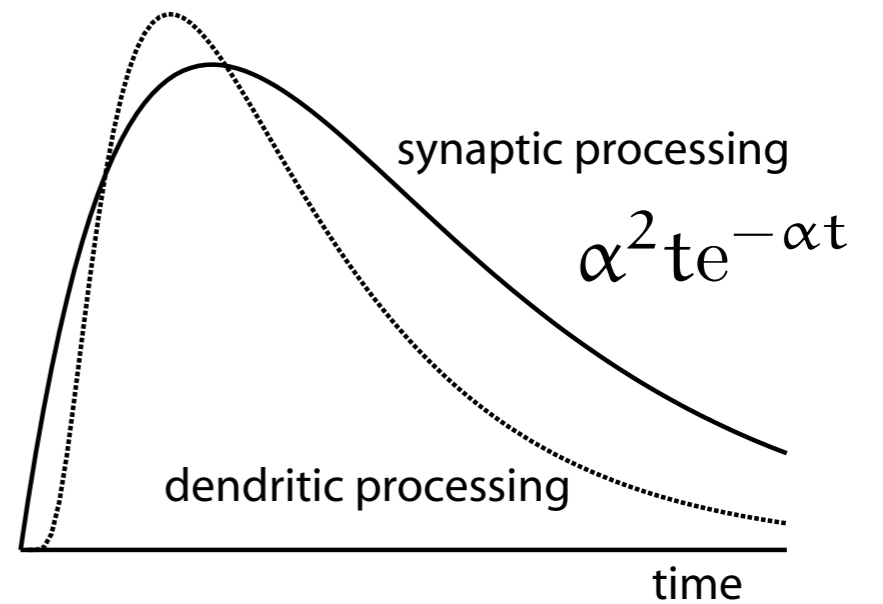


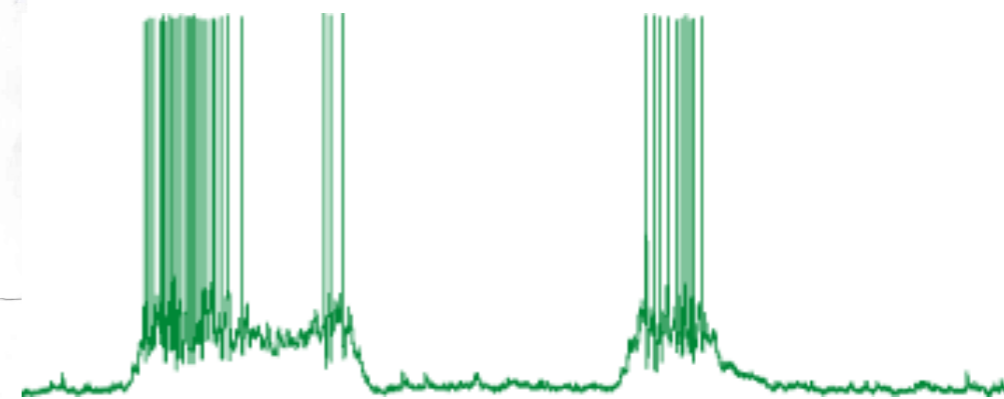
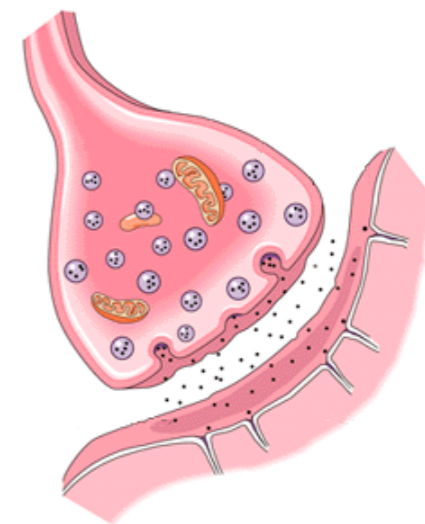
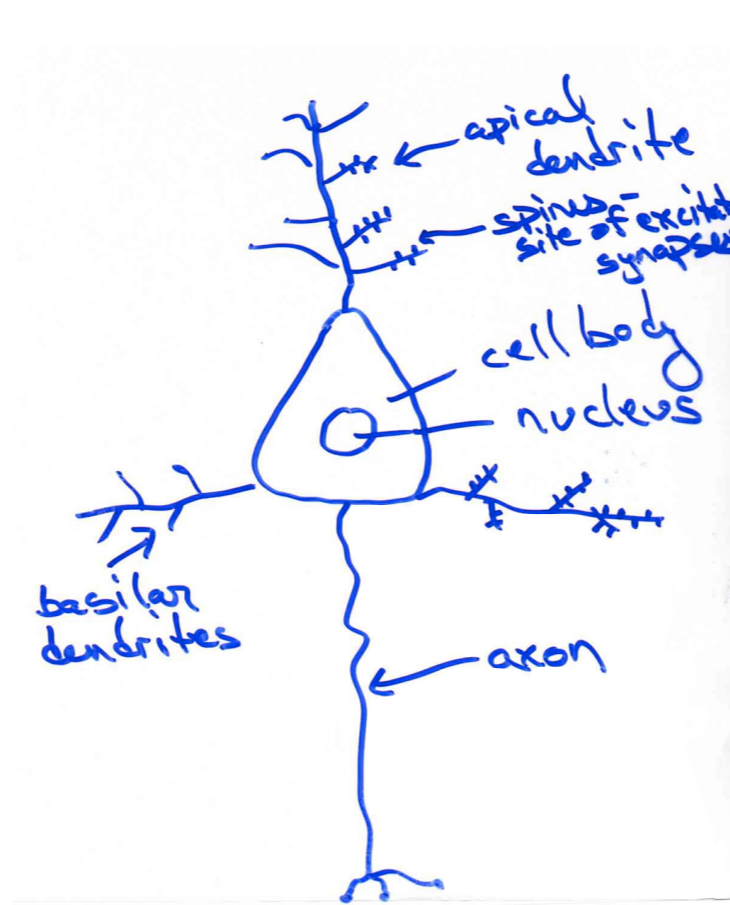
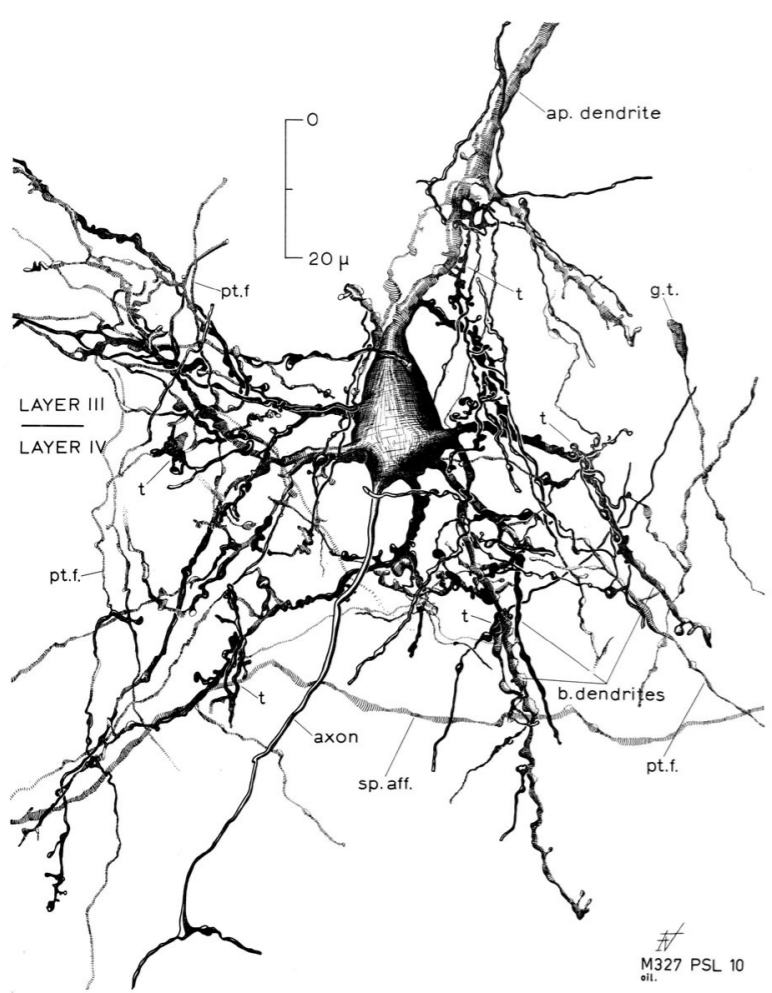


$$s_i(t) = \sum_{j=1}^N W_{ij} \sum_{m \in \mathbb{Z}} \eta(t - T_j^m)$$

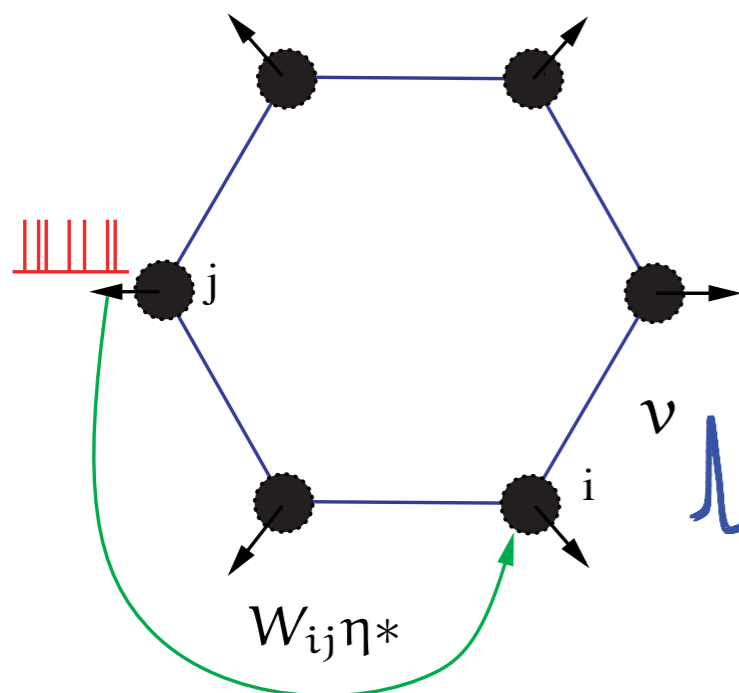


PSP





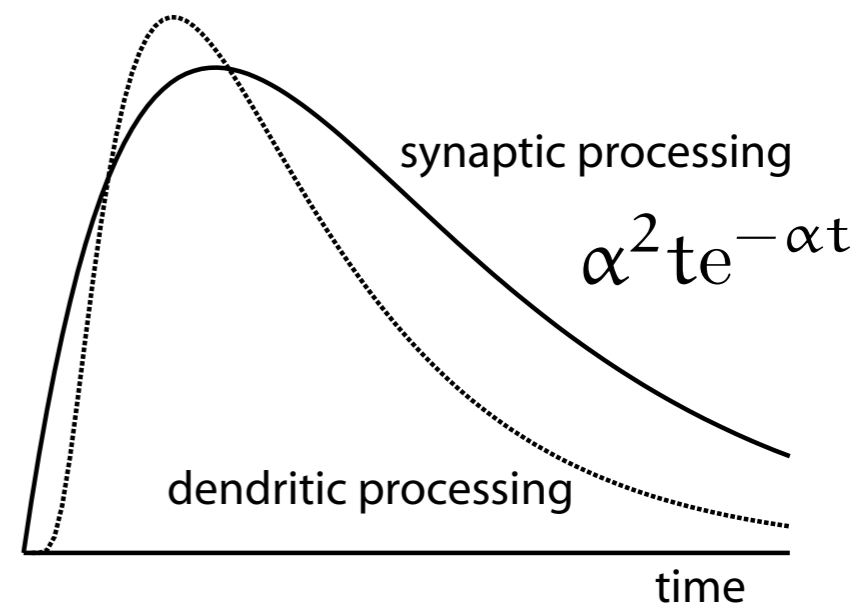
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HH or other



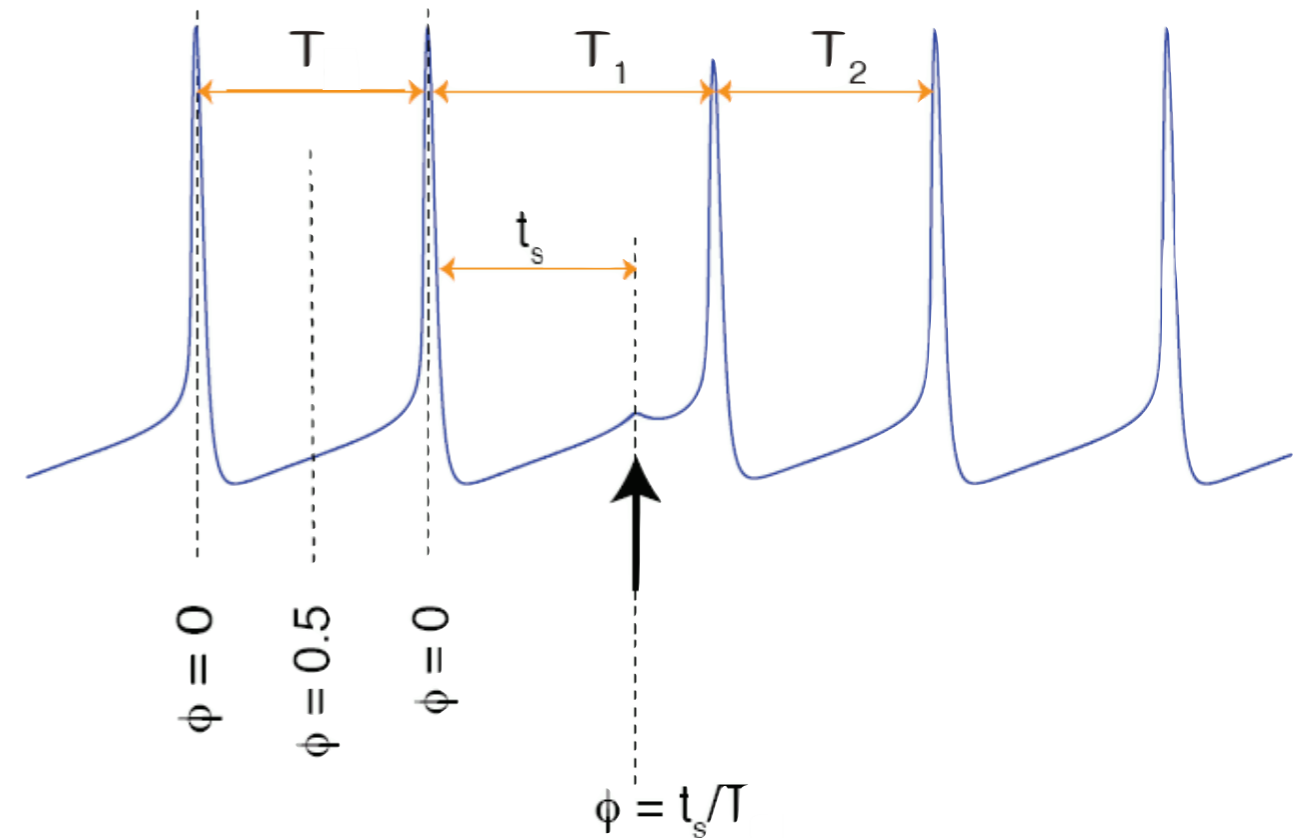
PSP





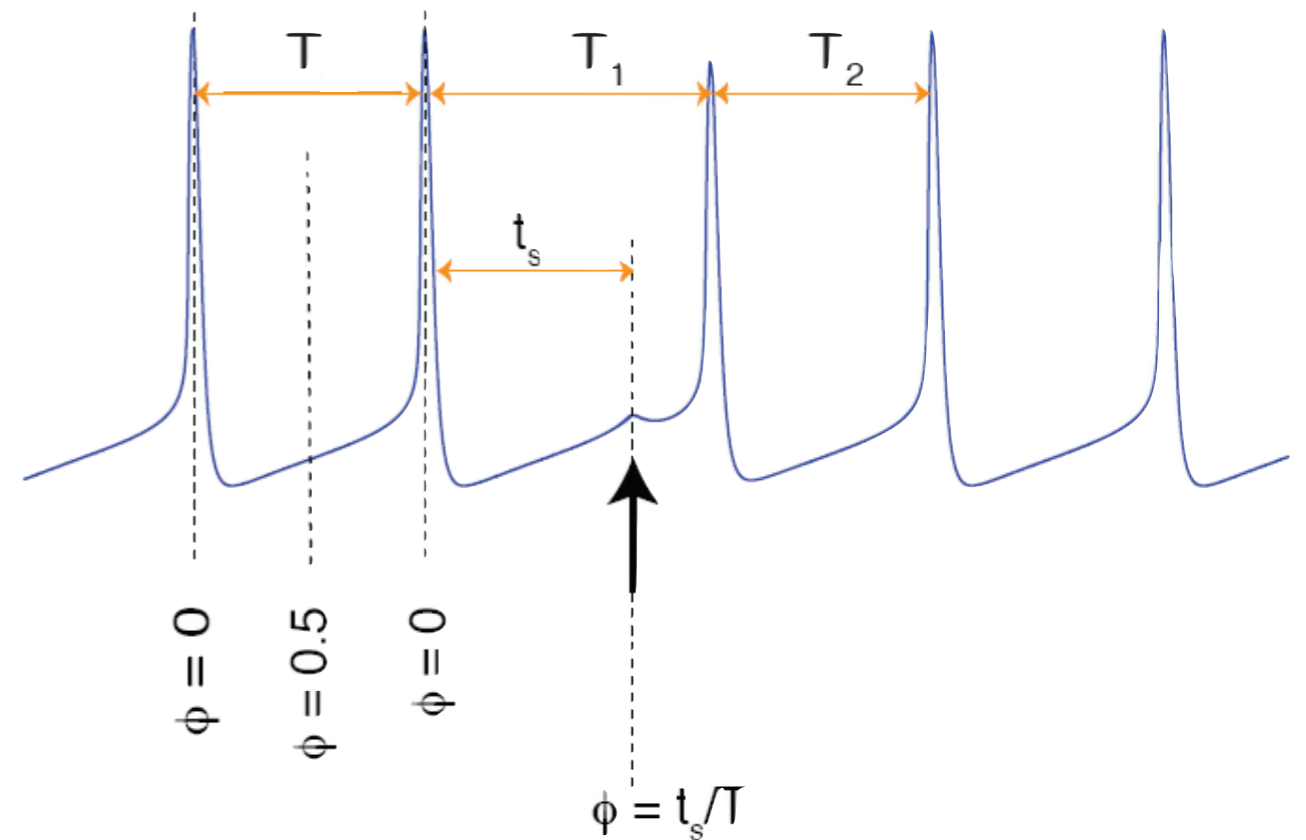
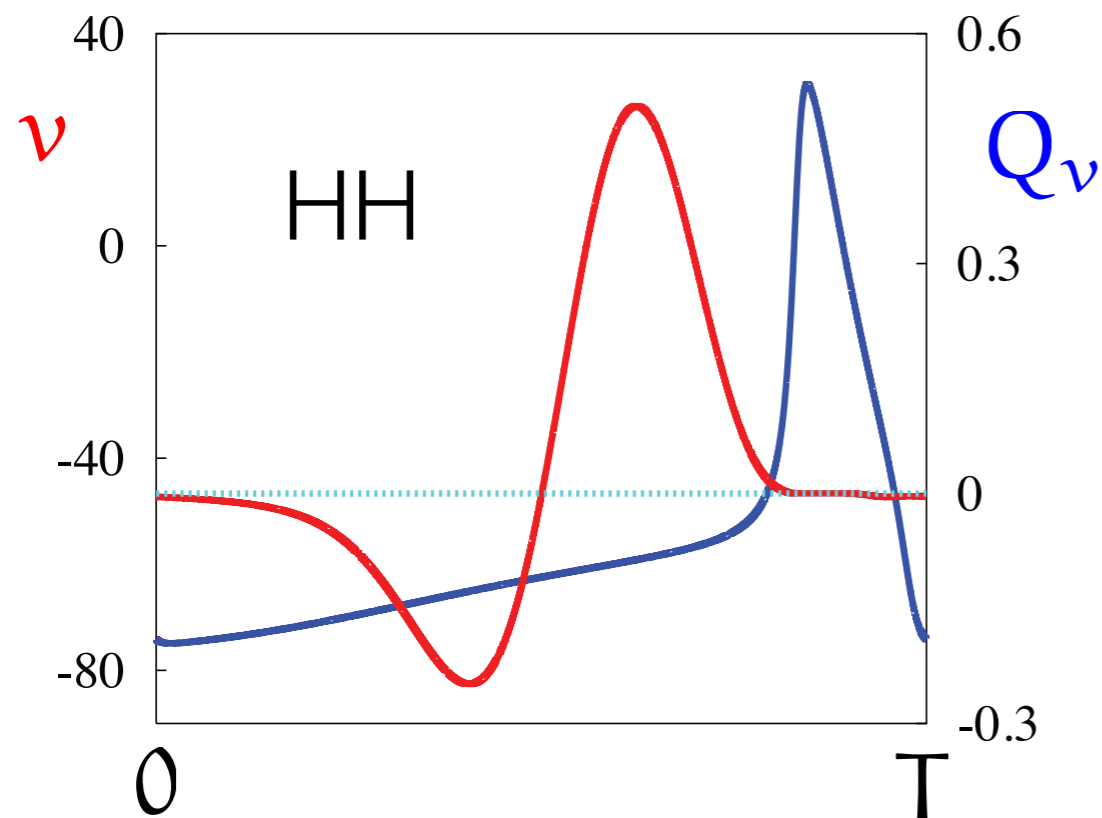
# Phase Response Curves

A **PRC** tabulates the transient change in the cycle period of an oscillator induced by a perturbation as a function of the phase at which it is received.



