Stochastic Modelling of Reaction, Diffusion and Taxis Processes in Biology

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- stochastic modelling of chemical reactions, gene regulatory networks
- equation-free methods (effective free energy surfaces)
- selection of coarse variables (diffusion maps)
- stochastic modelling of spatially distributed problems, pattern formation
- derivation of reactive boundary conditions for stochastic models





system of mutually repressing genes





- system of mutually repressing genes
- equation-free methods: we want to compute steady state distributions, effective potentials, first passage time of bistable systems and bifurcation diagrams

Evolution of the number of protein molecules



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system is effectively one-dimensional (we later use macroscopic observable $Q = P_1 - P_2$), bistability for $\gamma > 1.06$

Effective potential and first passage time





mean exit time can be computed from the potential:

$$\tau_{e;p} = \int_{q_m}^{q_u} \exp\left[\beta\Phi(q)\right] \frac{1}{D(q)} \int_{-\infty}^q \exp\left[-\beta\Phi(\xi)\right] d\xi \, dq$$

or approximated by the Kramer's formula:

$$\tau_{e;k} \approx \frac{4\pi \exp\left[\beta \Phi(q_u) - \beta \Phi(q_m)\right]}{\beta [D(q_u) + D(q_m)] \sqrt{\Phi''(q_m) |\Phi''(q_u)|}}$$

Steady state distributions







red line: steady state distributions obtained from potential $\Phi(Q)$ computed by the equation-free algorithm

blue histograms: obtained by direct long time simulations

R. Erban, I. Kevrekidis, D. Adalsteinsson and T. Elston, Journal of Chemical Physics, 2006

Equation-free bifurcation analysis





continuation algorithm wrapped around the stochastic timestepper (blue circles)

$$\begin{cases} Q - F(Q, \gamma) = 0\\ (Q - Q_2)(Q_2 - Q_1) + (\gamma - \gamma_2)(\gamma_2 - \gamma_1) - \delta = 0 \end{cases}$$

• deterministic steady states (red line)

Selection of coarse variables – diffusion maps





Model:

$$X + X \xrightarrow[k_2]{k_1} Y \qquad \emptyset \xrightarrow[k_3]{k_3} X$$

Slow variable? X + 2Y



4

time

6

8

10



Consider set of data points $\mathbf{X}^{(i)} = [X^{(i)}, Y^{(i)}]$, i = 1, ..., M. For every data point $\mathbf{X}^{(i)} = [X^{(i)}, Y^{(i)}]$, compute:

$$\mathbf{A}^{(i)} = \frac{1}{\sigma_X^{(i)} \sigma_Y^{(i)} - (\sigma_{XY}^{(i)})^2} \begin{pmatrix} \sigma_Y^{(i)} & -\sigma_{XY}^{(i)} \\ -\sigma_{XY}^{(i)} & \sigma_X^{(i)} \end{pmatrix}$$

where

$$\begin{split} \sigma_X^{(i)} &= \left\langle X^2(\Delta t) \,|\, \mathbf{X}(0) = \mathbf{X}^{(i)} \right\rangle - (\mu_X^{(i)})^2 \\ \sigma_Y^{(i)} &= \left\langle Y^2(\Delta t) \,|\, \mathbf{X}(0) = \mathbf{X}^{(i)} \right\rangle - (\mu_Y^{(i)})^2 \\ \sigma_{XY}^{(i)} &= \left\langle X(\Delta t) Y(\Delta t) \,|\, \mathbf{X}(0) = \mathbf{X}^{(i)} \right\rangle - \mu_X^{(i)} \mu_Y^{(i)} \end{split}$$

Distance of data points $\mathbf{X}^{(i)} = [X^{(i)}, Y^{(i)}]$ and $\mathbf{X}^{(j)} = [X^{(j)}, Y^{(j)}]$:

$$\mathsf{dist}^{2}(\mathbf{X}^{(i)}, \mathbf{X}^{(j)}) = \frac{1}{2} (\mathbf{X}^{(i)} - \mathbf{X}^{(j)}) \left[\mathbf{A}^{(i)} + \mathbf{A}^{(j)} \right] (\mathbf{X}^{(i)} - \mathbf{X}^{(j)})^{T}$$

Apply diffusion maps (*Coifman et al, PNAS, 2005; Singer and Coifman, 2007*) using this local distance to find slow variable(s).