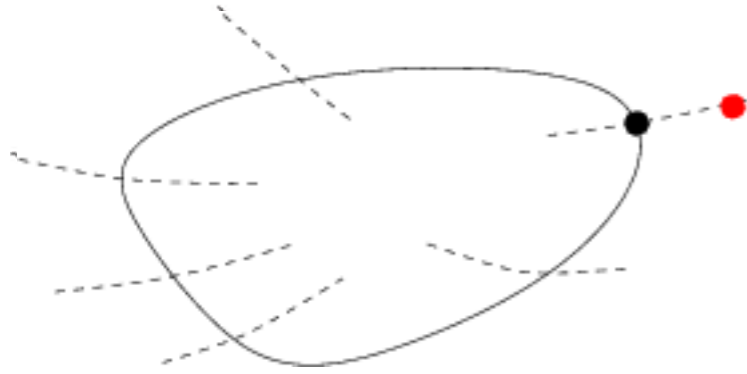
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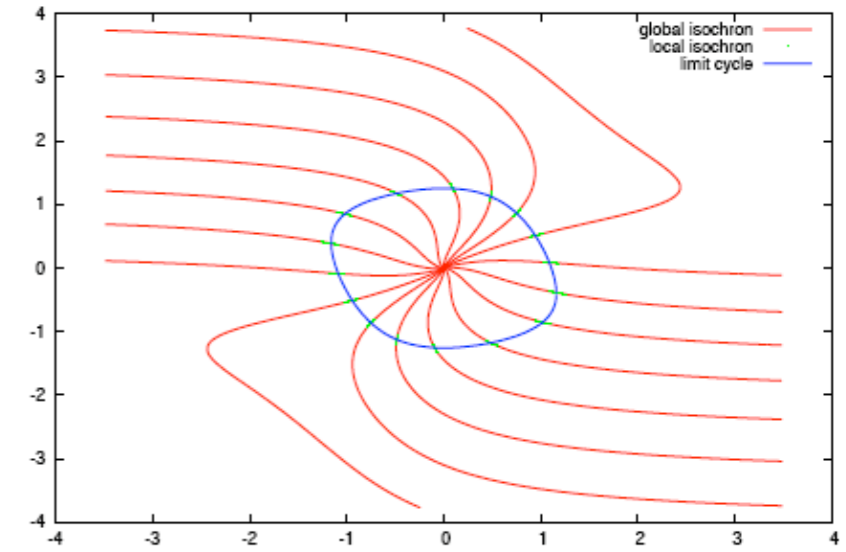


obtained numerically  
or experimentally

$$Q = \nabla_z \theta$$



Isochrons as leaves of the stable manifold of a hyperbolic limit cycle



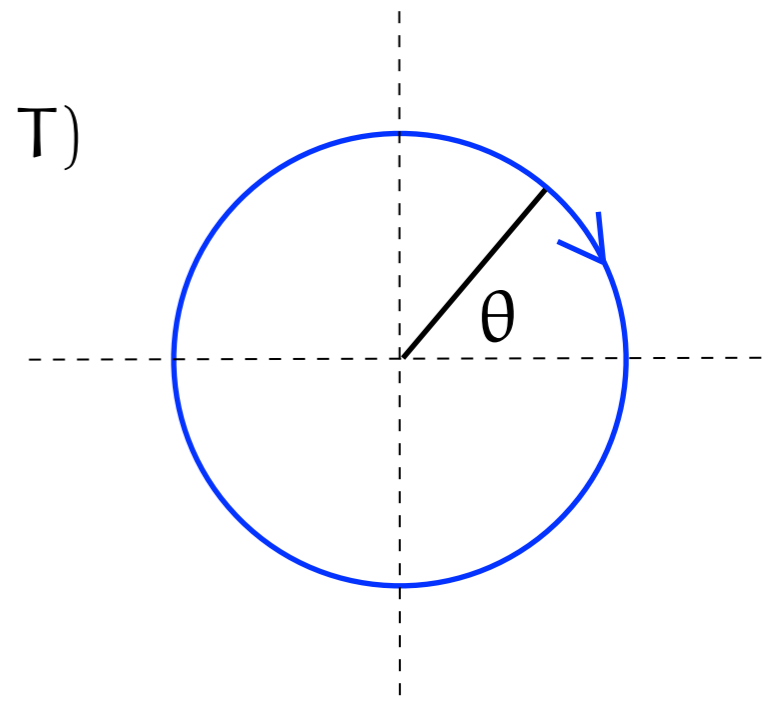
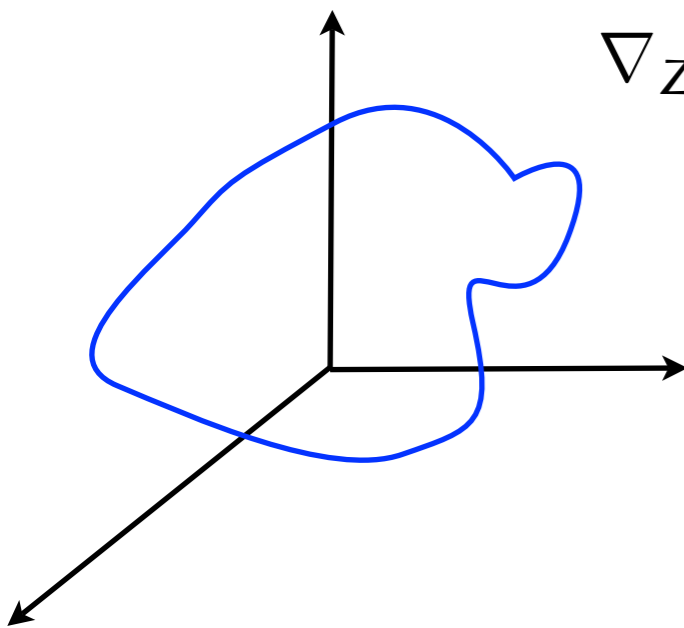
Call the orbit  $z = Z(t)$  where  $\dot{z} = F(z)$

Introduce a phase (isochronal coordinates)  $\theta$

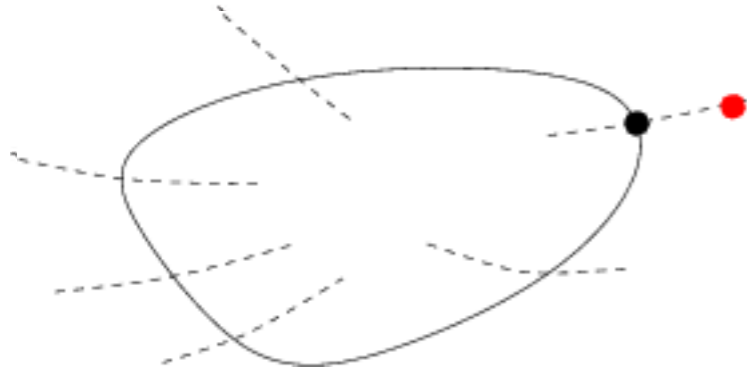
$$\frac{dQ}{dt} = D(t)Q, \quad D(t) = -DF^T(Z(t))$$

$$\nabla_{Z(0)} \cdot F(Z(0)) = \frac{1}{T} \quad \text{and} \quad Q(t) = Q(t + T)$$

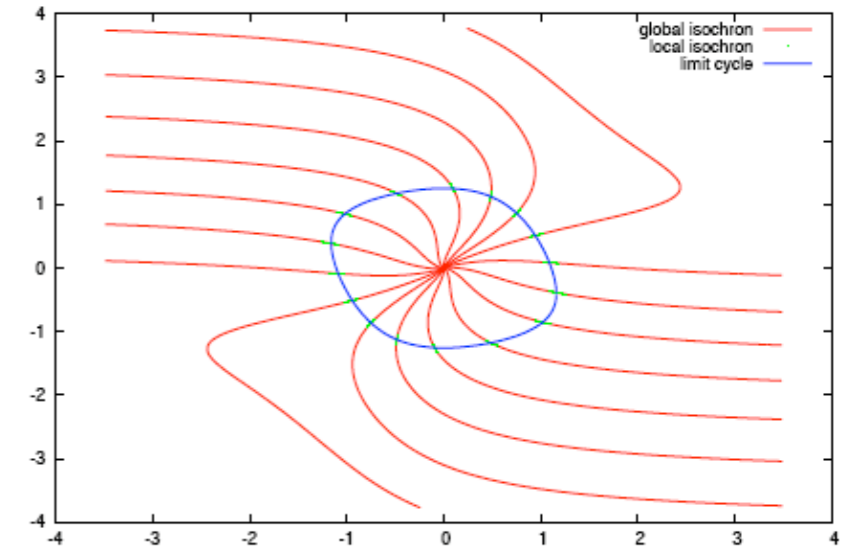
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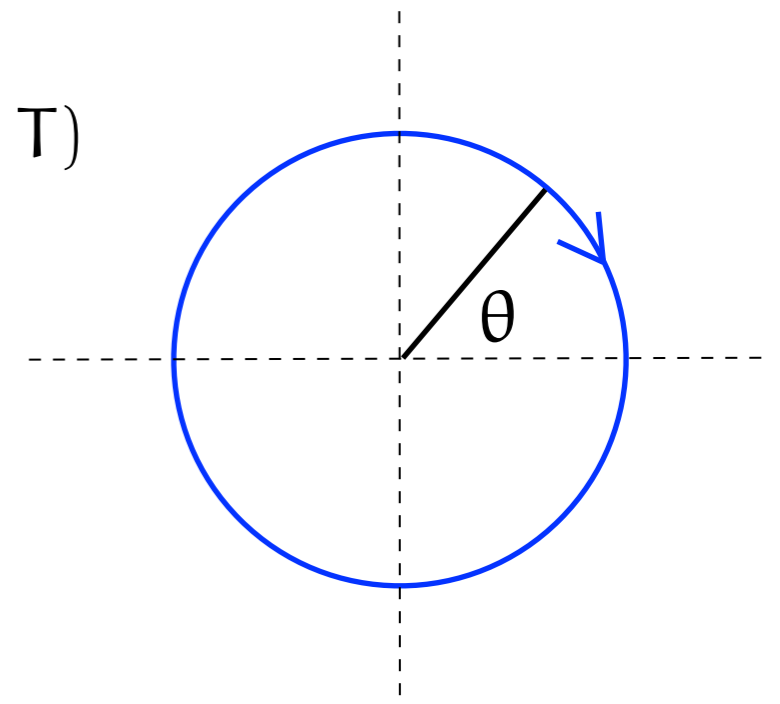
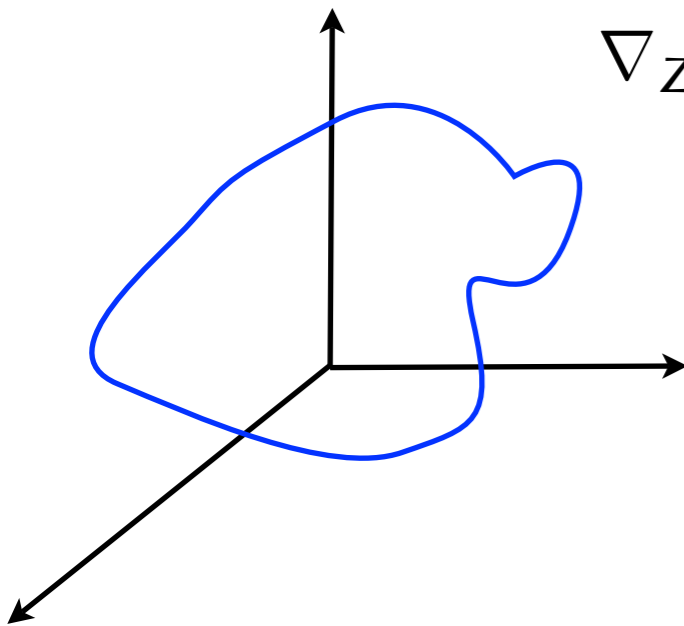
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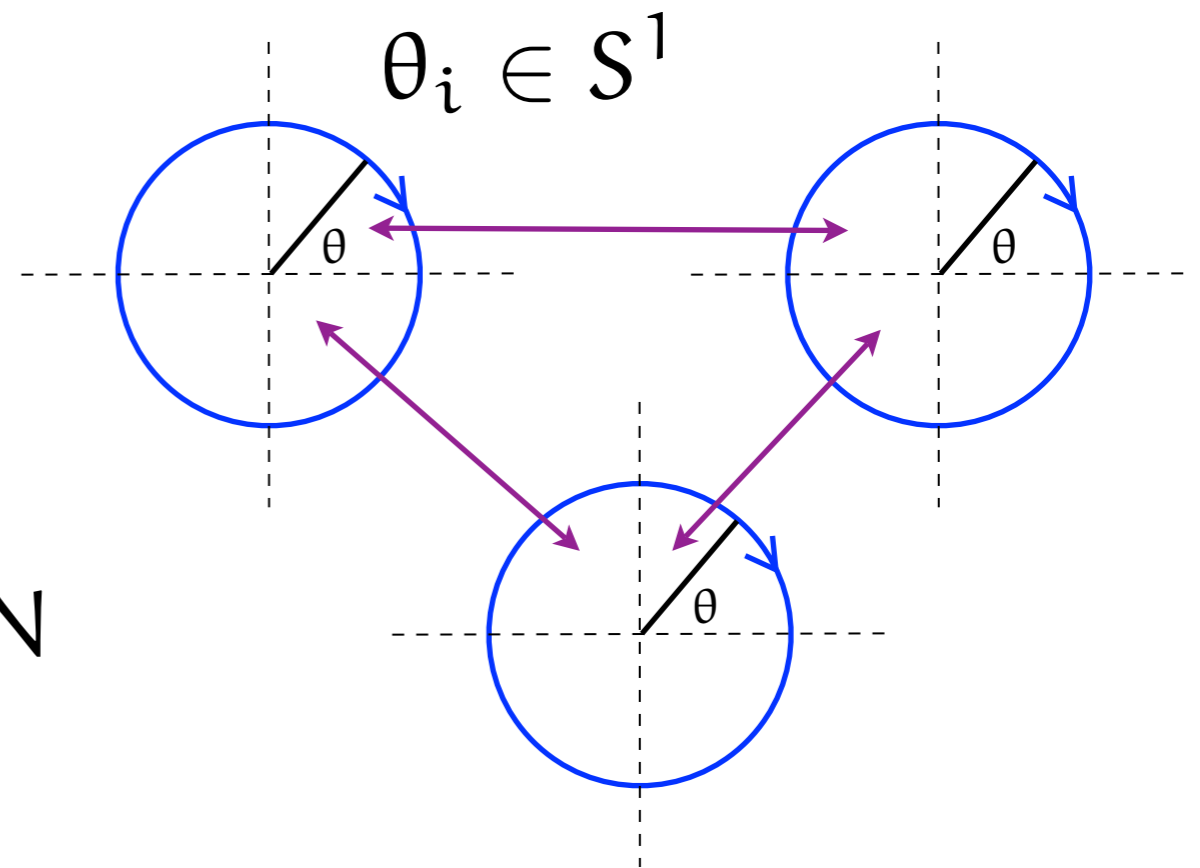
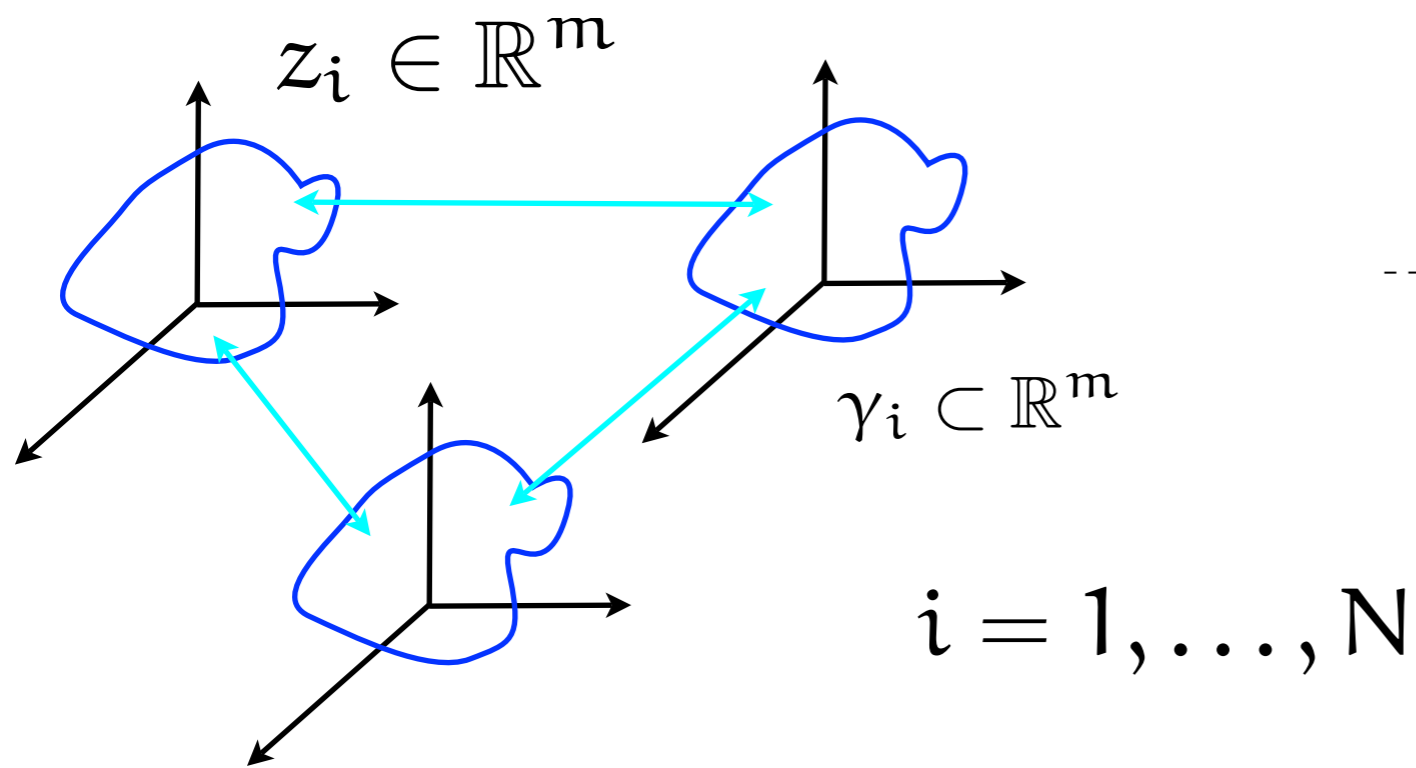
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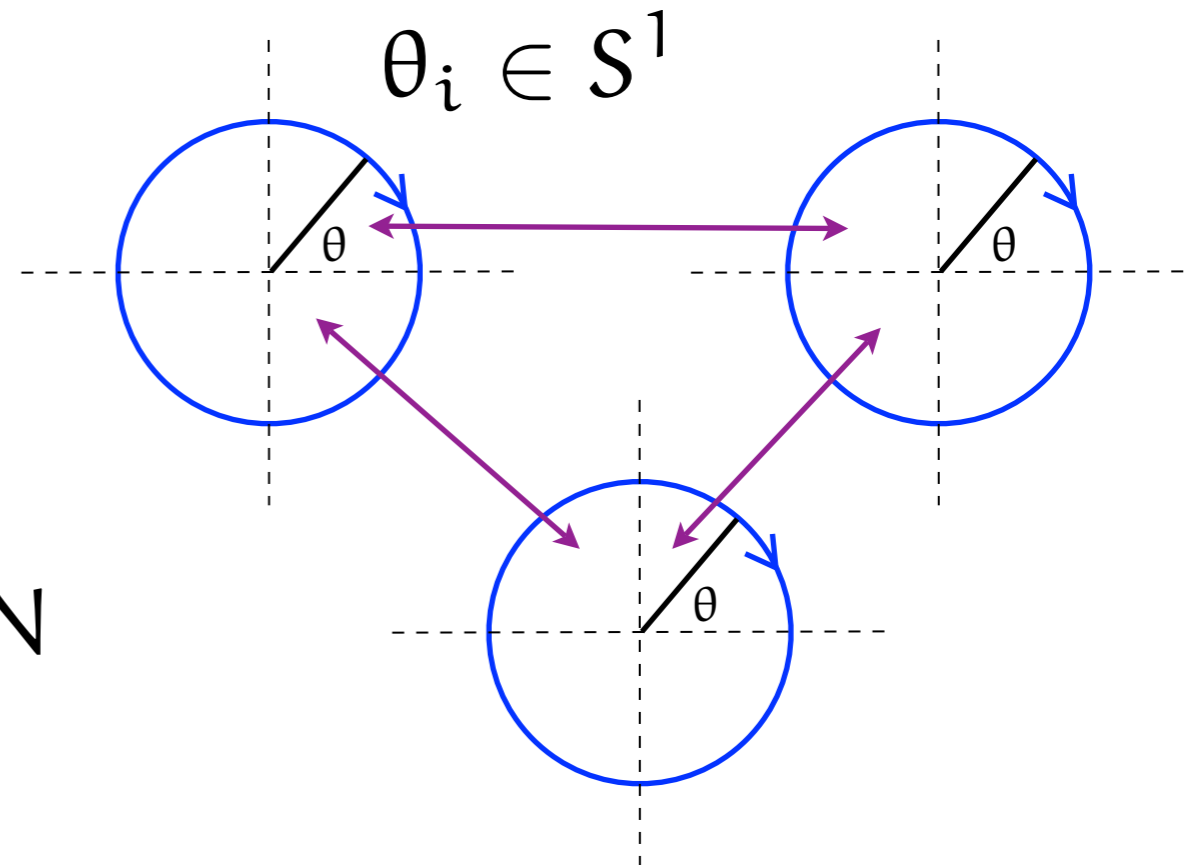
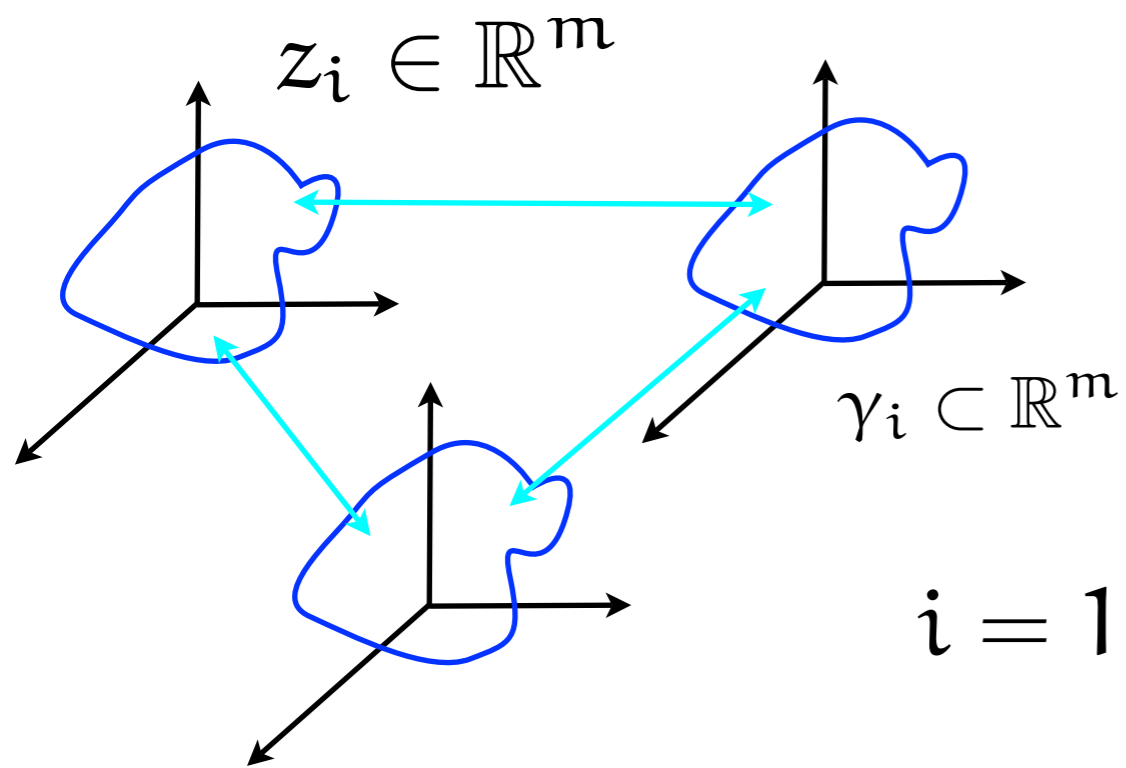
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# Weak Coupling

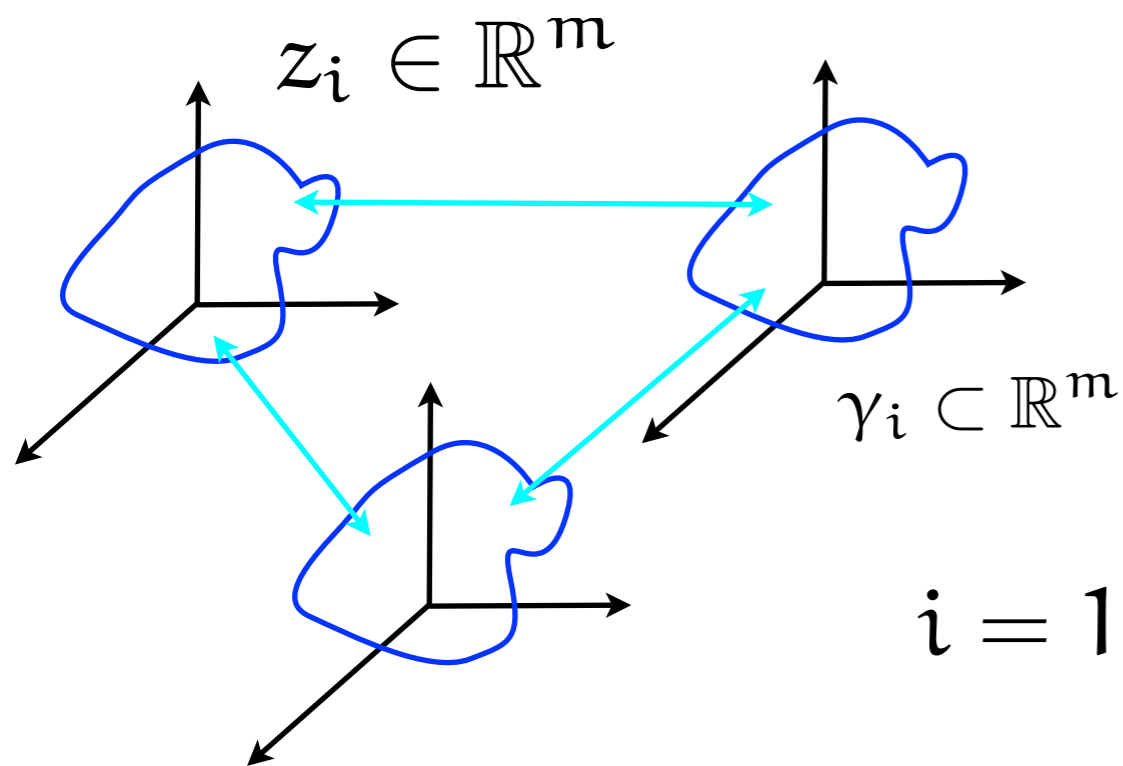


# Weak Coupling

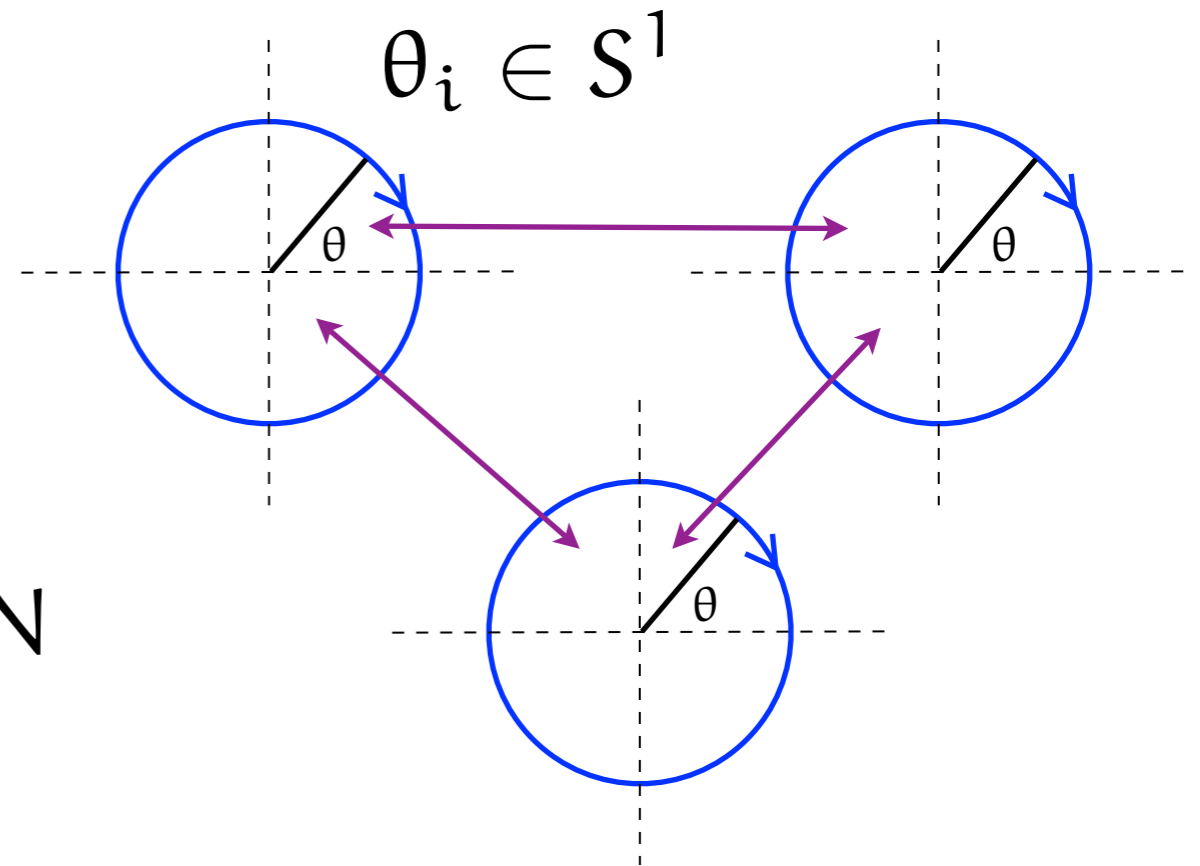


$\dot{z}_i = F(z_i) + \epsilon G_i(z_1, \dots, z_N)$  Uncoupled system has an exponentially stable limit cycle  $\gamma_i$

# Weak Coupling



$i = 1, \dots, N$

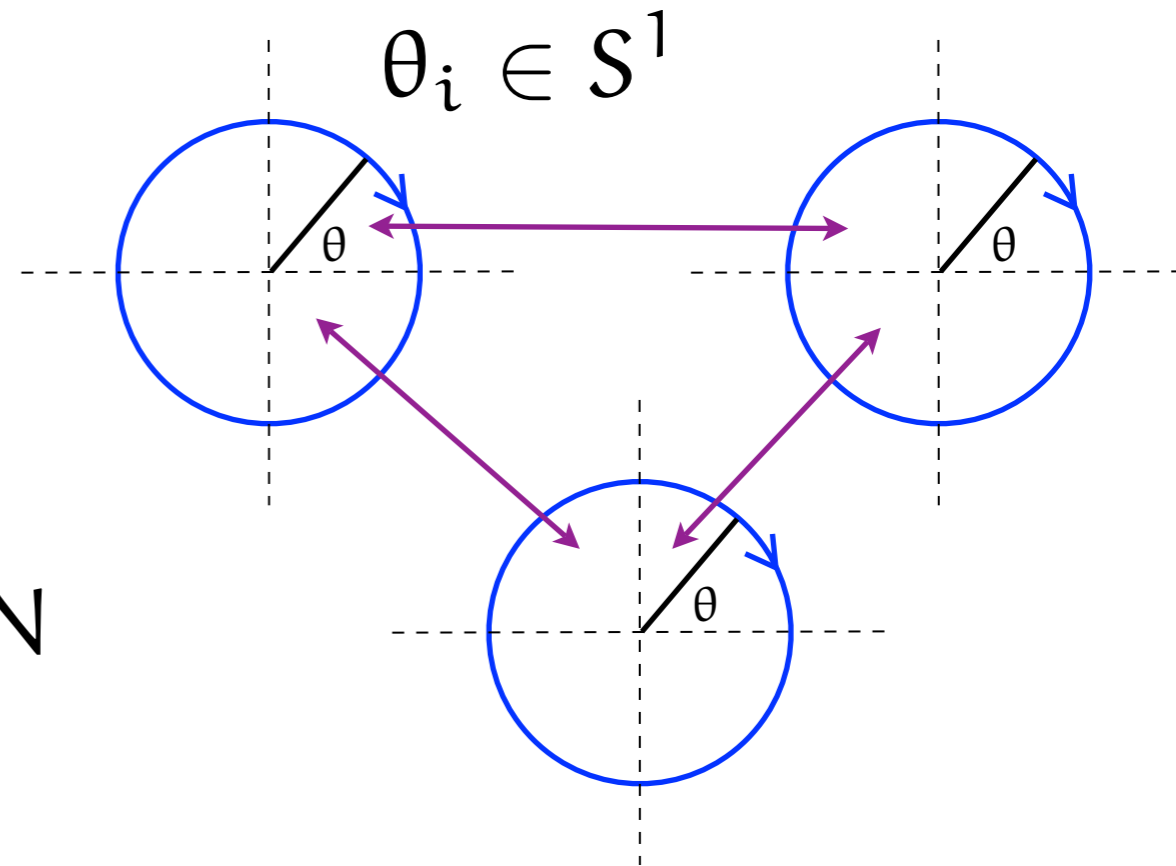
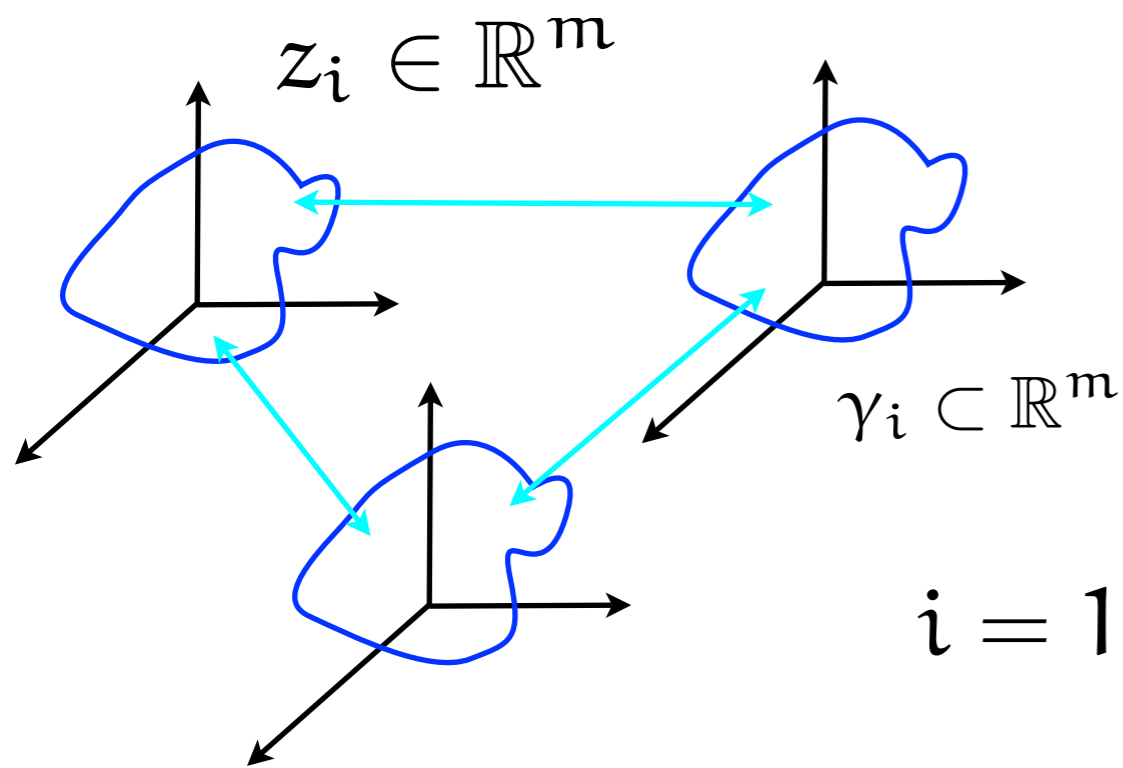


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Direct product of hyperbolic limit cycles is a normally hyperbolic invariant manifold

$$\dot{\theta}_i = \frac{1}{T} + \epsilon \langle Q(\theta_i), G_i(\Gamma(\theta)) \rangle$$

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Drive

PRC



# Phase oscillator network

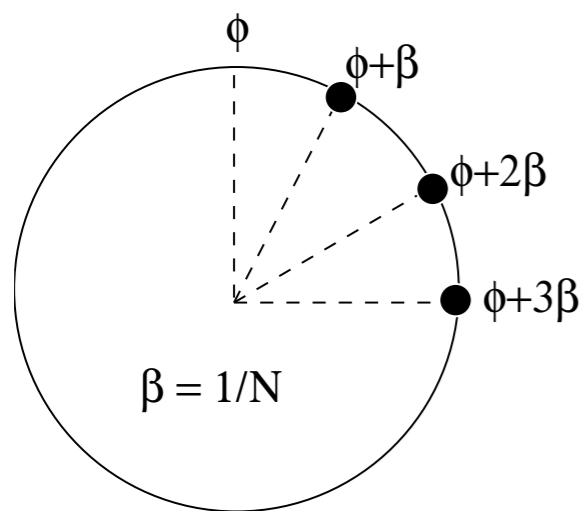
(after averaging)

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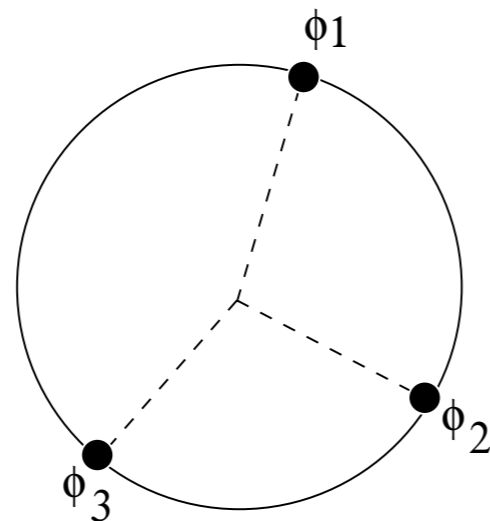
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$\text{Dim}(\text{Fix}(\Gamma)) = 1$



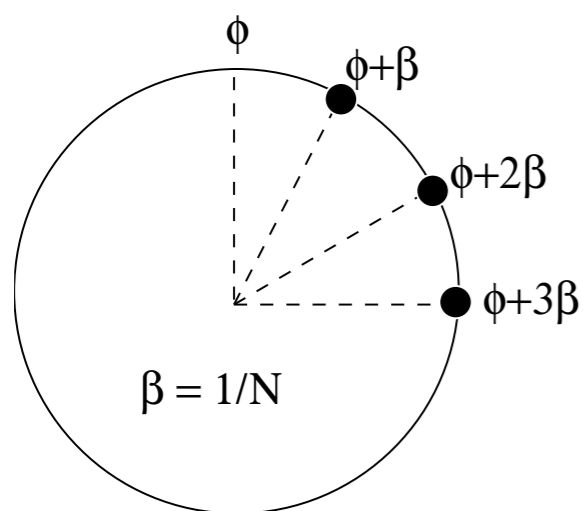
$\text{Dim}(\text{Fix}(\Gamma)) = 3$

Bifurcations from maximally symmetric solutions to ones with smaller isotropy groups. eg. cluster states.

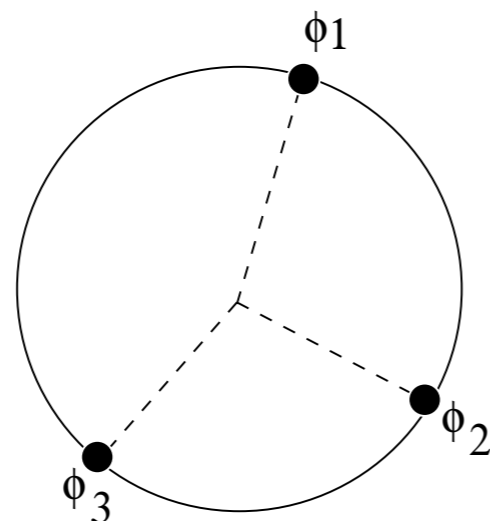
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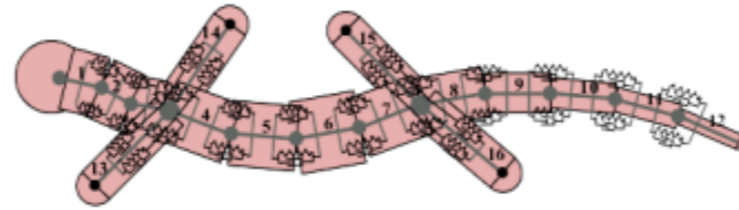
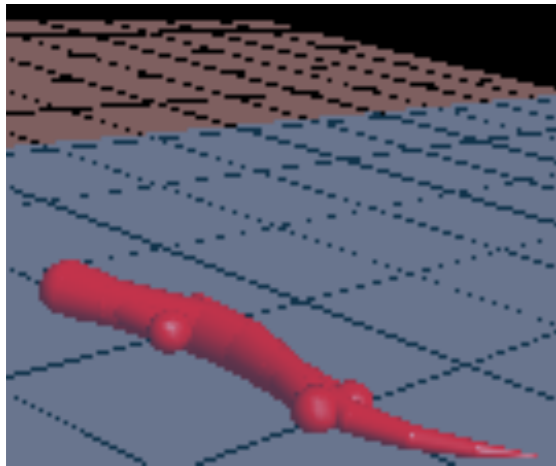
Bifurcations from maximally symmetric solutions to ones with smaller isotropy groups. eg. cluster states.

Stability of synchronous solution determined by eigenvalues of

$$\hat{H}_{ij} = H'(0) \left[ w_{ij} - \delta_{ij} \sum_k w_{ik} \right]$$

# Oscillator networks

Applications of weakly coupled oscillator theory to CPGs, robot control, ...