Selection of coarse variables – diffusion maps

200

180

0.5

0

-0.5

_'

-1.5

80

100

120

140

Х

160

eigenvector V₁



Diffusion maps (with the modified local distance) can be used to find the slow variable X + 2Y.

Next step - combine with equation-free approach (*R. Erban, T. Frewen, X. Wang, T. Elston, R. Coifman, B. Nadler and I. Kevrekidis, Journal of Chemical Physics, 2007*).

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Selection of coarse variables – diffusion maps





Model:

$$\begin{array}{ccccc} X & \stackrel{k_1}{\longrightarrow} & X + Z, & Y + Z & \stackrel{k_2}{\longrightarrow} & Y & \text{(fast)} \\ & \emptyset & \stackrel{k_3}{\longrightarrow} & Y, & Y & \stackrel{k_4}{\longrightarrow} & \emptyset & \text{(medium)} \\ & & \emptyset & \stackrel{k_5}{\longrightarrow} & X & \text{(slow)} \end{array}$$



Spatially Distributed Problems - Motivation



Model: diffusing morphogen which is produced in part of the domain and degraded everywhere

Morphogen gradient is interpreted by the layer of cells, utilizing thresholds, to produce different structures at different places – pattern formation.



Spatially Distributed Problems - Turing Patterns



Model: diffusion of A, B and $2A + B \xrightarrow{k_1} 3A \qquad \emptyset \xrightarrow{k_2} A \qquad \emptyset \xrightarrow{k_4} B$

Turing patterns: homogeneous solution unstable, spatial patterns develop, number of blue peaks not unique (several favourable states)



Deterministic equations



Reaction-diffusion partial differential equations:

$$\frac{\partial n_i}{\partial t} = D_i \Delta n_i + R_i(n_1, n_2, \dots, n_k), \qquad i = 1, 2, \dots, k$$

 $n_i \equiv n_i(x, t) \dots$ concentration of the *i*-th chemical species at point x and time t $D_i \dots \dots$ diffusion constant of the *i*-th chemical species $R_i(n_1, n_2, \dots, n_k) \dots$ changes of n_i because of chemical reactions

- equations considered in domain Ω (e.g. a cell bounded by its membrane)
- we need to introduce suitable boundary conditions

 $X(t + \Delta t) = X(t) + \sqrt{2D \,\Delta t} \,\zeta_x$ $Y(t + \Delta t) = Y(t) + \sqrt{2D \,\Delta t} \,\zeta_y$ $Z(t + \Delta t) = Z(t) + \sqrt{2D \,\Delta t} \,\zeta_z$

 ζ_x , ζ_y , ζ_z ... normally distributed random variables with zero mean and unit variance

 $D \dots$ diffusion constant





 $X(t + \Delta t) = X(t) + \sqrt{2D \Delta t} \zeta_x$ $Y(t + \Delta t) = Y(t) + \sqrt{2D \Delta t} \zeta_y$ $Z(t + \Delta t) = Z(t) + \sqrt{2D \Delta t} \zeta_z$

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 $X(t + \Delta t) = X(t) + \sqrt{2D\Delta t} \zeta_x$ $Y(t + \Delta t) = Y(t) + \sqrt{2D\,\Delta t}\,\zeta_u$ $Z(t + \Delta t) = Z(t) + \sqrt{2D\,\Delta t}\,\zeta_z$

 $\zeta_x, \zeta_y, \zeta_z$... normally distributed random variables with zero mean and unit variance

D ... diffusion constant





 $X(t + \Delta t) = X(t) + \sqrt{2D \Delta t} \zeta_x$ $Y(t + \Delta t) = Y(t) + \sqrt{2D \Delta t} \zeta_y$ $Z(t + \Delta t) = Z(t) + \sqrt{2D \Delta t} \zeta_z$