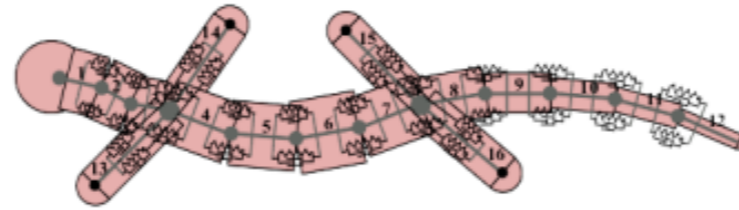
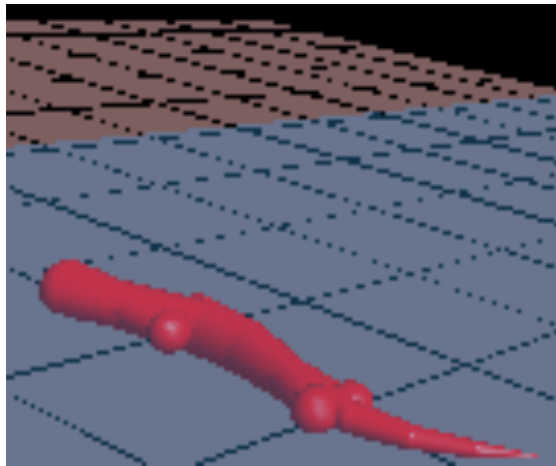


Biorobotics lab at EPFL



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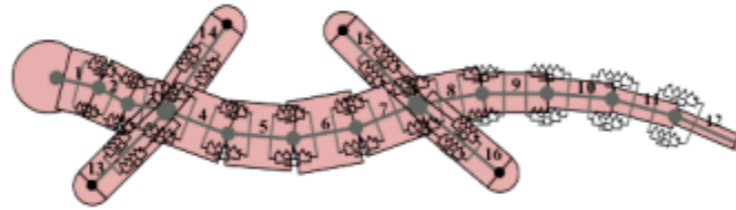
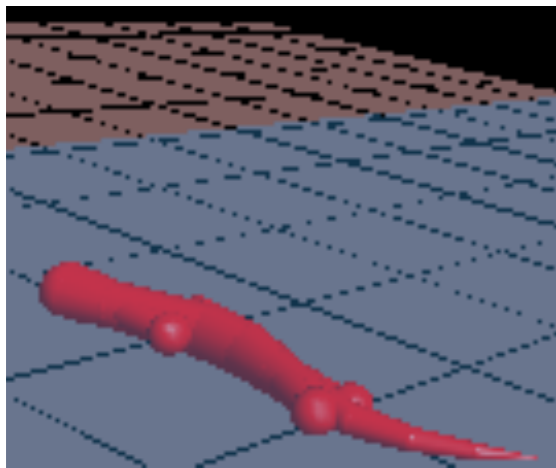


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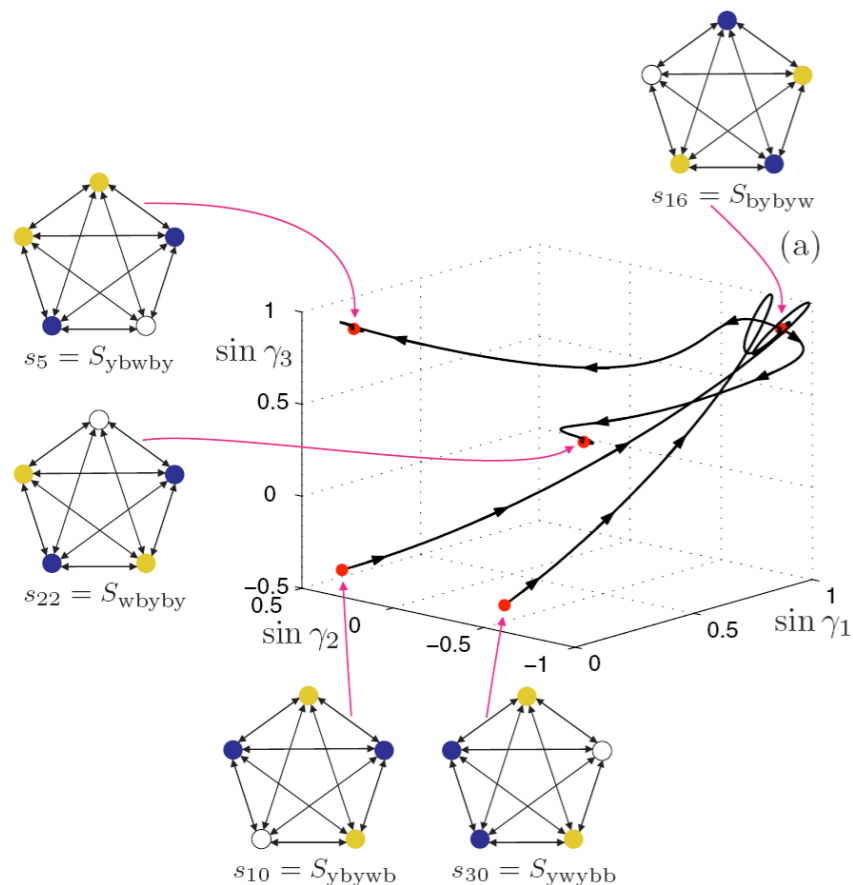


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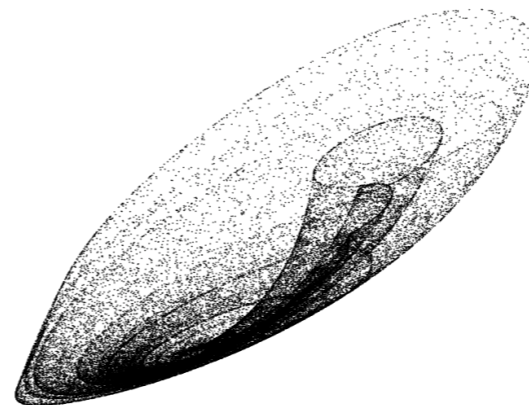


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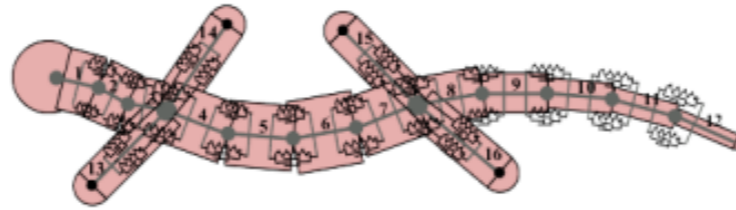
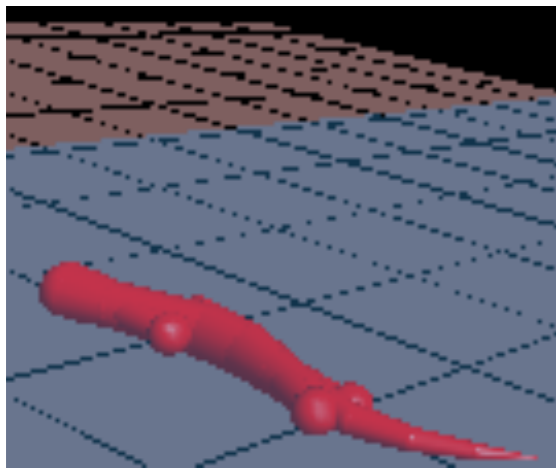
Rabinovich et al. Dynamical principles in neuroscience, Rev. Mod. Phys., 78, 2006.

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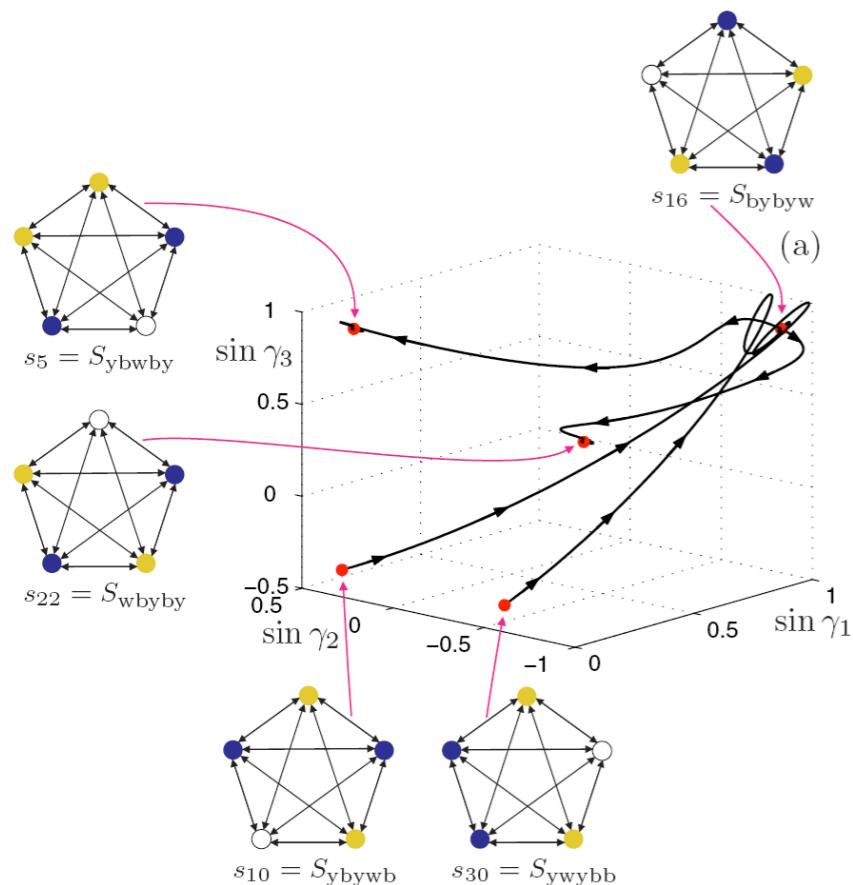


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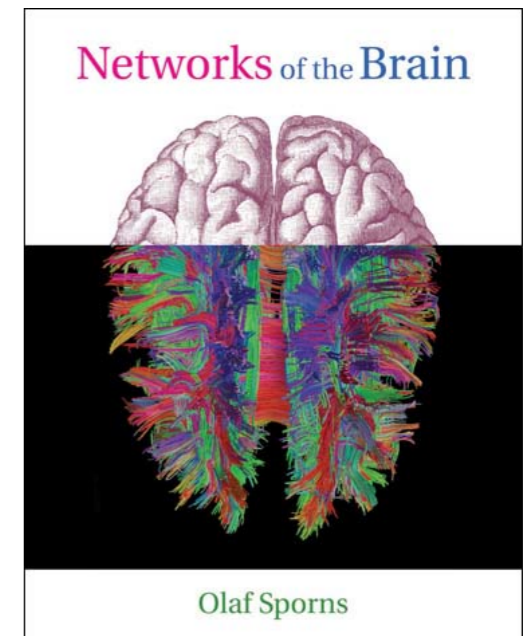
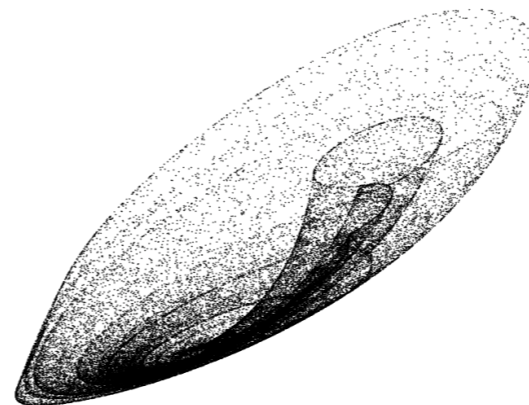


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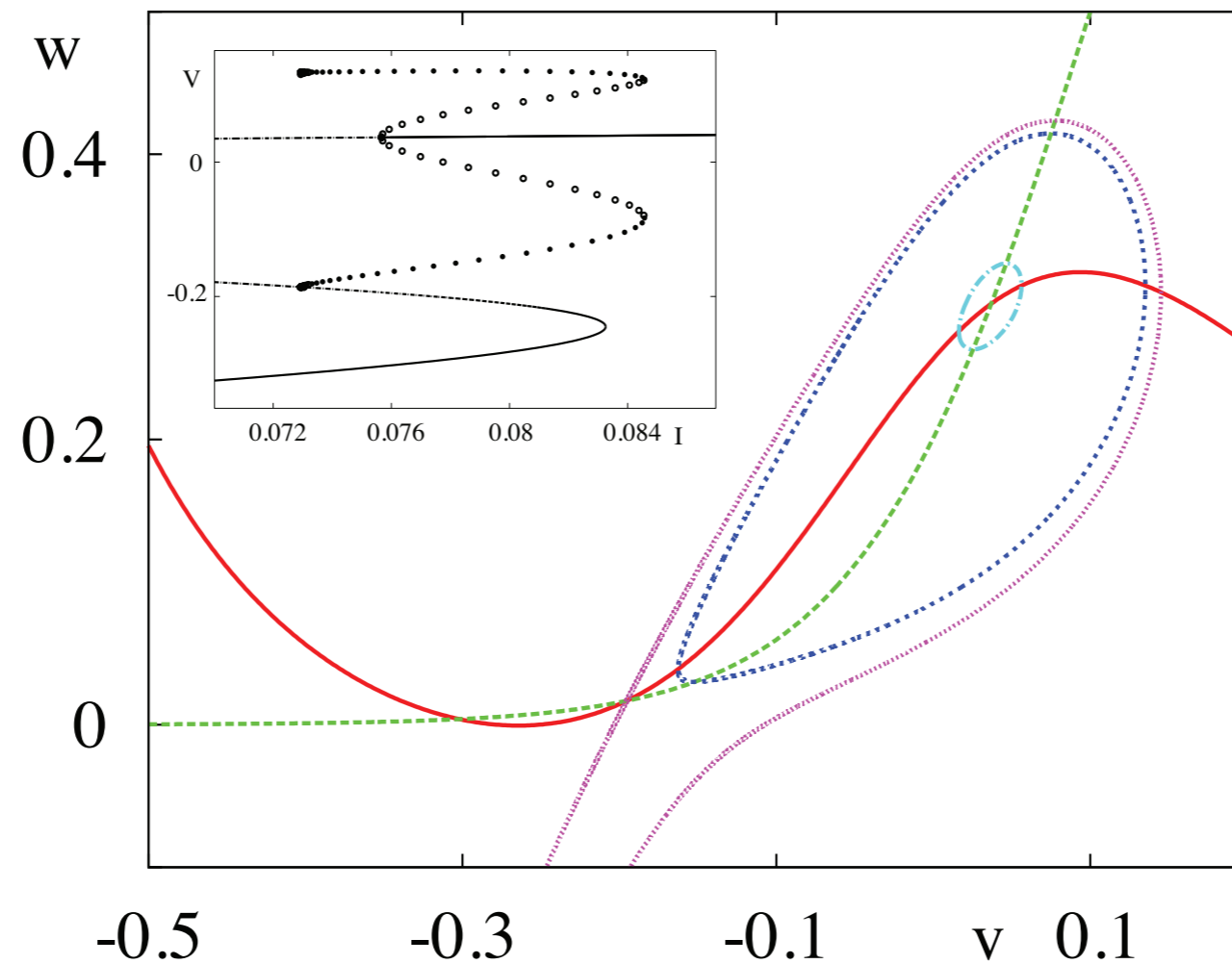
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# Breakdown of phase reduction

[the 'i' in iPRC]

Morris-Lecar example



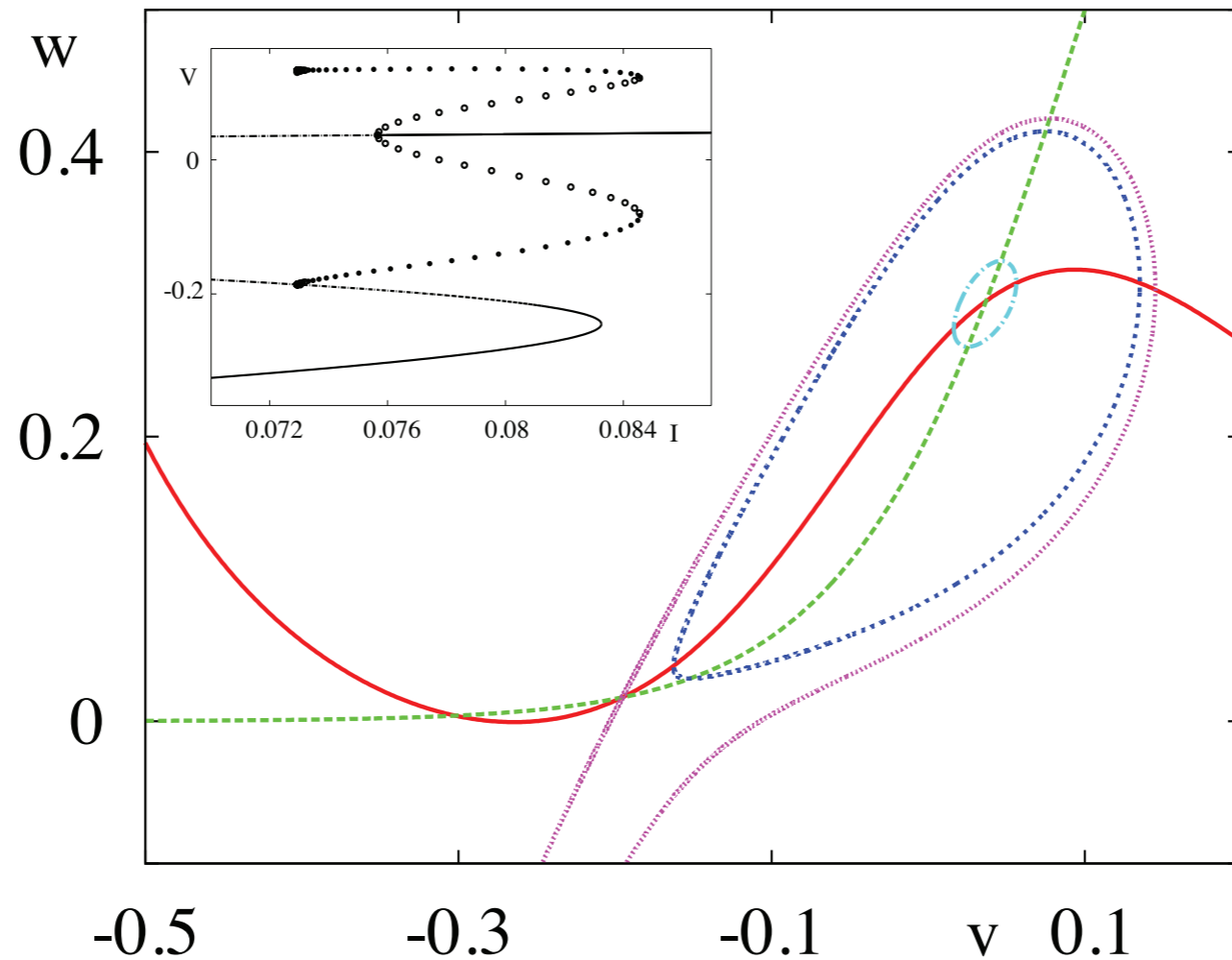


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Leaving the basin of the periodic orbit

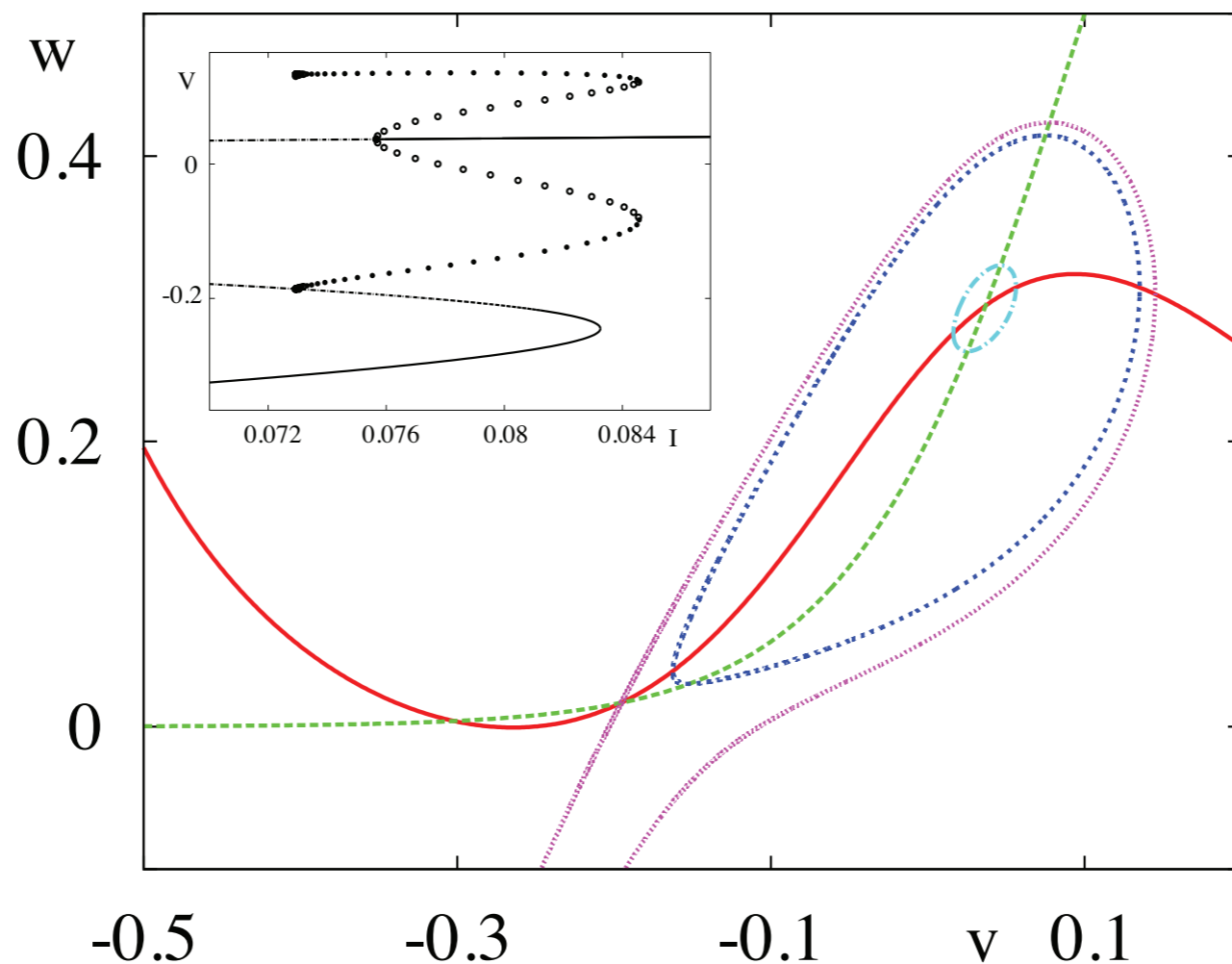


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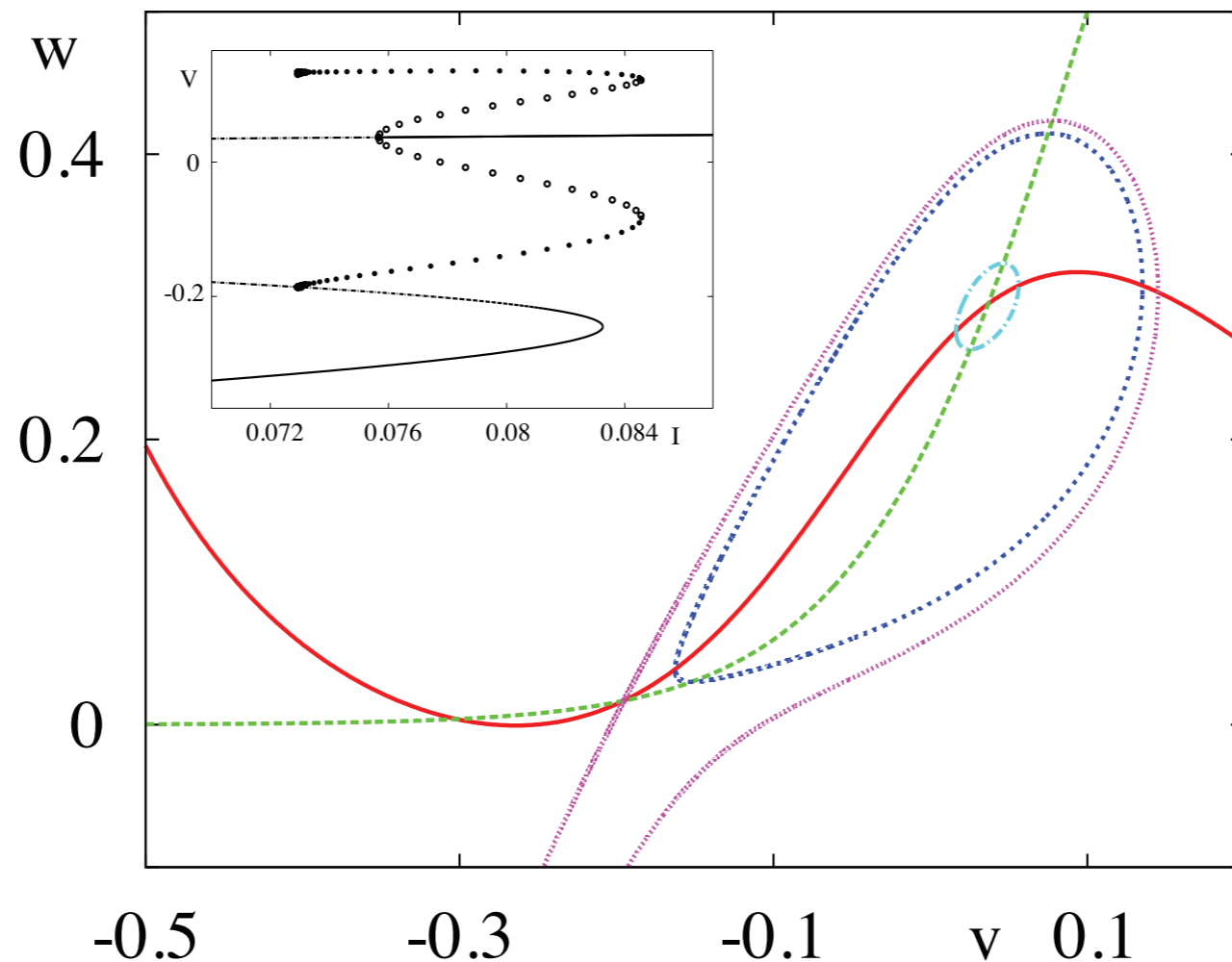
Invariant structures and *trapping*

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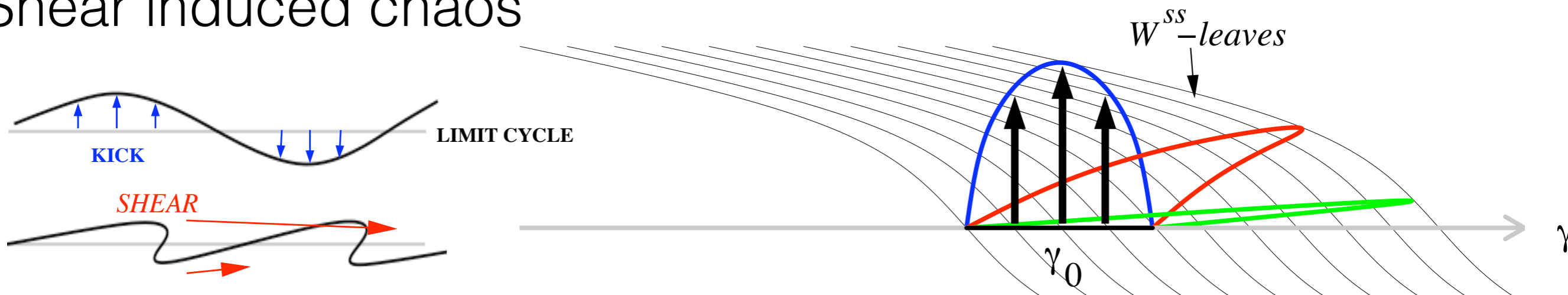
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Invariant structures and *trapping*

Shear induced chaos



# Aside - shear induced chaos

Q Wang and L-S Young “Strange attractors in periodically-kicked limit cycles and Hopf bifurcations”, 2003 Comm. Math. Phys.

A toy model (that “breaks” the invariant circle)

$$\dot{\theta} = 1 + \sigma y, \quad \dot{y} = -\lambda y + A H(\theta) \sum_{n=0}^{\infty} \delta(t - nT)$$

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Need

$$\frac{\sigma}{\lambda} A \equiv \frac{\text{shear}}{\text{contraction rate}} \text{kick}$$

sufficiently large

[depends on ‘bump’ function  $H$ ]  $H(\theta) = \sin(2\pi\theta)$

# Aside - shear induced chaos

Q Wang and L-S Young "Strange attractors in periodically-kicked limit cycles and Hopf bifurcations", 2003 Comm. Math. Phys.

A toy model (that "breaks" the invariant circle)

$$\dot{\theta} = 1 + \sigma y, \quad \dot{y} = -\lambda y + A H(\theta) \sum_{n=0}^{\infty} \delta(t - nT)$$

When  $A = 0$  the system has a limit cycle  $\gamma = S^1 \times \{0\}$

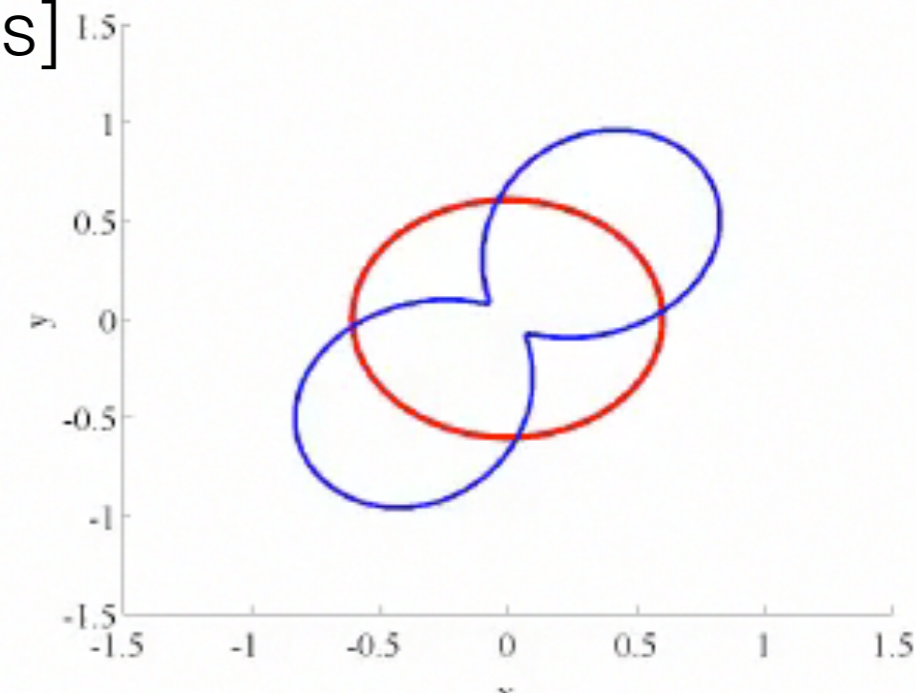
When  $A \neq 0$  there is a positive measure set of  $T$  that allows a 'strange attractor'. [sustained chaotic behaviour and observable for large sets of initial conditions]

Need

$$\frac{\sigma}{\lambda} A \equiv \frac{\text{shear}}{\text{contraction rate}} \text{kick}$$

sufficiently large

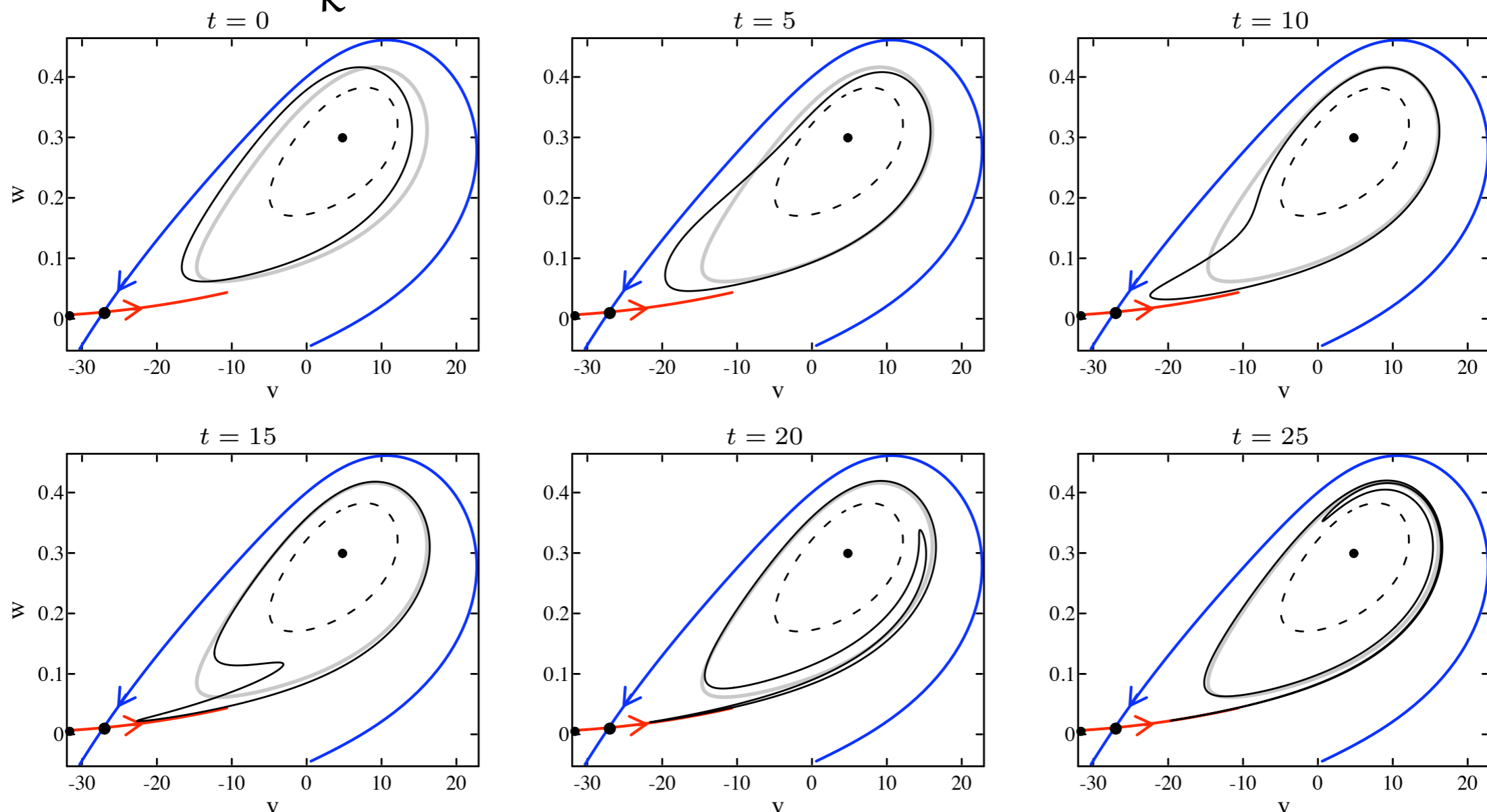
[depends on 'bump' function  $H$ ]  $H(\theta) = \sin(2\pi\theta)$





# Chaotic response of ML to periodic kicking [not a toy model!]

$$\dot{\mathbf{v}} \rightarrow \dot{\mathbf{v}} + A \sum_k \delta(t - kT) \quad \text{Shear induced folding one kick}$$

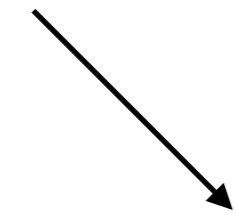


iPRC/phase analysis would not predict chaos

# Phase-*amplitude*

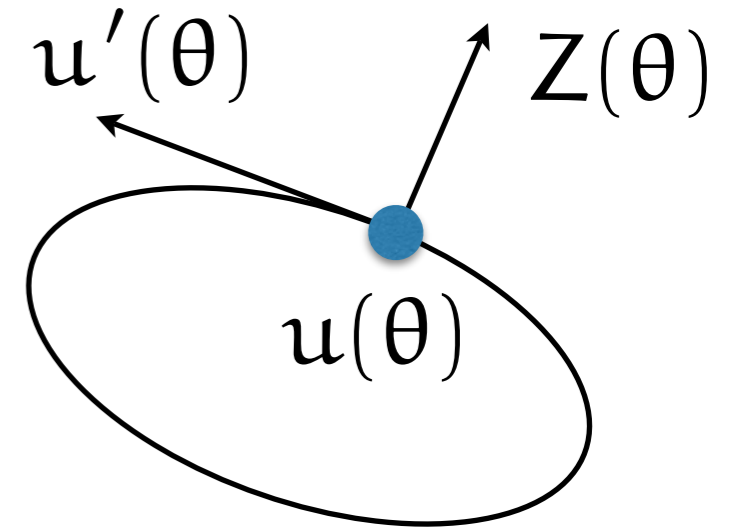
Single cell - phase and amplitude (Hale 1969)

on cycle



$$z = u(\theta) + Z(\theta)\rho$$

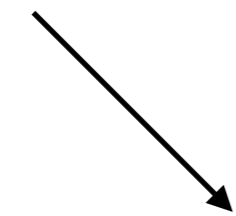
orthogonal to cycle



# Phase-*amplitude*

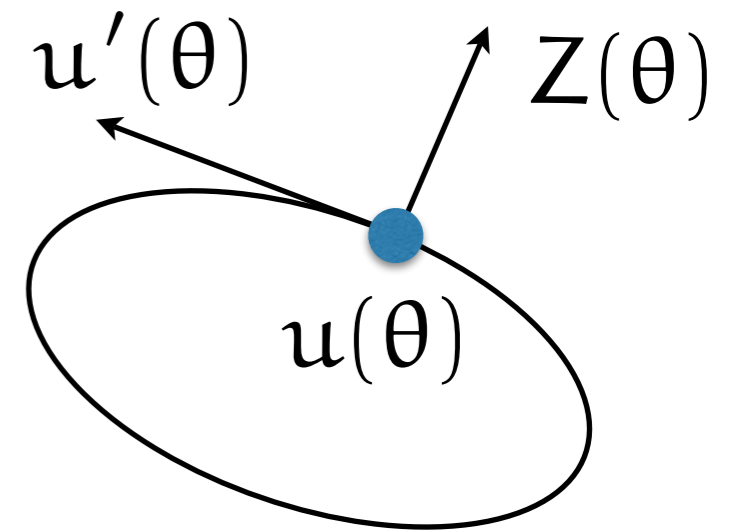
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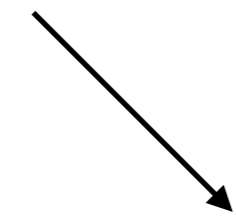
$$\dot{\theta} = 1 + f_1(\theta, \rho)$$

$$\dot{\rho} = A(\theta)\rho + f_2(\theta, \rho)$$

# Phase-*amplitude*

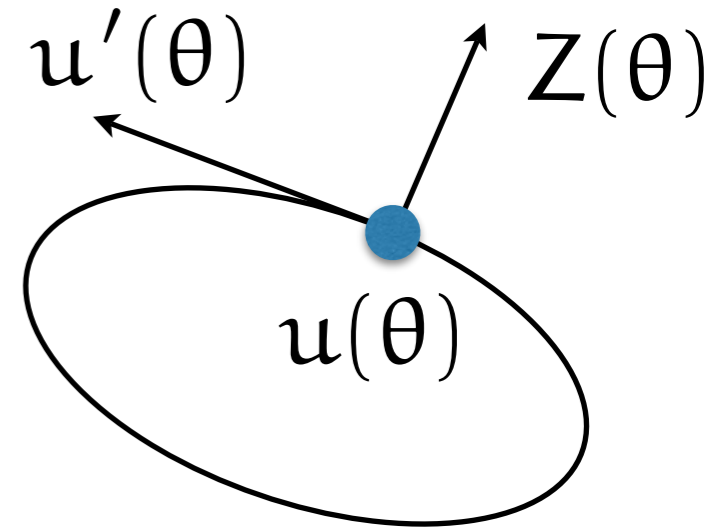
Single cell - phase and amplitude (Hale 1969)

on cycle



$$z = u(\theta) + Z(\theta)\rho$$

orthogonal to cycle



$$A(\theta) = Z^T \left[ -\frac{dZ(\theta)}{d\theta} + \frac{\partial F(u(\theta))}{\partial z} Z(\theta) \right]$$

$$\dot{\theta} = 1 + f_1(\theta, \rho)$$

$$\dot{\rho} = A(\theta)\rho + f_2(\theta, \rho)$$

$$|f_1(\theta, \rho)| = O(|\rho|) \quad |\rho| \rightarrow 0$$

$$|f_2(\theta, 0)| = 0 \quad \frac{\partial f_2(\theta, 0)}{\partial \rho} = 0$$

# The perturbed system

$$\dot{z} = F(z) + \varepsilon g(x, t)$$

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$$\dot{\rho} = A(\theta)\rho + f_2(\theta, \rho) + \varepsilon B(\theta, \rho) g(\mathbf{u}(\theta) + Z(\theta)\rho)$$

hide the details for  $h$  and  $B$  [phase-amplitude responses]

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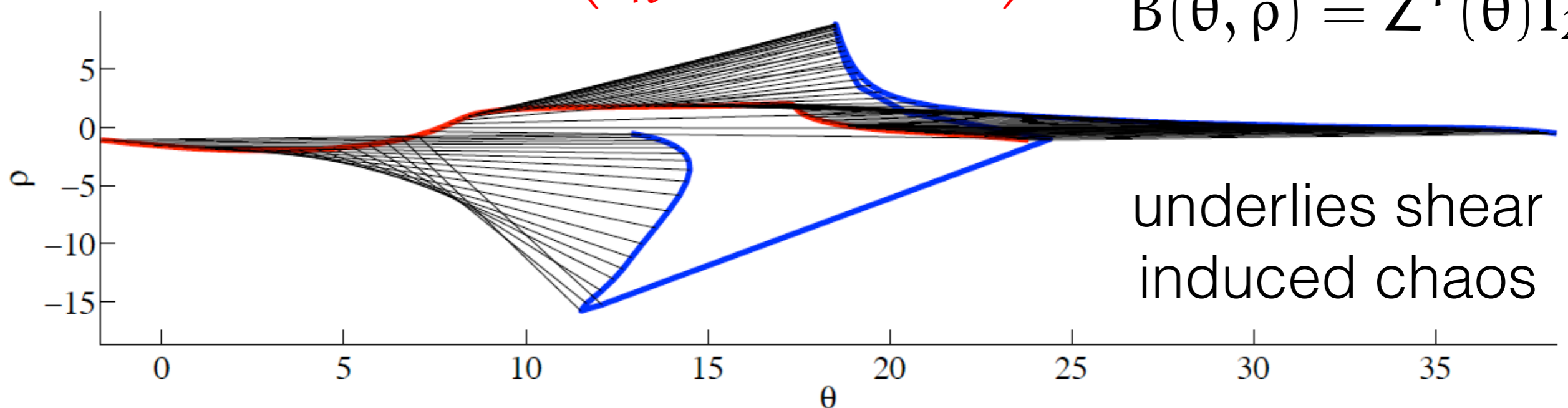
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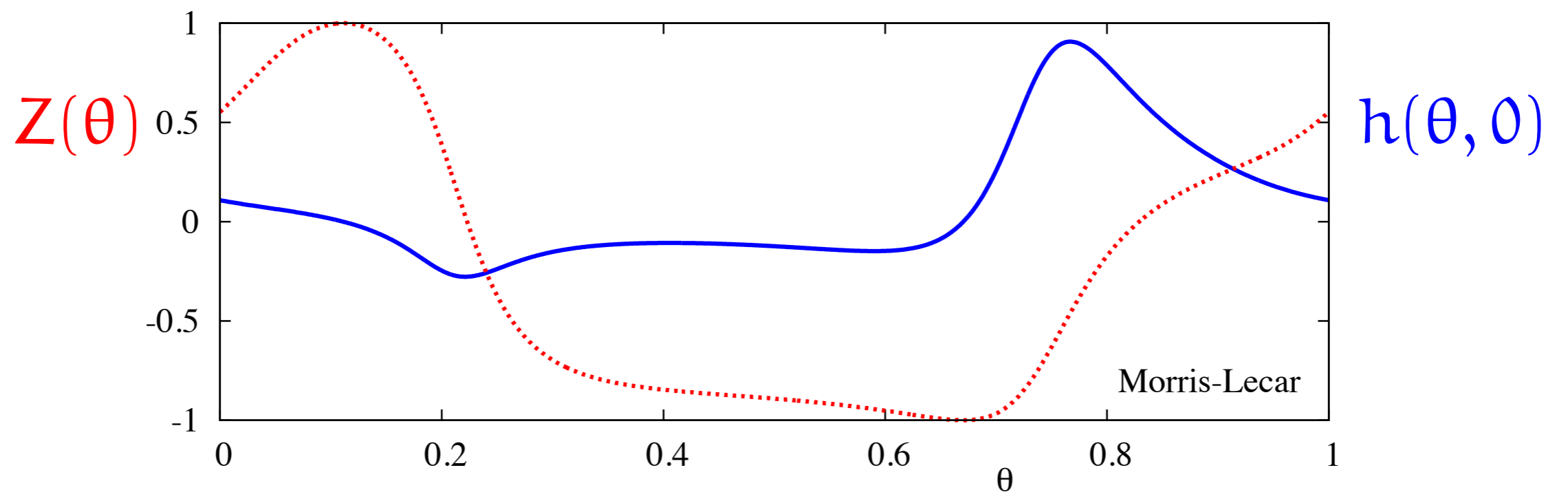
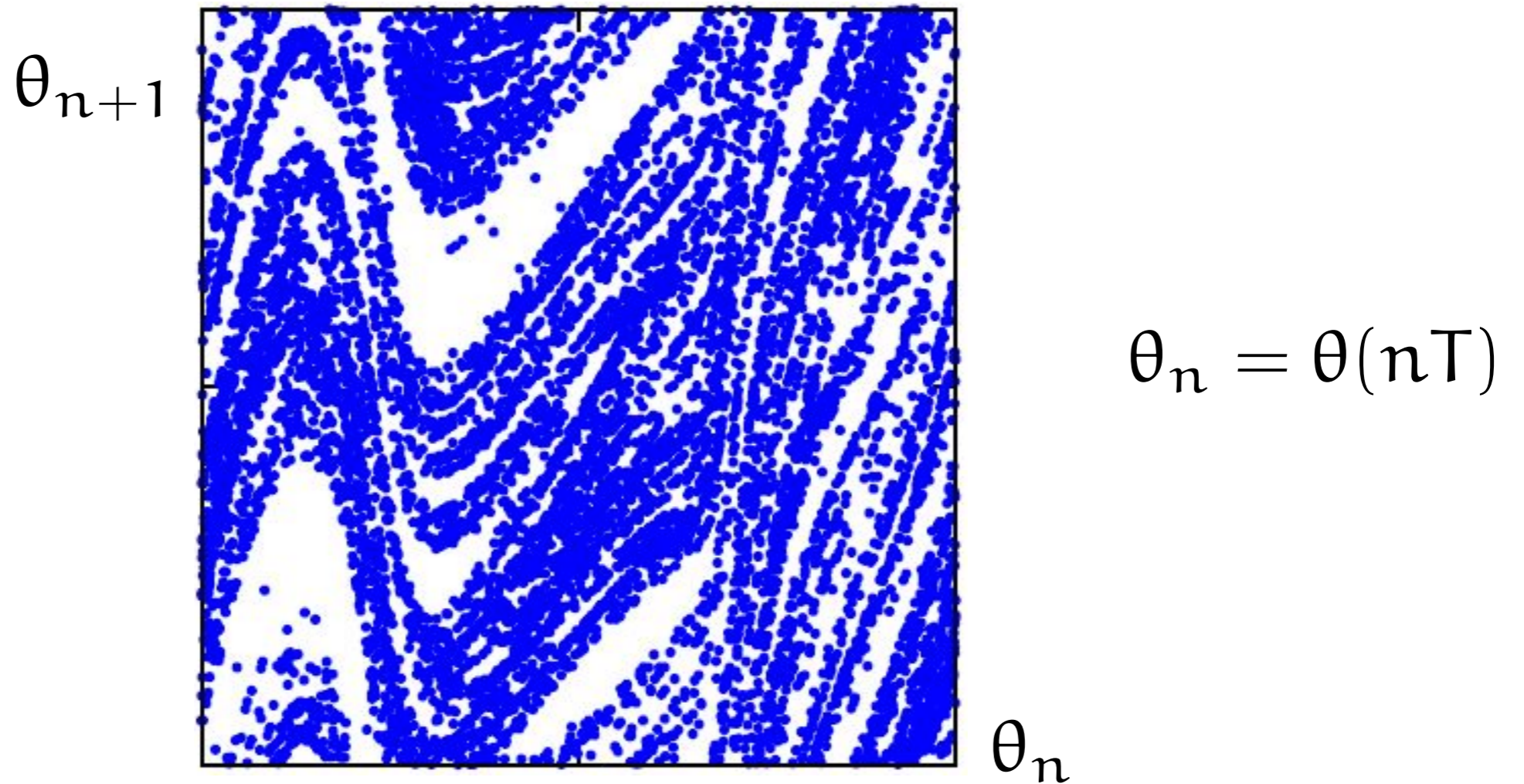
$$g(\mathbf{u}(\theta) + \mathbf{Z}(\theta), t) = \left( \sum_n \delta(t - nT), 0 \right)^T$$