 $\zeta_x, \zeta_y, \zeta_z$... normally distributed random variables with zero mean and unit variance D ... diffusion constant



Several stochastic simulation algorithms for modelling diffusion, reaction and taxis: position jump processes, velocity jump processes

- stochastic simulation in domain Ω (e.g. a cell bounded by its membrane)
- we need to introduce suitable boundary conditions





One-dimensional diffusion equation in [0,L]:
$$\frac{\partial n}{\partial t} = D \frac{\partial^2 n}{\partial x^2}$$

 $(n \equiv n(x, t) \dots$ density of molecules at point x and time t; D \dots diffusion constant)

Reactive (radiation, Robin) boundary condition at x = 0:

$$D\frac{\partial n}{\partial x}(0,t) = K n(0,t)$$

 $K \dots$ reactivity of the boundary (e.g. rate constant of boundary chemical reaction)

- K = 0 perfect reflection of molecules (zero-flux boundary condition)
- $K = \infty$... perfect adsorption of molecules (Dirichlet boundary condition)



whenever a molecule hits the boundary, it is adsorbed with some probability, and reflected otherwise

- $P\ldots$ probability that a molecule is adsorbed, rather than reflected
- $K \dots$ reactivity of the boundary (e.g. rate constant of boundary chemical reaction)

What is a relation between P and K?



whenever a molecule hits the boundary, it is adsorbed with some probability, and reflected otherwise

- $P\ldots$ probability that a molecule is adsorbed, rather than reflected
- $K \dots$ reactivity of the boundary (e.g. rate constant of boundary chemical reaction)

What is a relation between P and K?

- (zero-flux boundary) $K = 0 \iff P = 0$ (molecules always reflected)
- value of P depends on K and on the stochastic model for K > 0
- relations between P and K for four different stochastic simulation algorithms are derived in R. Erban and J. Chapman, Physical Biology, 2007

Same value P = 5 % for different stochastic models





[whenever a molecule hits boundary x = 0, it is adsorbed with probability 5%, and reflected otherwise]



Position Jump Process I: lattice points a distance *h* apart

$$X(t + \Delta t) = \begin{cases} X(t) & \text{with probability } 1 - 2D\Delta t/h^2 \\ X(t) - h & \text{with probability } D\Delta t/h^2 \\ X(t) + h & \text{with probability } D\Delta t/h^2 \end{cases}$$

Boundary condition: whenever a molecule hits the boundary, it is adsorbed with probability $P = P_1 h$, and reflected otherwise.

Position Jump Process 2: $X(t + \Delta t) = X(t) + \sqrt{2D \Delta t} \zeta_x$

Boundary condition: whenever a molecule hits the boundary, it is adsorbed with probability $P = P_2 \sqrt{\Delta t}$, and reflected otherwise.

Relations between P and K:

$$P_1 = \frac{K}{D} \qquad \qquad P_2 = \frac{K\sqrt{7}}{2\sqrt{L}}$$

Correct choice of P for different stochastic models





R. Erban and J. Chapman, Physical Biology, 2007



We considered only diffusion so far, but:

- the boundary conditions for stochastic models of reaction, diffusion and taxis depend on the corresponding model of the diffusion only
- chemical reactions (e.g. modelling gene regulatory networks) or taxis/advection (e.g. modelling ion channels) do not influence the boundary conditions

We considered behaviour of biomolecules (e.g. proteins) so far, but a stochastic description is also useful for modelling unicellular organisms (e.g. chemotaxis of bacteria or Dictyostelium):

RE, H. Othmer, SIAM Journal on Applied Mathematics, 2004
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- stochastic modelling of reaction, diffusion and taxis processes in biology
- equation-free methods (computation of steady state distributions, effective potentials, first passage time of bistable systems and bifurcation diagrams)
- selection of coarse variables (anisotropic diffusion maps)
- derivation of reactive boundary conditions for stochastic models



- I. Kevrekidis, W. Gear, T. Frewen, L. Qiao (Princeton University)
- A. Singer, R. Coifman, B. Nadler (Yale University)
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- H. Othmer (University of Minnesota)

Preprints:

www.maths.ox.ac.uk/~erban

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