ML (2D):

$$B(\theta, \rho) = \mathbf{Z}^T(\theta) \mathbf{I}_2$$

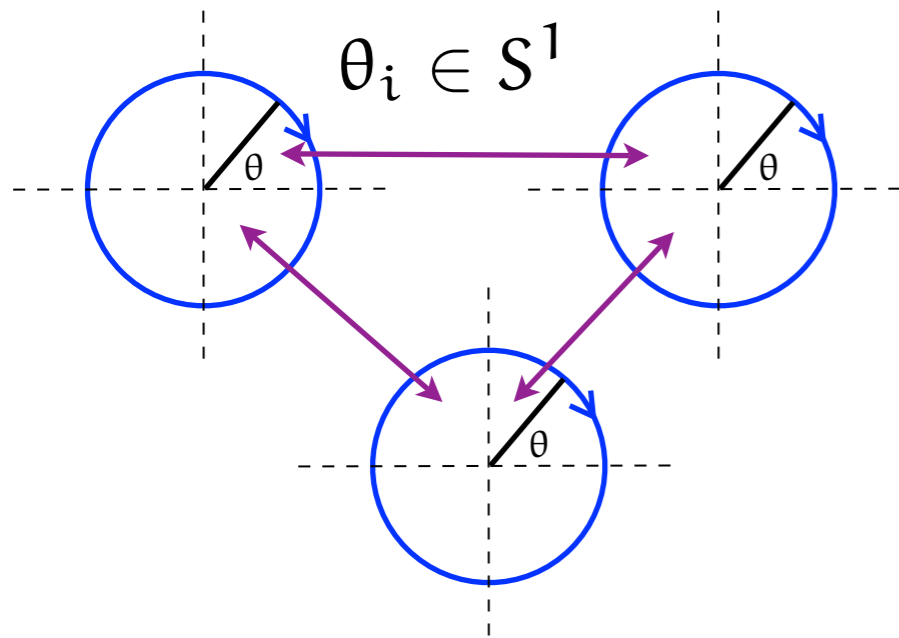


# Positive Lyapunov exponent

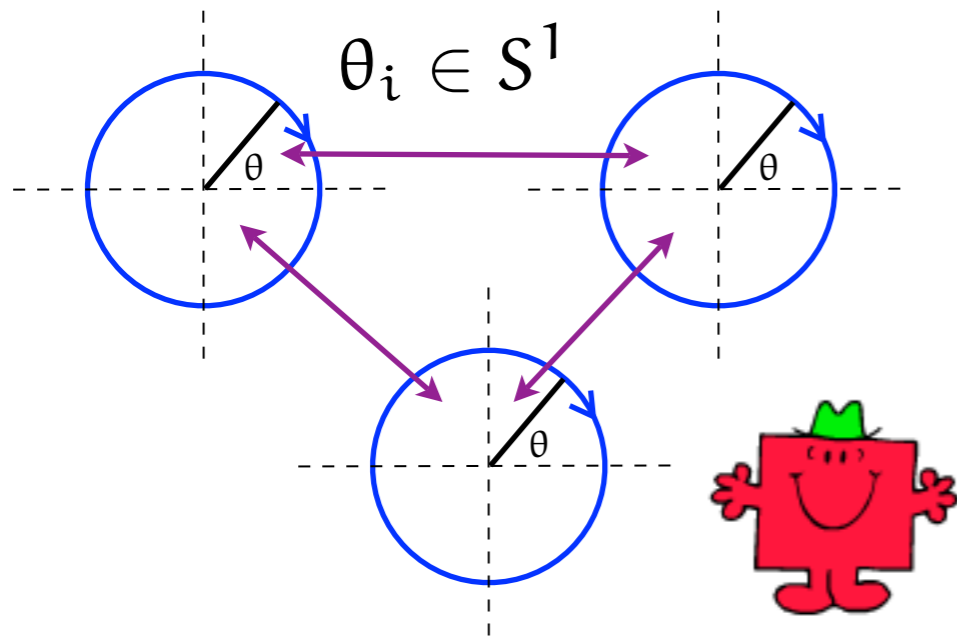




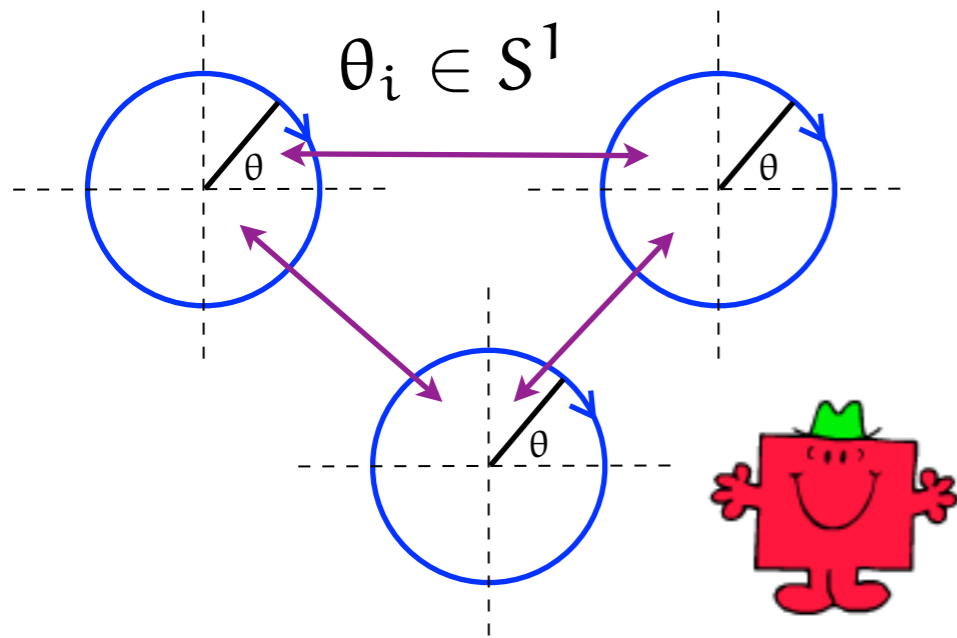
# Strongly coupled networks?



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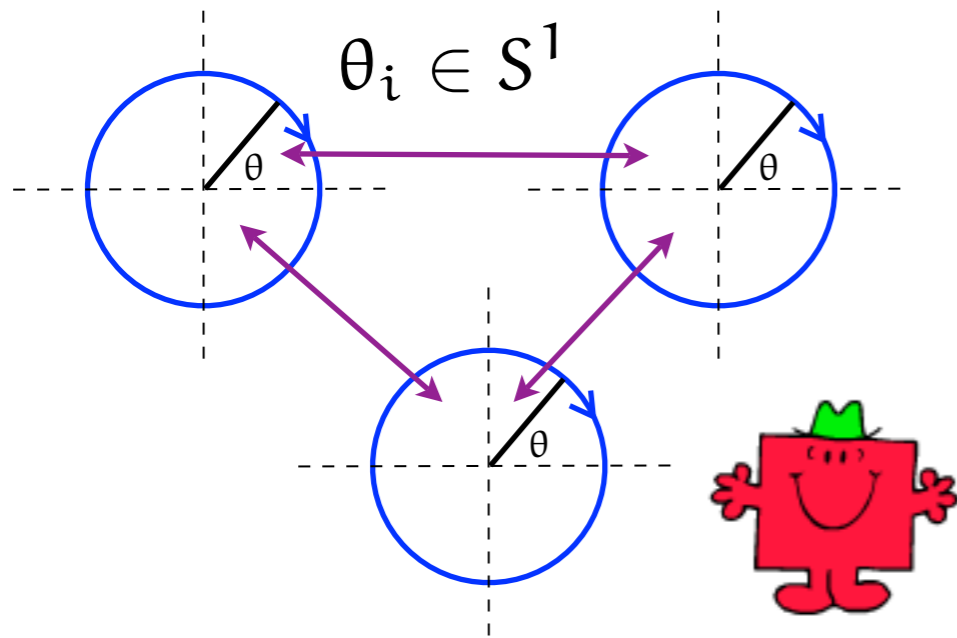
# Strongly coupled networks?



$$\dot{\theta}_i = f(\theta_i, \rho_i) + \varepsilon \sum_j w_{ij} H_1(\theta_i, \theta_j, \rho_i, \rho_j)$$

$$\dot{\rho}_i = A(\theta_i)\rho_i + \varepsilon \sum_j w_{ij} H_2(\theta_i, \theta_j, \rho_i, \rho_j)$$

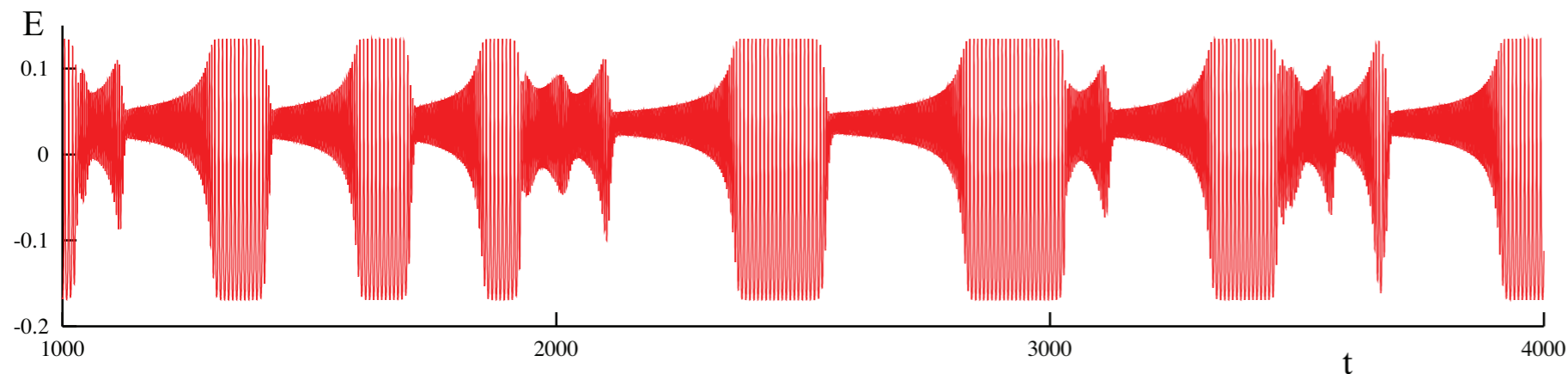
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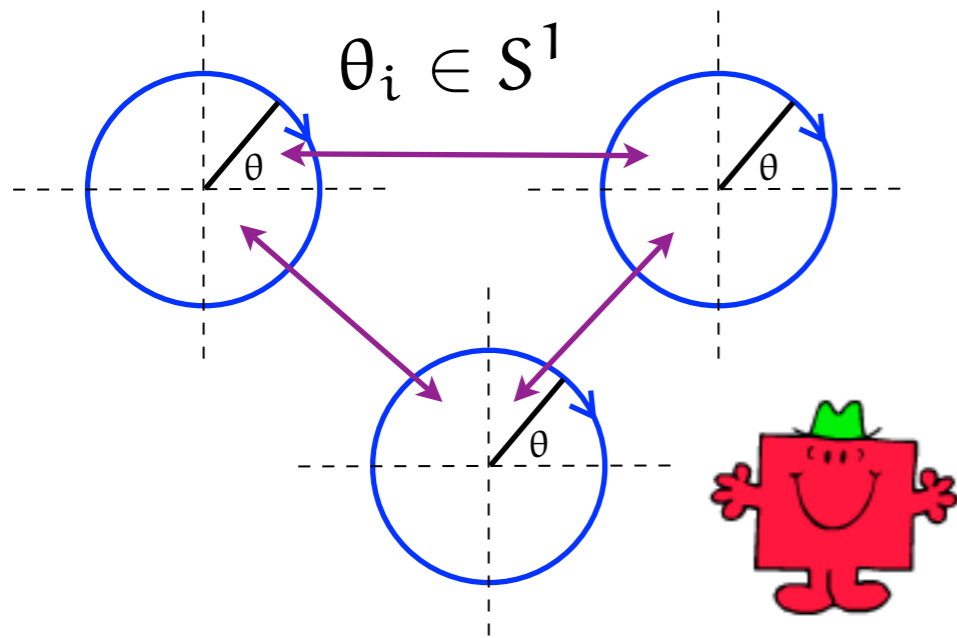
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global linear coupling of ML - mean field signal as average membrane potential



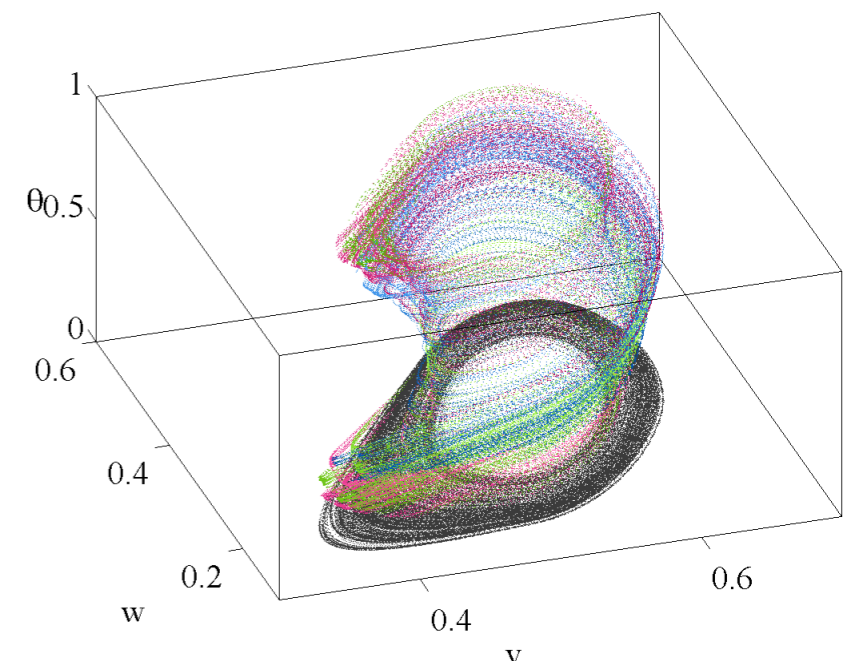
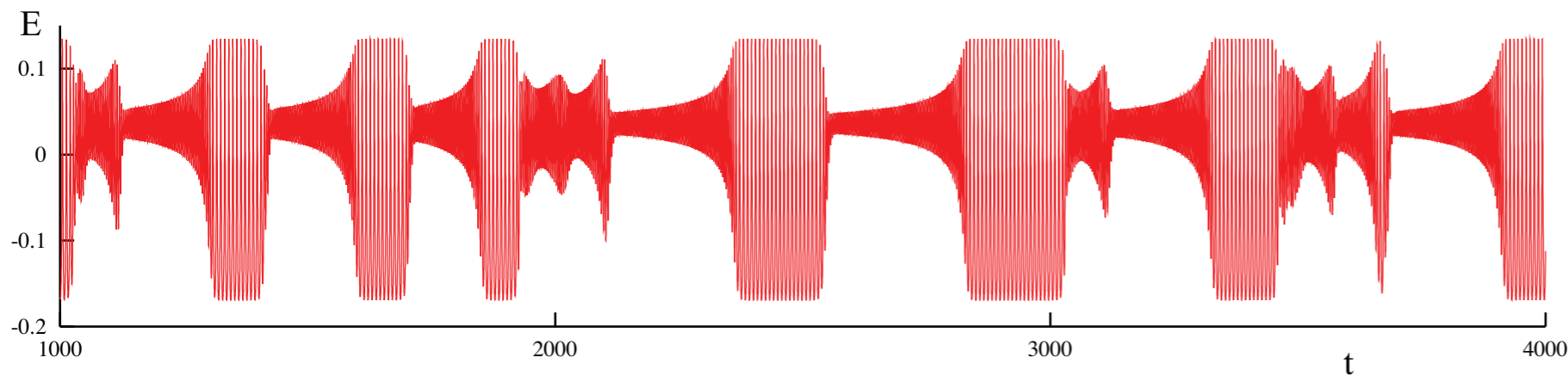
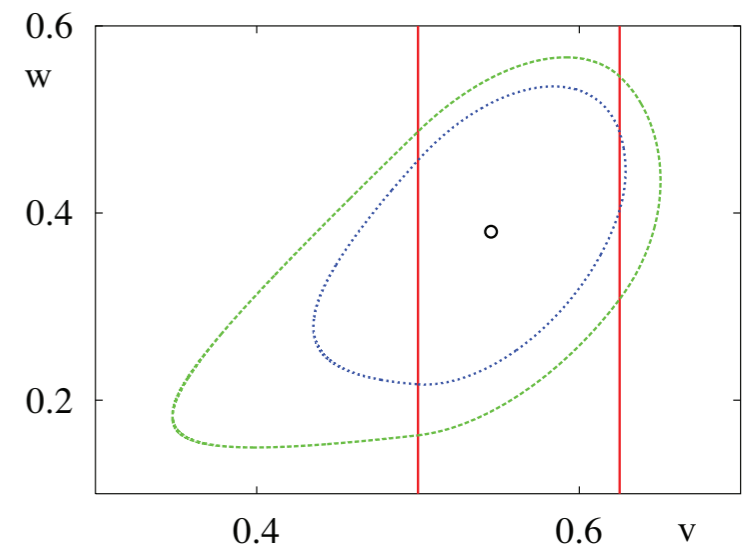
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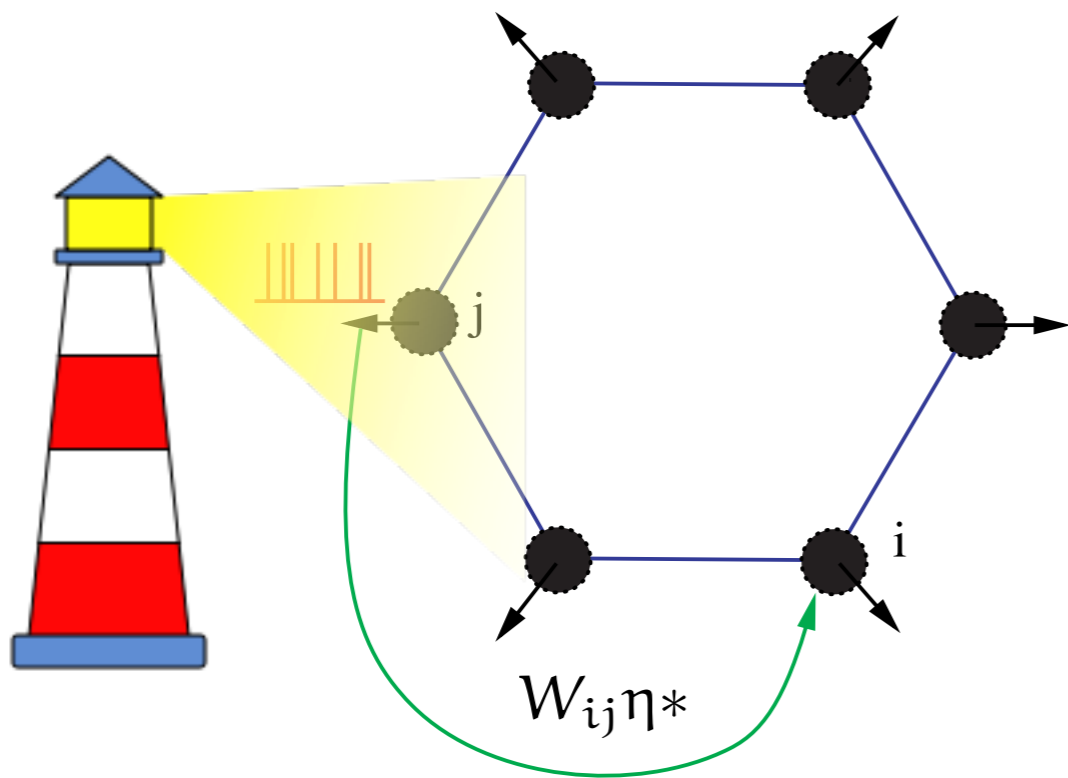
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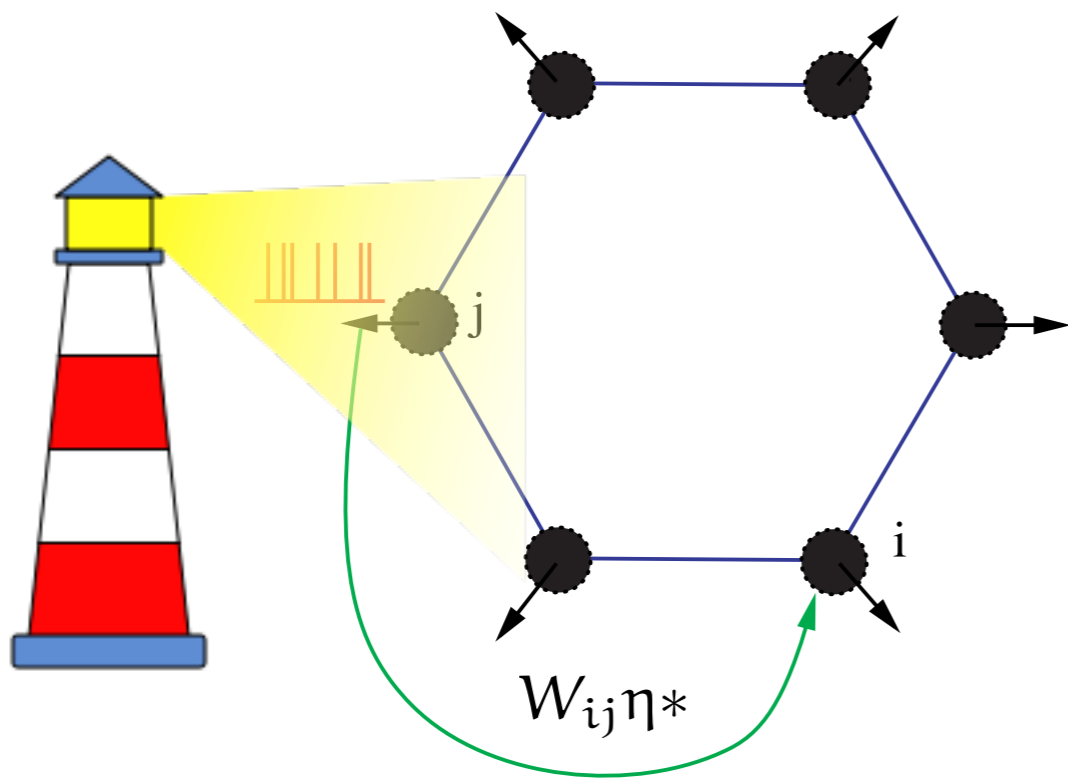
S Coombes 2008 Neuronal networks with gap junctions:  
A study of piece-wise linear planar neuron models,  
SIAM Journal on Applied Dynamical Systems, Vol 7, 1101-112

# A solvable spiking neurodynamics?



Haken Lighthouse model

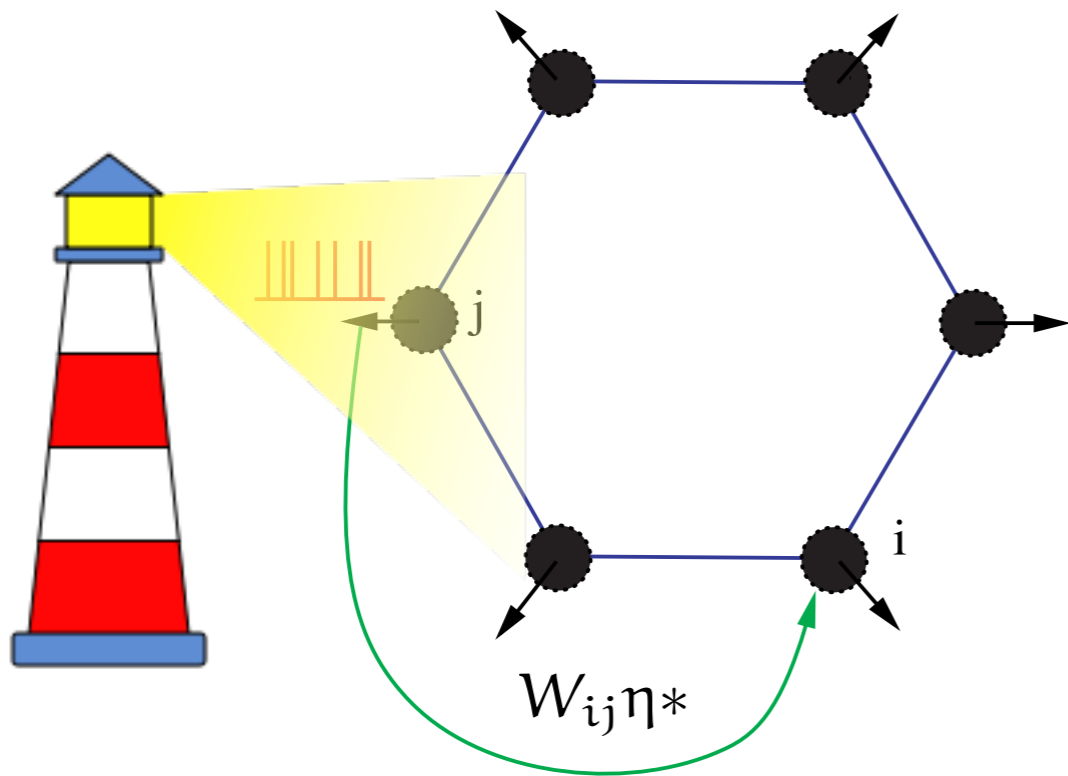
# A solvable spiking neurodynamics?



Haken Lighthouse model

$$\frac{\partial \theta(x, t)}{\partial t} = H(u(x, t) - h)$$

# A solvable spiking neurodynamics?



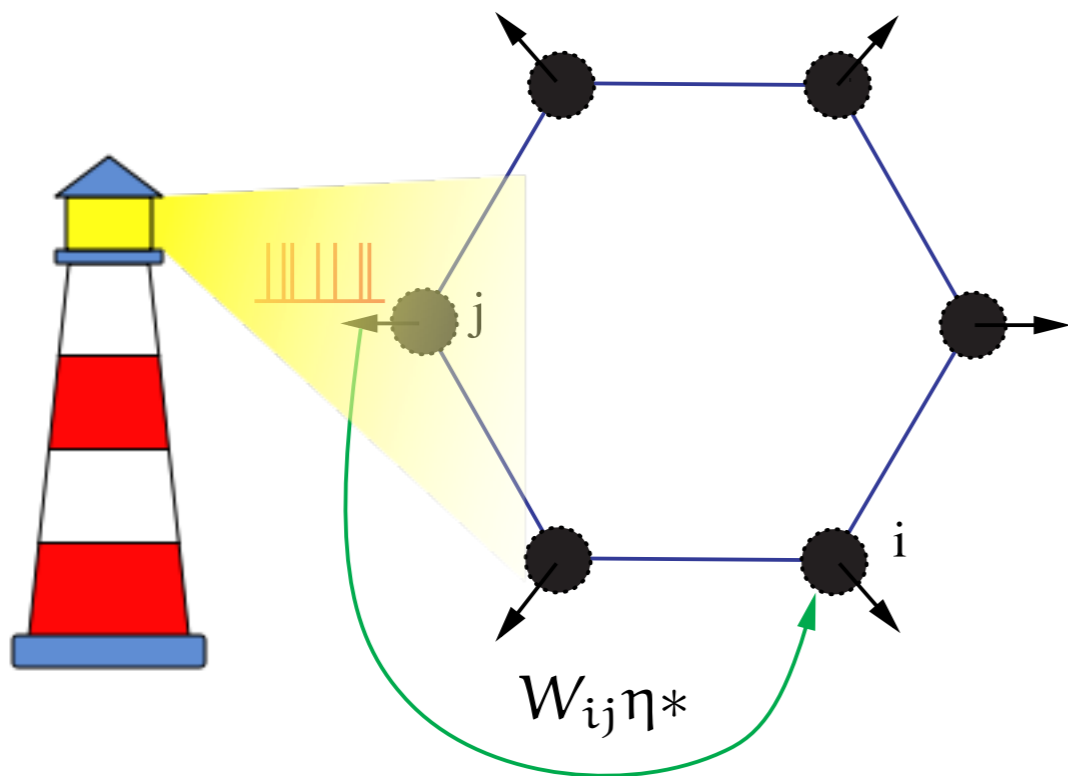
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$$u(x, t) = \sum_m \int_0^\infty ds \eta(s) \int_{-\infty}^\infty dy w(x - y) \delta(s - t + T^m(y))$$



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Haken Lighthouse model

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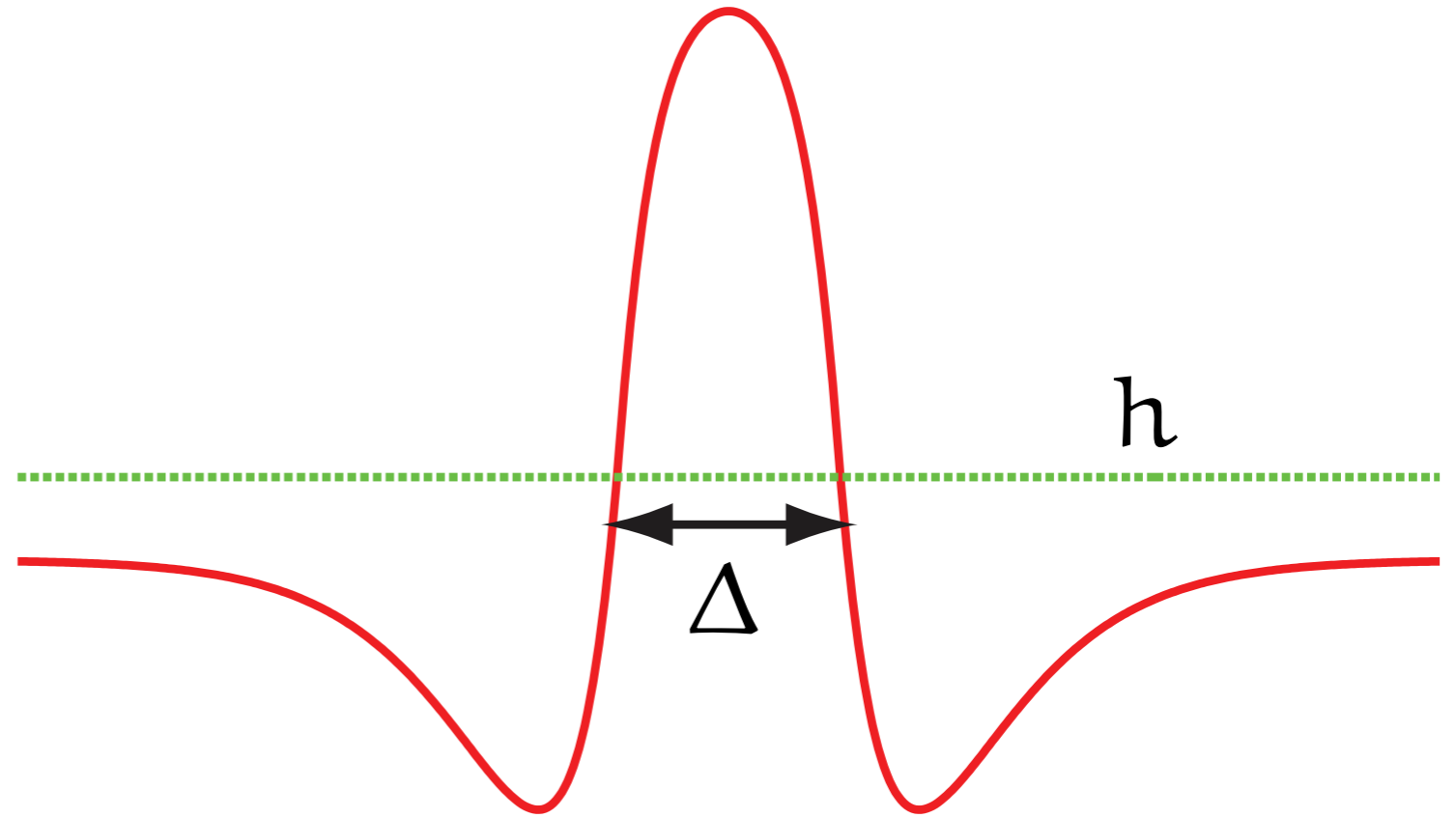
$$u(x, t) = \sum_m \int_0^\infty ds \eta(s) \int_{-\infty}^\infty dy w(x - y) \delta(s - t + T^m(y))$$

$\eta(t) = \alpha e^{-\alpha t} H(t)$  and slow synapses recovers Amari

$$\frac{1}{\alpha} \frac{\partial u(x, t)}{\partial t} = -u(x, t) + \int_{-\infty}^\infty dy w(x - y) H(u(y, t) - h)$$

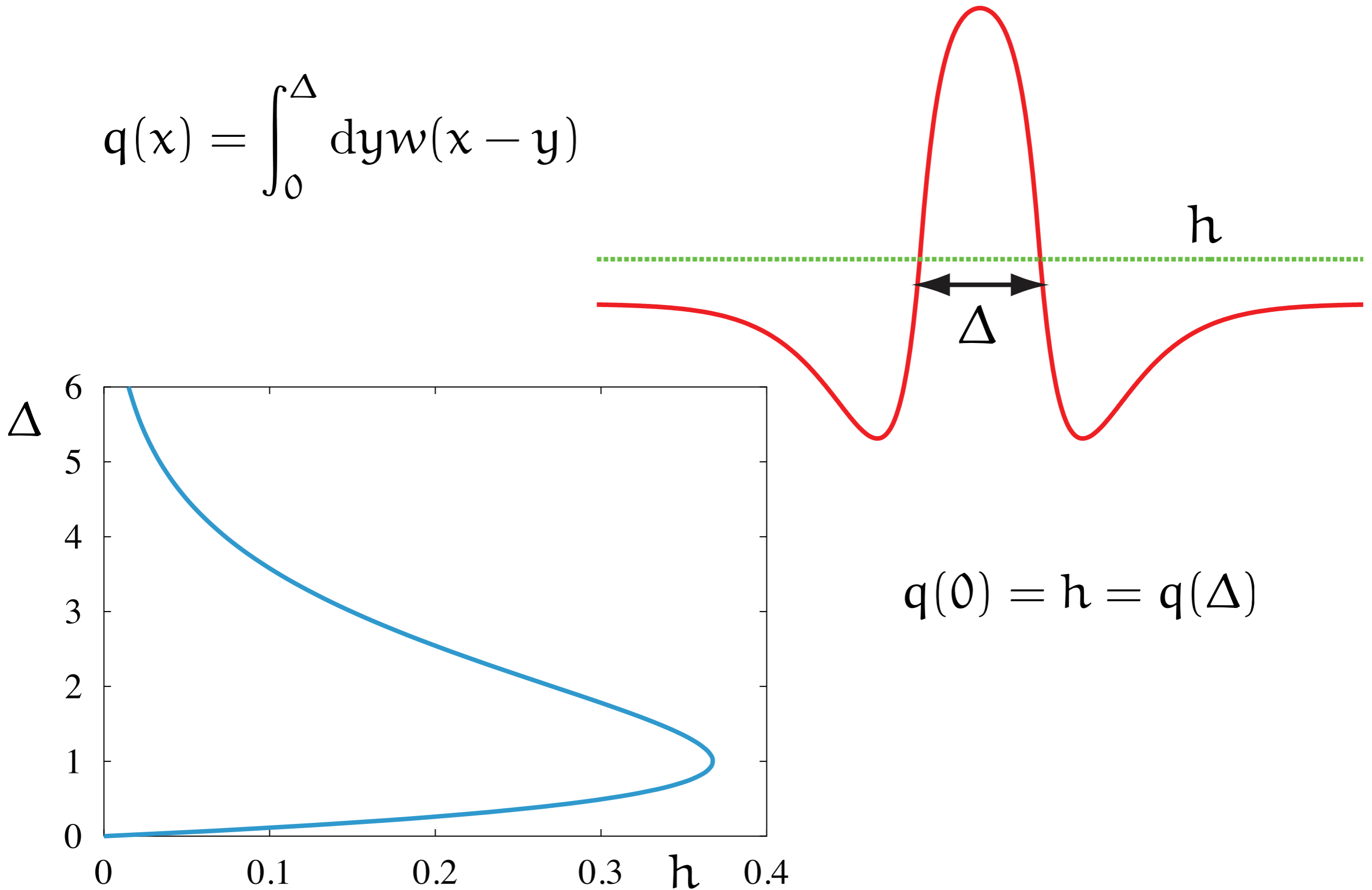
# Amari bumps with Mexican-hat

$$q(x) = \int_0^\Delta dy w(x-y)$$



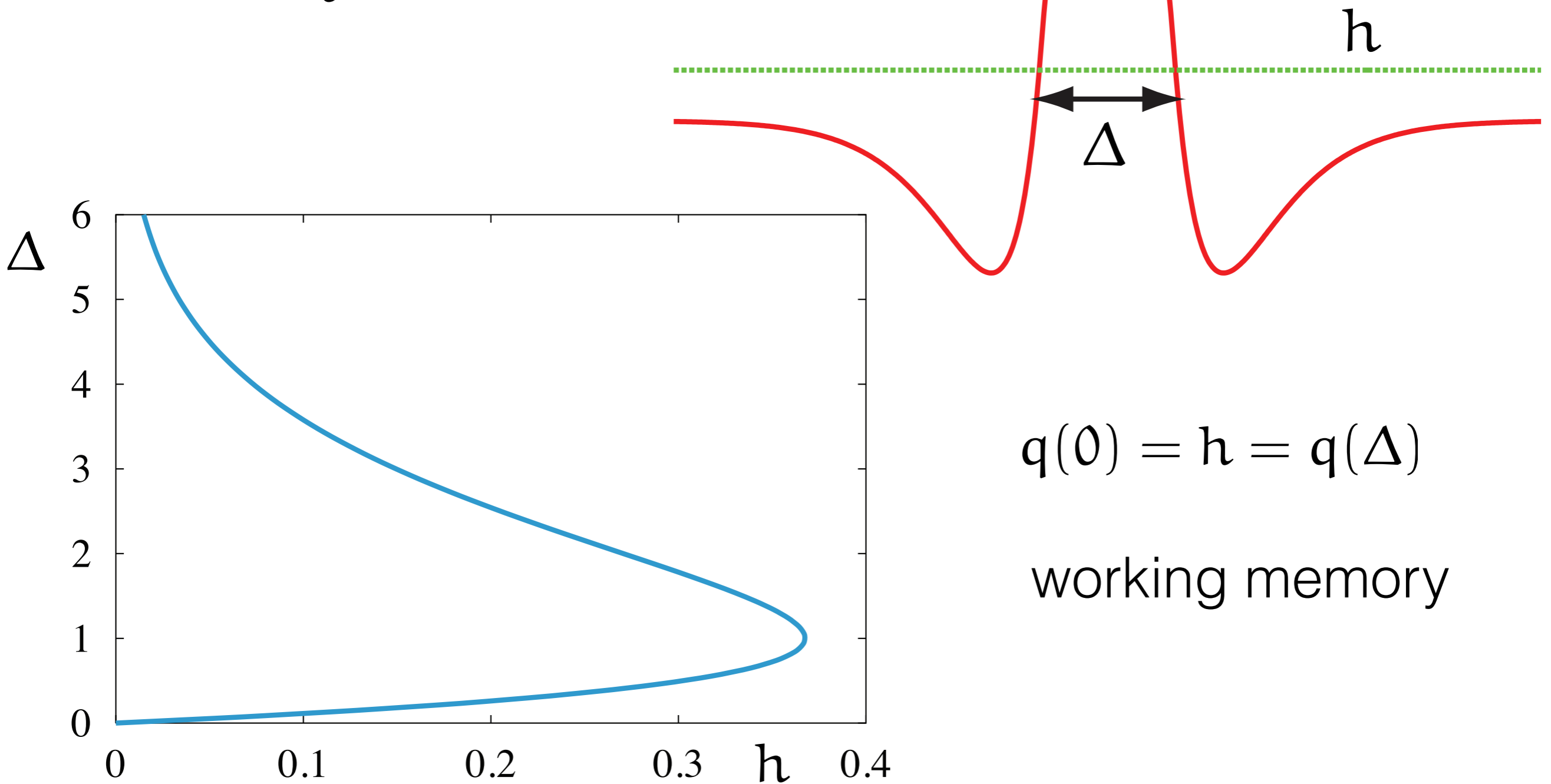
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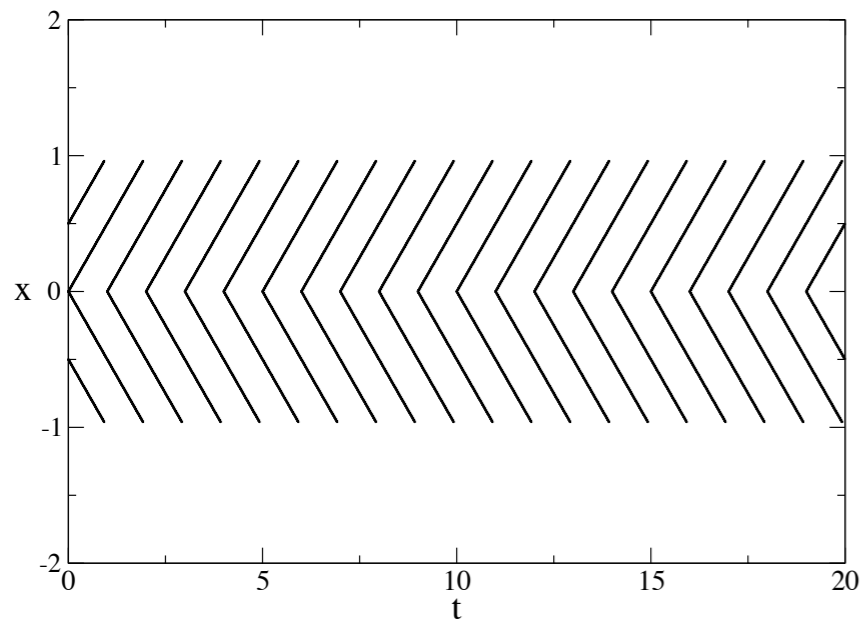
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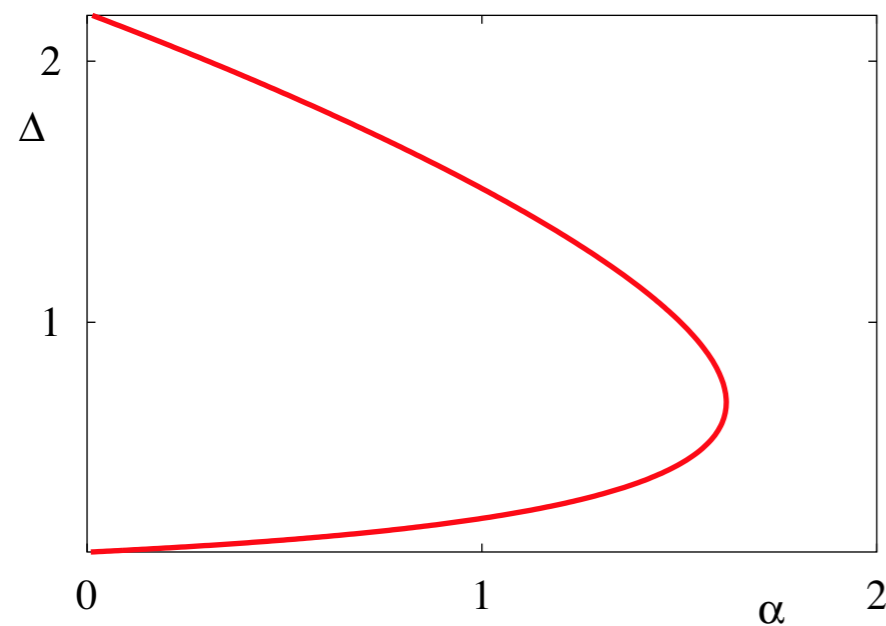
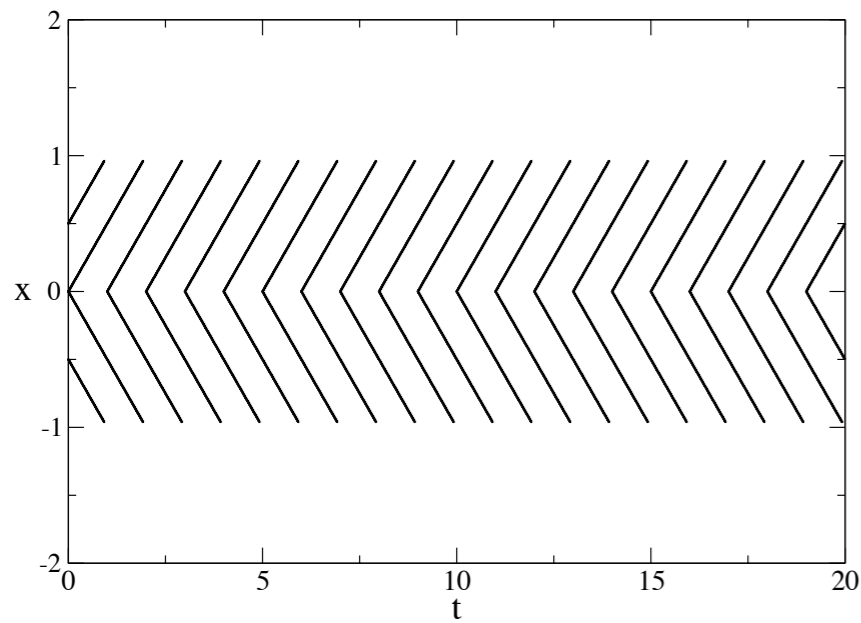
# Spiking bumps

$$h = \int_0^{\Delta} w(y) dy + 2\text{Re} \left( \sum_{n>0} \hat{\eta}(2\pi n) G(2\pi n) e^{2\pi i n t^*} \right) *$$



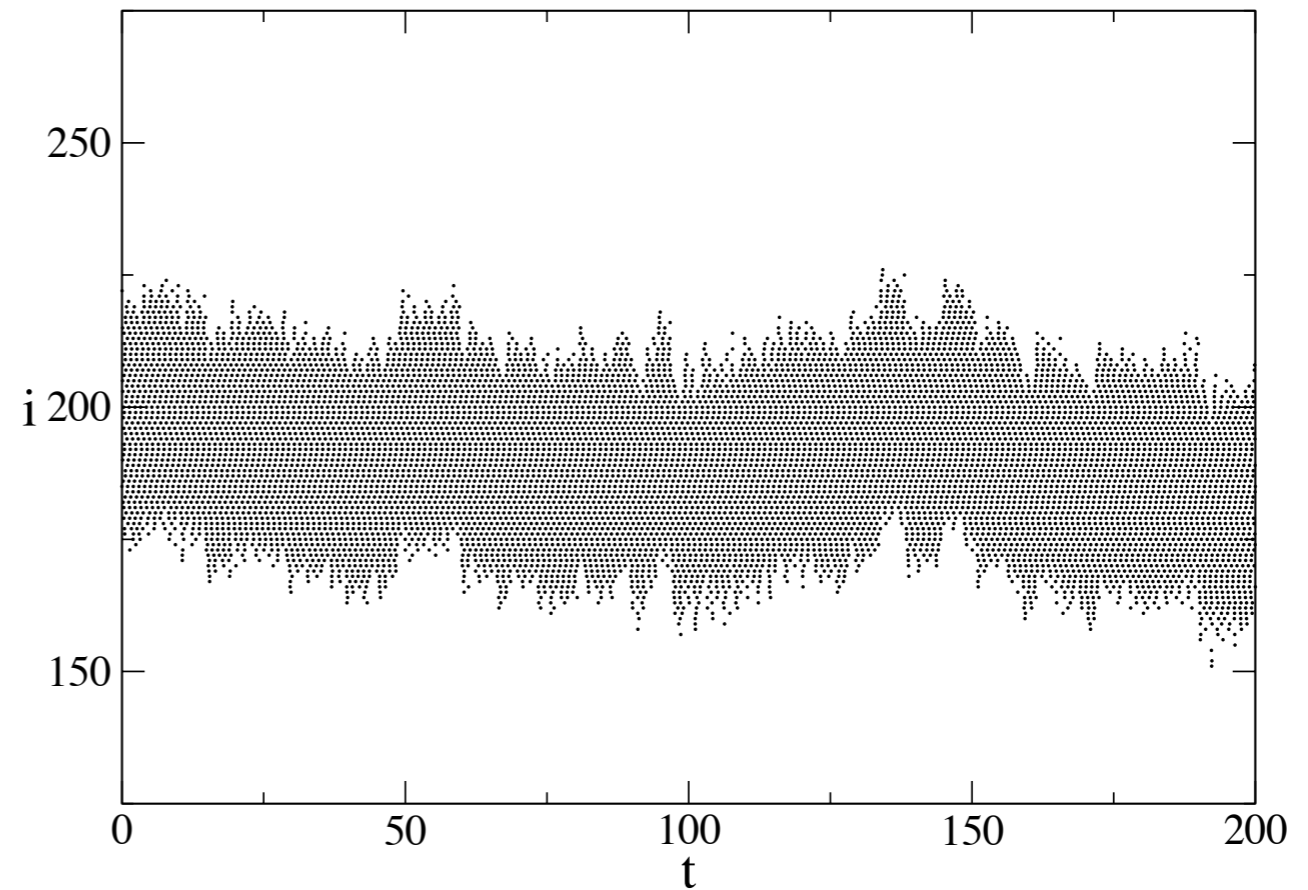
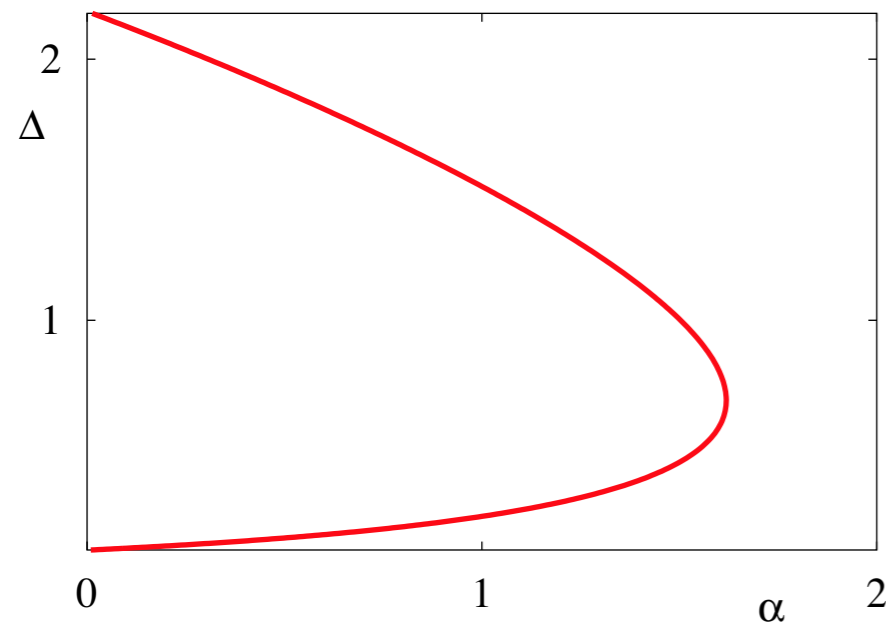
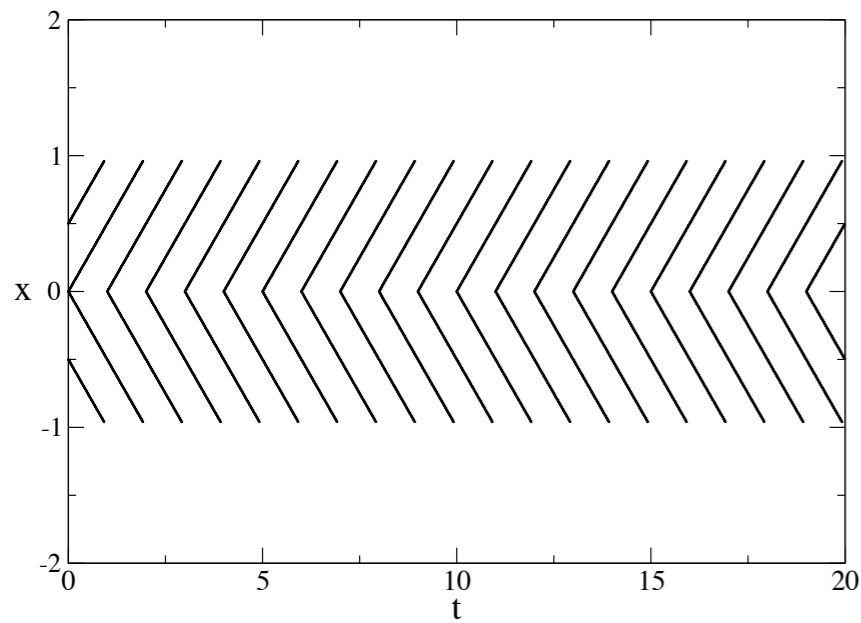
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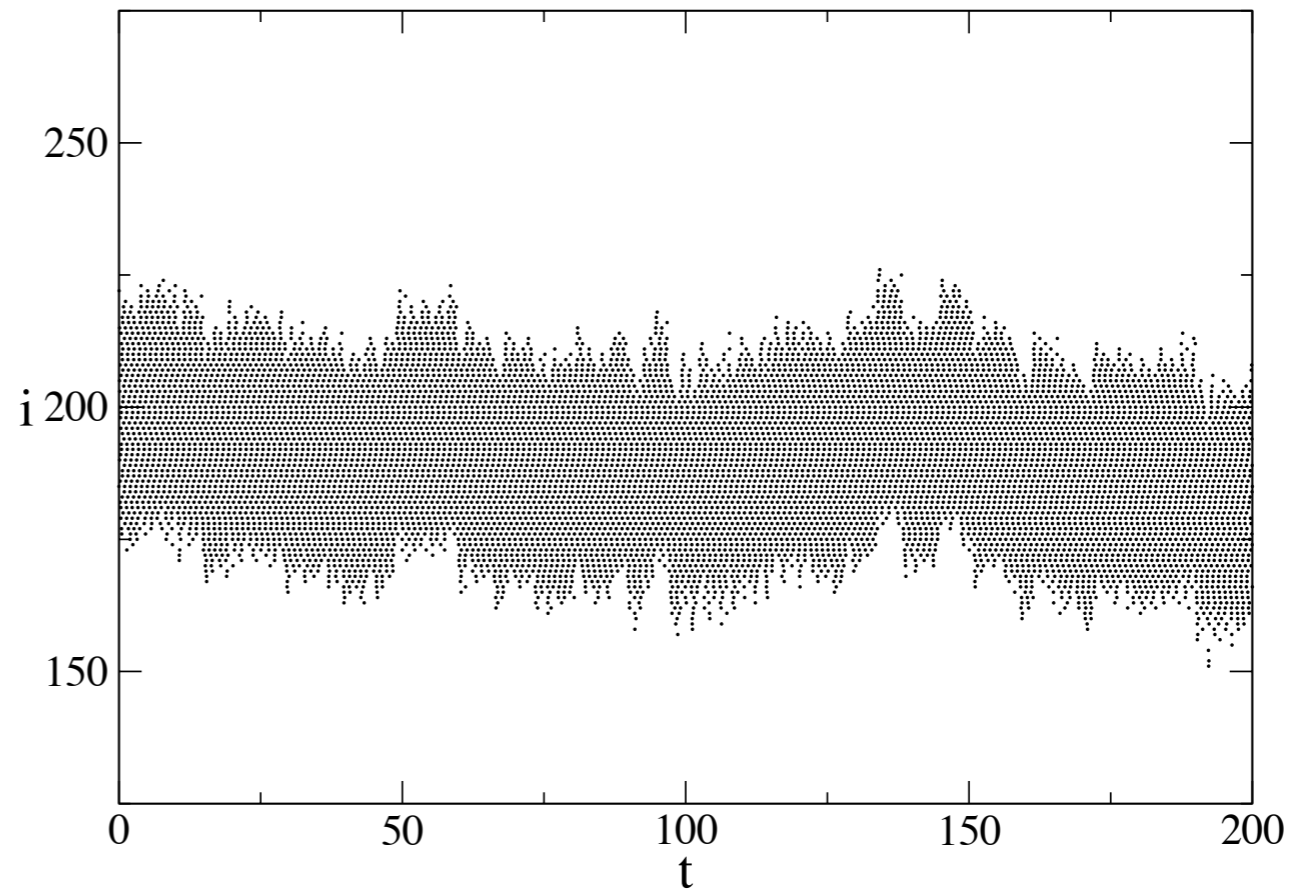
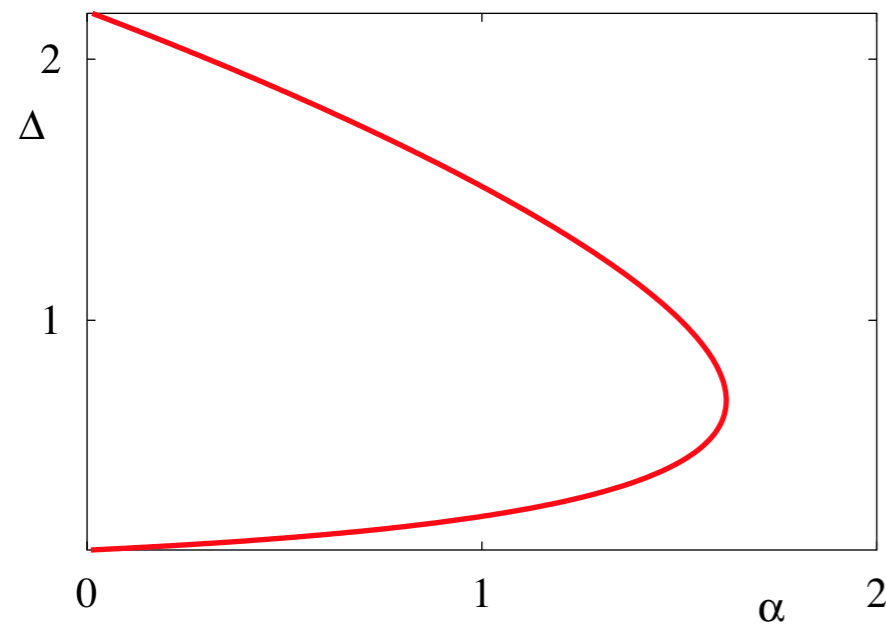
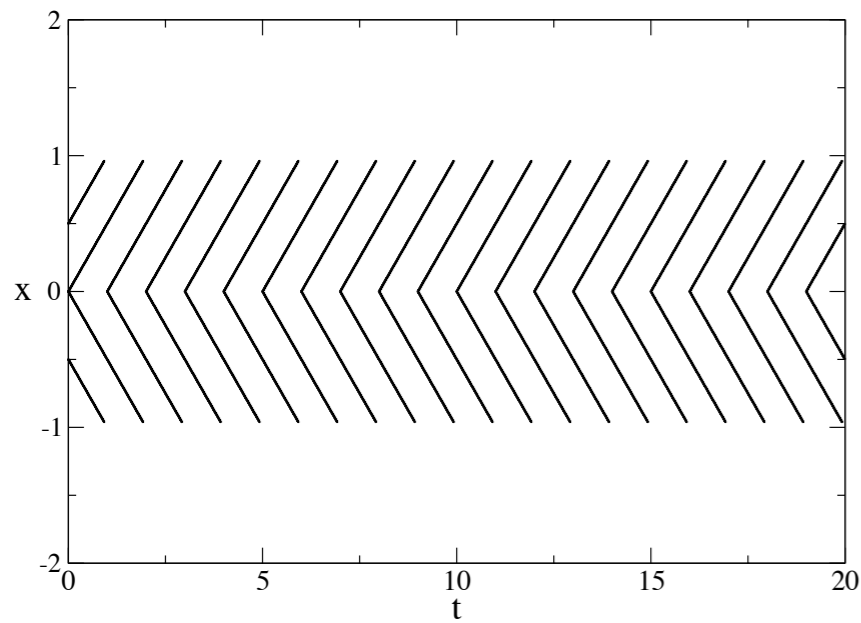
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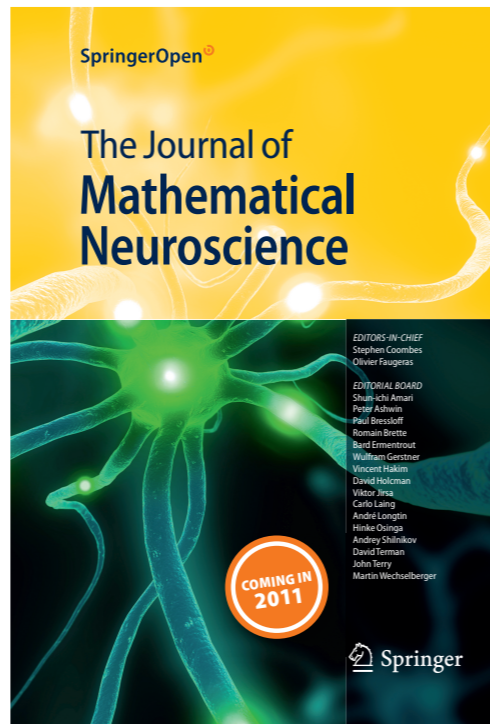
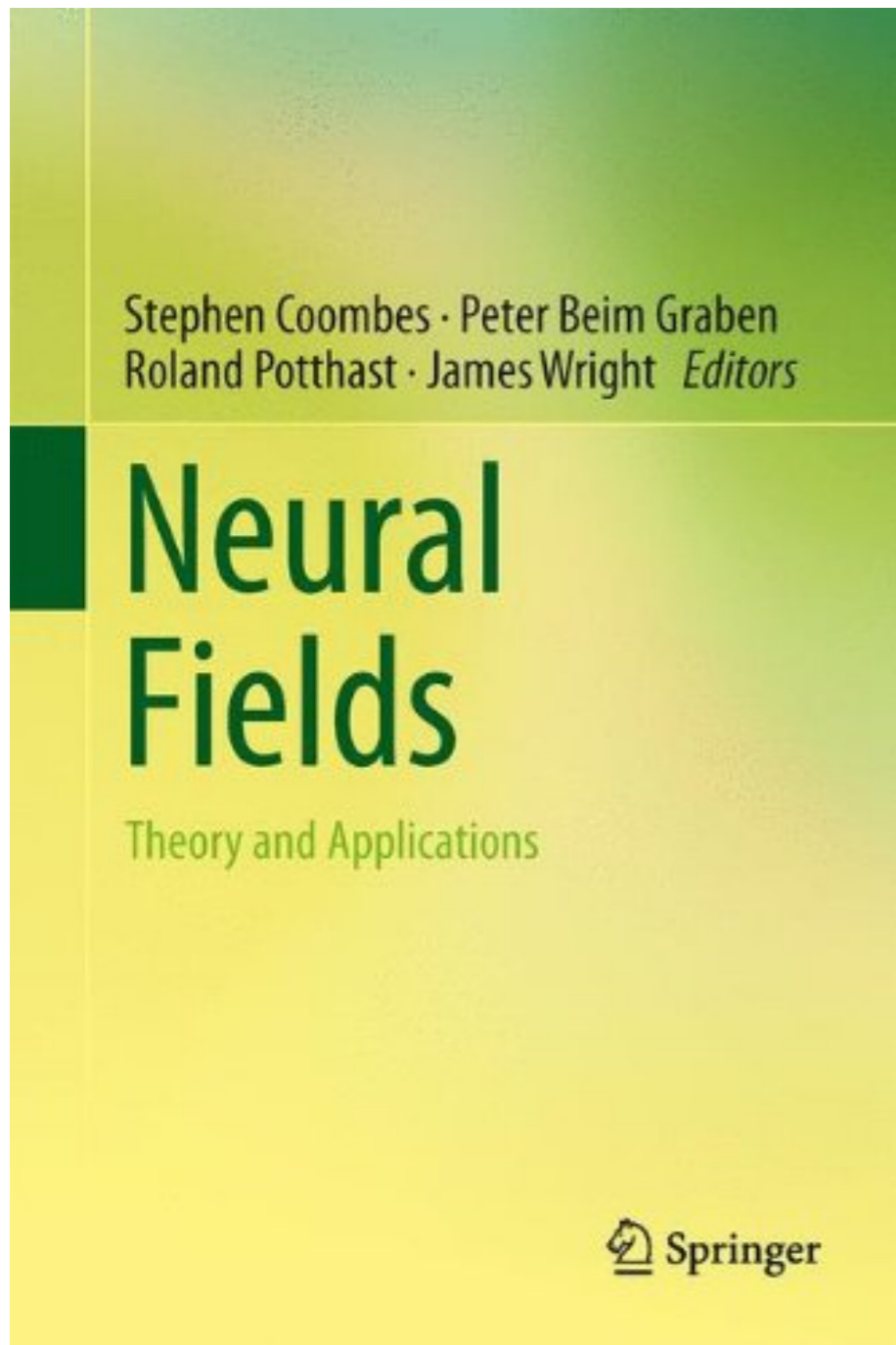
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Is there an effective beyond MF model that has  $*$  as a solution ?





K C A Wedgwood, K K Lin, R Thul and S Coombes 2013  
Phase-amplitude descriptions of neural oscillator models, Journal of Mathematical Neuroscience, 3:2.



C C Chow and S Coombes 2006  
Existence and wandering of bumps in a spiking neural network model, SIAM Journal on Applied Dynamical Systems, Vol 5, 552-574

